

# Package ‘Directional’

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**Type** Package

**Title** A Collection of Functions for Directional Data Analysis

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**Author**

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**Maintainer** Michail Tsagris <mtsagris@uoc.gr>

**Description** A collection of functions for directional data (including massive data, with millions of observations) analysis. Hypothesis testing, discriminant and regression analysis, MLE of distributions and more are included. The standard textbook for such data is the “Directional Statistics” by Mardia, K. V. and Jupp, P. E. (2000). Other references include a) Phillip J. Paine, Simon P. Preston Michail Tsagris and Andrew T. A. Wood (2018). An elliptically symmetric angular Gaussian distribution. *Statistics and Computing* 28(3): 689-697. <doi:10.1007/s11222-017-9756-4>. b) Tsagris M. and Alenazi A. (2019). Comparison of discriminant analysis methods on the sphere. *Communications in Statistics: Case Studies, Data Analysis and Applications* 5(4):467--491. <doi:10.1080/23737484.2019.1684854>. c) P. J. Paine, S. P. Preston, M. Tsagris and Andrew T. A. Wood (2020). Spherical regression models with general covariates and anisotropic errors. *Statistics and Computing* 30(1): 153--165. <doi:10.1007/s11222-019-09872-2>. d) Tsagris M. and Alenazi A. (2022). An investigation of hypothesis testing procedures for circular and spherical mean vectors. *Communications in Statistics-Simulation and Computation* (Accepted for publication). <doi:10.1080/03610918.2022.2045499>.

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Directional-package	<i>This is an R package that provides methods for the statistical analysis of directional data, including massive (very large scale) directional data.</i>
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## Description

Circular-linear regression, spherical-spherical regression, spherical regression, discriminant analysis, ANOVA for circular and (hyper-)spherical data, tests for equality of concentration parameters, fitting distributions, random values generation, contour plots and many more functions are included.

## Details

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## Maintainers

Michail Tsagris <mtsagris@uoc.gr>

## Note

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If you want more information on many of these algorithms see Chapters 9 and 10 in the following document. [https://www.researchgate.net/publication/324363311\\_Multivariate\\_data\\_analysis\\_in\\_R](https://www.researchgate.net/publication/324363311_Multivariate_data_analysis_in_R)

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### References

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley and Sons.

---

A test for testing the equality of the concentration parameters for circular data  
*A test for testing the equality of the concentration parameter among  $g$  samples, where  $g \geq 2$  for circular data*

---

### Description

A test for testing the equality of the concentration parameter among  $g$  samples, where  $g \geq 2$  for circular data. It is a tangential approach.

**Usage**

```
tang.conc(u, ina, rads = FALSE)
```

**Arguments**

<code>u</code>	A numeric vector containing the values of all samples.
<code>ina</code>	A numerical variable or factor indicating the groups of each value.
<code>rads</code>	If the data are in radians this should be TRUE and FALSE otherwise.

**Details**

This test works for circular data.

**Value**

A vector including:

<code>test</code>	The value of the test statistic.
<code>p-value</code>	The p-value of the test.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons. Fisher, N. I. (1995). Statistical analysis of circular data. Cambridge University Press.

**See Also**

[embed.circaov](#), [hcf.circaov](#), [lr.circaov](#), [het.circaov](#), [conc.test](#)

**Examples**

```
x <- rvonmises(100, 2.4, 15)
ina <- rep(1:4, each = 25)
tang.conc(x, ina, rads = TRUE)
```

---

Angular central Gaussian random values simulation

*Angular central Gaussian random values simulation*

---

## Description

Angular central Gaussian random values simulation.

## Usage

```
racg(n, sigma)
```

## Arguments

n	The sample size, a numerical value.
sigma	The covariance matrix in $R^d$ .

## Details

The algorithm uses univariate normal random values and transforms them to multivariate via a spectral decomposition. The vectors are then scaled to have unit length.

## Value

A matrix with the simulated data.

## Author(s)

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

## References

Tyler D. E. (1987). Statistical analysis for the angular central Gaussian distribution on the sphere. *Biometrika* 74(3): 579-589.

## See Also

[acg.mle](#), [rvmf](#), [rvonmises](#)

## Examples

```
s <- cov( iris[, 1:4] )
x <- racg(100, s)
Directional::acg.mle(x)
Directional::vmf.mle(x)
## the concentration parameter, kappa, is very low, close to zero, as expected.
```

---

Anova for (hyper-)spherical data

*Analysis of variance for (hyper-)spherical data*

---

### Description

Analysis of variance for (hyper-)spherical data.

### Usage

```
hcf.aov(x, ina, fc = TRUE)
hclr.aov(x, ina)
lr.aov(x, ina)
embed.aov(x, ina)
het.aov(x, ina)
```

### Arguments

x	A matrix with the data in Euclidean coordinates, i.e. unit vectors.
ina	A numerical variable or a factor indicating the group of each vector.
fc	A boolean that indicates whether a corrected F test should be used or not.

### Details

The high concentration (`hcf.aov`), high concentration likelihood ratio (`hclr.aov`), log-likelihood ratio (`lr.aov`), embedding approach (`embed.aov`) or the non equal concentration parameters approach (`het.aov`) is used.

### Value

A vector with two or three elements, the test statistic, the p-value and the common concentration parameter kappa based on all the data.

### Author(s)

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>.

### References

- Mardia K. V. and Jupp P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.
- Rumcheva P. and Presnell B. (2017). An improved test of equality of mean directions for the Langevin-von Mises-Fisher distribution. Australian & New Zealand Journal of Statistics, 59(1), 119-135.
- Tsagris M. and Alenazi A. (2022). An investigation of hypothesis testing procedures for circular and spherical mean vectors. Communications in Statistics-Simulation and Computation (Accepted for publication).



**See Also**

[hcf.boot](#), [spherconc.test](#), [conc.test](#), [hclr.circaov](#),

**Examples**

```
x <- rvmf(60, rnorm(3), 15)
ina <- rep(1:3, each = 20)
hcf.aov(x, ina)
hcf.aov(x, ina, fc = FALSE)
lr.aov(x, ina)
embed.aov(x, ina)
het.aov(x, ina)
```

---

Anova for circular data

*Analysis of variance for circular data*

---

**Description**

Analysis of variance for circular data.

**Usage**

```
hcf.circaov(u, ina, rads = FALSE)
hclr.circaov(u, ina, rads = FALSE)
lr.circaov(u, ina, rads = FALSE)
het.circaov(u, ina, rads = FALSE)
embed.circaov(u, ina, rads = FALSE)
```

**Arguments**

<code>u</code>	A numeric vector containing the data.
<code>ina</code>	A numerical or factor variable indicating the group of each value.
<code>rads</code>	If the data are in radians, this should be TRUE and FALSE otherwise.

**Details**

The high concentration (`hcf.circaov`), high concentration likelihood ratio (`hclr.aov`), log-likelihood ratio (`lr.circaov`), embedding approach (`embed.circaov`) or the non equal concentration parameters approach (`het.circaov`) is used.

**Value**

A vector including:

<code>test</code>	The value of the test statistic.
<code>p-value</code>	The p-value of the test.
<code>kappa</code>	The concentration parameter based on all the data. If the <code>het.circaov</code> is used this argument is not returned.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>.

**References**

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.

Rumcheva P. and Presnell B. (2017). An improved test of equality of mean directions for the Langevin-von Mises-Fisher distribution. Australian & New Zealand Journal of Statistics, 59(1), 119-135.

Tsagris M. and Alenazi A. (2022). An investigation of hypothesis testing procedures for circular and spherical mean vectors. Communications in Statistics-Simulation and Computation (Accepted for publication).

**See Also**

[conc.test](#), [hclr.aov](#), [hcfcirc.boot](#)

**Examples**

```
x <- rvonmises(100, 2.4, 15)
ina <- rep(1:4,each = 25)
hcf.circaov(x, ina, rads = TRUE)
lr.circaov(x, ina, rads = TRUE)
het.circaov(x, ina, rads = TRUE)
embed.circaov(x, ina, rads = TRUE)
```

---

BIC for the model based clustering using mixtures of von Mises-Fisher distributions  
*BIC to choose the number of components in a model based clustering  
using mixtures of von Mises-Fisher distributions*

---

**Description**

BIC to choose the number of components in a model based clustering using mixtures of von Mises-Fisher distributions

**Usage**

```
bic.mixvmf(x, A, n.start = 20)
```

**Arguments**

x	A matrix containing directional data.
A	The maximum number of clusters to be tested. Default value is 3.
n.start	The number of random starts to try. See also R's built-in function <a href="#">kmeans</a> for more information about this.

**Details**

If the data are not unit vectors, they are transformed into unit vectors.

**Value**

A plot of the BIC values and a list including:

BIC	The BIC values for all the models tested.
runtime	The run time of the algorithm. A numeric vector. The first element is the user time, the second element is the system time and the third element is the elapsed time.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Hornik, K. and Grun, B. (2014). movMF: An R package for fitting mixtures of von Mises-Fisher distributions. *Journal of Statistical Software*, 58(10):1–31.

**See Also**

[mixvmf.mle](#), [rmixvmf](#), [mixvmf.contour](#)

**Examples**

```
x <- as.matrix( iris[, 1:4] )
x <- x / sqrt( rowSums(x^2) )
bic.mixvmf(x, 5)
```

---

Bootstrap 2-sample mean test for (hyper-)spherical data

*Bootstrap 2-sample mean test for (hyper-)spherical data*

---

**Description**

Bootstrap 2-sample mean test for (hyper-)spherical data.

**Usage**

```
hcf.boot(x1, x2, fc = TRUE, B = 999)
lr.boot(x1, x2, B = 999)
hclr.boot(x1, x2, B = 999)
embed.boot(x1, x2, B = 999)
het.boot(x1, x2, B = 999)
```

**Arguments**

x1	A matrix with the data in Euclidean coordinates, i.e. unit vectors.
x2	A matrix with the data in Euclidean coordinates, i.e. unit vectors.
fc	A boolean that indicates whether a corrected F test should be used or not.
B	The number of bootstraps to perform.

**Details**

The high concentration (`hcf.boot`), log-likelihood ratio (`lr.boot`), high concentration log-likelihood ratio (`hclr.boot`), embedding approach (`embed.boot`) or the non equal concentration parameters approach (`het.boot`) is used.

**Value**

A vector including two or three numbers, the test statistic value, the bootstrap p-value of the test and the common concentration parameter  $\kappa$  based on all the data.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <[mtsagris@uoc.gr](mailto:mtsagris@uoc.gr)>.

**References**

- Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.
- Rumcheva P. and Presnell B. (2017). An improved test of equality of mean directions for the Langevin-von Mises-Fisher distribution. Australian & New Zealand Journal of Statistics, 59(1), 119-135.
- Tsagris M. and Alenazi A. (2022). An investigation of hypothesis testing procedures for circular and spherical mean vectors. Communications in Statistics-Simulation and Computation (Accepted for publication).

**See Also**

[hcf.aov](#), [hcf.perm](#), [spherconc.test](#), [conc.test](#)

**Examples**

```
x <- rvmf(60, rnorm(3), 15)
ina <- rep(1:2, each = 30)
x1 <- x[ina == 1, ]
x2 <- x[ina == 2, ]
hcf.boot(x1, x2)
lr.boot(x1, x2)
het.boot(x1, x2)
```

---

Bootstrap 2-sample mean test for circular data

*Bootstrap 2-sample mean test for circular data*

---

### Description

Bootstrap 2-sample mean test for circular data.

### Usage

```
hcfcirc.boot(u1, u2, rads = TRUE, B = 999)
lrcirc.boot(u1, u2, rads = TRUE, B = 999)
hclrcirc.boot(u1, u2, rads = TRUE, B = 999)
embedcirc.boot(u1, u2, rads = TRUE, B = 999)
hetcirc.boot(u1, u2, rads = TRUE, B = 999)
```

### Arguments

u1	A numeric vector containing the data of the first sample.
u2	A numeric vector containing the data of the first sample.
rads	If the data are in radians, this should be TRUE and FALSE otherwise.
B	The number of bootstraps to perform.

### Details

The high concentration (`hcfcirc.boot`), the log-likelihood ratio test (`lrcirc.boot`), high concentration log-likelihood ratio (`hclrcirc.boot`), embedding approach (`embedcirc.boot`), or the non equal concentration parameters approach (`hetcirc.boot`) is used.

### Value

A vector including two or three numbers, the test statistic value, the bootstrap p-value of the test and the common concentration parameter  $\kappa$  based on all the data.

### Author(s)

Michail Tsagris.

R implementation and documentation: Michail Tsagris <[mtsagris@uoc.gr](mailto:mtsagris@uoc.gr)>.

### References

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.

Rumcheva P. and Presnell B. (2017). An improved test of equality of mean directions for the Langevin-von Mises-Fisher distribution. Australian & New Zealand Journal of Statistics, 59(1), 119-135.

Tsagris M. and Alenazi A. (2022). An investigation of hypothesis testing procedures for circular and spherical mean vectors. Communications in Statistics-Simulation and Computation (Accepted for publication).

### See Also

[hcf.circaov](#), [het.aov](#)

### Examples

```
u1 <- rvonmises(20, 2.4, 5)
u2 <- rvonmises(20, 2.4, 10)
hcfcirc.boot(u1, u2)
```

---

Check visually whether matrix Fisher samples is correctly generated or not  
*Check visually whether matrix Fisher samples is correctly generated or not.*

---

### Description

It plots the log probability trace of matrix Fisher distribution which should close to the maximum value of the logarithm of matrix Fisher distribution, if samples are correctly generated.

### Usage

```
visual.check(x, Fa)
```

### Arguments

x	The simulated data. An array with at least 2 3x3 matrices.
Fa	An arbitrary 3x3 matrix represents the parameter matrix of this distribution.

### Details

For a given parameter matrix Fa, maximum value of the logarithm of matrix Fisher distribution is calculated via the form of singular value decomposition of  $Fa = U\Lambda V^T$  which is  $tr(\Lambda)$ . Multiply the last column of  $U$  by  $-1$  and replace small eigenvalue, say,  $\lambda_3$  by  $-\lambda_3$  if  $|UV^T| = -1$ .

### Value

A plot which shows log probability trace of matrix Fisher distribution. The values are also returned.

### Author(s)

Anamul Sajib<[sajibstat@du.ac.bd](mailto:sajibstat@du.ac.bd)>

R implementation and documentation: Anamul Sajib<[sajibstat@du.ac.bd](mailto:sajibstat@du.ac.bd)>

**References**

Habeck M. (2009). Generation of three-dimensional random rotations in fitting and matching problems. *Computational Statistics*, 24(4):719–731.

**Examples**

```
Fa <- matrix( c(85, 11, 41, 78, 39, 60, 43, 64, 48), ncol = 3) / 10
x <- rmatrixfisher(1000, Fa)
a <- visual.check(x, Fa)
```

---

Circular correlations between one and many circular variables  
*Circular correlations between two circular variables*

---

**Description**

Circular correlations between two circular variables.

**Usage**

```
circ.cors1(theta, phi)
```

**Arguments**

theta	The first circular variable expressed in radians, not degrees.
phi	The other circular variable. In the case of "circ.cors1" this is a matrix with many circular variables. In either case, the values must be in radians, not degrees.

**Details**

Correlation for circular variables using the cosinus and sinus formula of Jammaladaka and Sen-Gupta (1988).

**Value**

A matrix with two columns, the correlations and the p-values.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**References**

Jammalamadaka, R. S. and Sengupta, A. (2001). *Topics in circular statistics*. World Scientific.  
Jammalamadaka, S. R. and Sarma, Y. R. (1988). A correlation coefficient for angular variables. *Statistical Theory and Data Analysis*, 2:349–364.

**See Also**[spml.reg](#)**Examples**

```
y <- runif(50, 0, 2 * pi)
x <- matrix(runif(50 * 10, 0, 2 * pi), ncol = 10)
circ.cors1(y, x)
```

---

Circular correlations between two circular variables

*Circular correlations between two circular variables*

---

**Description**

Circular correlations between two circular variables.

**Usage**

```
circ.cor1(theta, phi, rads = FALSE)
```

```
circ.cor2(theta, phi, rads = FALSE)
```

**Arguments**

theta	The first circular variable.
phi	The other circular variable.
rads	If the data are expressed in rads, then this should be TRUE. If the data are in degrees, then this is FALSE.

**Details**

circ.cor1: Correlation for circular variables using the cosinus and sinus formula of Jammaladaka and SenGupta (1988).

circ.cor2: Correlation for circular variables using the cosinus and sinus formula of Mardia and Jupp (2000).

**Value**

A vector including:

rho	The value of the correlation coefficient.
p-value	The p-value of the zero correlation hypothesis testing.



**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Jammalamadaka, R. S. and Sengupta, A. (2001). Topics in circular statistics. World Scientific.

Jammalamadaka, S. R. and Sarma, Y. R. (1988) . A correlation coefficient for angular variables. Statistical Theory and Data Analysis, 2:349–364.

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.

**See Also**

[circlin.cor](#), [circ.cor2](#), [spml.reg](#)

**Examples**

```
y <- runif(50, 0, 2 * pi)
x <- runif(50, 0, 2 * pi)
circ.cor1(x, y, rads = TRUE)
circ.cor2(x, y, rads = TRUE)
```

---

Circular or angular regression

*Circular or angular regression*

---

**Description**

Regression with circular dependent variable and Euclidean or categorical independent variables.

**Usage**

```
spml.reg(y, x, rads = TRUE, xnew = NULL, seb = FALSE, tol = 1e-07)
```

**Arguments**

y	The dependent variable, a numerical vector, it can be in radians or degrees.
x	The independent variable(s). Can be Euclidean or categorical (factor variables).
rads	If the dependent variable is expressed in rads, this should be TRUE and FALSE otherwise.
xnew	The new values of some independent variable(s) whose circular values you want to predict. Can be Euclidean or categorical. If they are categorical, the user must provide them as dummy variables. It does not accept factor variables. If you have no new x values, leave it NULL (default).

seb	a boolean variable. If TRUE, the standard error of the coefficients will be returned. Set to FALSE in case of simulation studies or in other cases such as a forward regression setting for example. In these cases, it can save some time.
tol	The tolerance value to terminate the Newton-Raphson algorithm.

### Details

The Newton-Raphson algorithm is fitted in this regression as described in Presnell et al. (1998).

### Value

A list including:

runtime	The runtime of the procedure.
iters	The number of iterations required until convergence of the EM algorithm.
beta	The regression coefficients.
seb	The standard errors of the coefficients.
loglik	The value of the maximised log-likelihood.
est	The fitted values expressed in radians if the observed data are in radians and in degrees otherwise. If <code>xnew</code> is not NULL, i.e. if you have new <code>x</code> values, then the predicted values of <code>y</code> will be returned.

### Author(s)

Michail Tsagris

R implementation and documentation: Michail Tsagris <[mtsagris@uoc.gr](mailto:mtsagris@uoc.gr)> and Giorgos Athineou <[gioathineou@gmail.com](mailto:gioathineou@gmail.com)>

### References

Presnell Brett, Morrison Scott P. and Littell Ramon C. (1998). Projected multivariate linear models for directional data. *Journal of the American Statistical Association*, 93(443): 1068-1077.

### See Also

[circlin.cor](#), [circ.cor1](#), [circ.cor2](#), [spher.cor](#), [spher.reg](#)

### Examples

```
x <- rnorm(100)
z <- cbind(3 + 2 * x, 1 - 3 * x)
y <- cbind( rnorm(100,z[,1], 1), rnorm(100, z[,2], 1) )
y <- y / sqrt( rowSums(y^2) )
y <- ( atan( y[, 2] / y[, 1] ) + pi * I(y[, 1] < 0) ) %% (2 * pi)
spml.reg(y, x, rads = TRUE)
```

---

Circular-linear correlation

*Circular-linear correlation*

---

### **Description**

It calculates the squared correlation between a circular and one or more linear variables.

### **Usage**

```
circlin.cor(theta, x, rads = FALSE)
```

### **Arguments**

theta	The circular variable.
x	The linear variable or a matrix containing many linear variables.
rads	If the circular variable is in rads, this should be TRUE and FALSE otherwise.

### **Details**

The squared correlation between a circular and one or more linear variables is calculated.

### **Value**

A matrix with as many rows as linear variables including:

R-squared	The value of the squared correlation.
p-value	The p-value of the zero correlation hypothesis testing.

### **Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

### **References**

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.

### **See Also**

[circ.cor1](#), [circ.cor2](#), [spml.reg](#)

**Examples**

```
phi <- rvonmises(50, 2, 20, rads = TRUE)
x <- 2 * phi + rnorm(50)
y <- matrix(rnorm(50 * 5), ncol = 5)
circlin.cor(phi, x, rads = TRUE)
circlin.cor(phi, y, rads = TRUE)
```

---

Column-wise MLE of the angular Gaussian and the von Mises Fisher distributions  
*Column-wise MLE of the angular Gaussian and the von Mises Fisher distributions*

---

**Description**

Column-wise MLE of the angular Gaussian and the von Mises Fisher distributions.

**Usage**

```
colspml.mle(x ,tol = 1e-07, maxiters = 100, parallel = FALSE)
colvm.mle(x, tol = 1e-07)
```

**Arguments**

<code>x</code>	A numerical matrix with data. Each column refers to a different vector of observations of the same distribution. The values of for Lognormal must be greater than zero, for the logitnormal they must be percentages, excluding 0 and 1, whereas for the Borel distribution the <code>x</code> must contain integer values greater than 1.
<code>tol</code>	The tolerance value to terminate the Newton-Raphson algorithm.
<code>maxiters</code>	The maximum number of iterations that can take place in each regression.
<code>parallel</code>	Do you want this to be executed in parallel or not. The parallel takes place in C++, and the number of threads is defined by each system's available cores.

**Details**

For each column, `spml.mle` function is applied that fits the angular Gaussian distribution estimates its parameters and computes the maximum log-likelihood.

**Value**

A matrix with four columns. The first two are the mean vector, then the  $\gamma$  parameter, and the fourth column contains maximum log-likelihood.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**References**

Presnell Brett, Morrison Scott P. and Littell Ramon C. (1998). Projected multivariate linear models for directional data. *Journal of the American Statistical Association*, 93(443): 1068-1077.

**See Also**

[spml.mle](#), [spml.reg](#), [vm.mle](#), [vmf.mle](#)

**Examples**

```
x <- matrix( runif(100 * 10), ncol = 10)
a <- colspml.mle(x)
b <- colvm.mle(x)
x <- NULL
```

---

Column-wise uniformity Watson test for circular data  
*Column-wise uniformity tests for circular data*

---

**Description**

Column-wise uniformity tests for circular data.

**Usage**

```
colwatsons(u, rads = FALSE)
```

**Arguments**

u	A numeric matrix containing the circular data which are expressed in radians. Each column is a different sample.
rads	A boolean variable. If the data are in radians, put this TRUE. If the data are expressed in degrees make this FALSE.

**Details**

These tests are used to test the hypothesis that the data come from a circular uniform distribution.

**Value**

A matrix with two columns, the value of the test statistic and its associated p-value.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

Jammalamadaka, S. Rao and SenGupta, A. (2001). Topics in Circular Statistics, pg. 156-157.

**See Also**

[watson](#), [kuiper](#), [fishkent](#)

**Examples**

```
x <- matrix( rvonmises(n = 50 * 10, m = 2, k = 0), ncol = 10 )
res<-colwatsons(x)
x <- NULL
```

---

Contour plot of a mixture of von Mises-Fisher distributions model

*Contour plot of a mixture of von Mises-Fisher distributions model for spherical data only.*

---

**Description**

Contour lines are produced of mixture model for spherical data only.

**Usage**

```
mixvmf.contour(u, mod)
```

**Arguments**

u	A two column matrix. The first column is the longitude and the second is the latitude.
mod	This is mix.vmf object, actually it is a list. Run a mixture model and save it as mod for example, mod = mix.vmf(x, 3).

**Details**

The contour plot is displayed with latitude and longitude in the axes. No Lambert projection is used here. This works for spherical data only which are given as longitude and latitude.

**Value**

A plot including: The points and the contour lines.

**Author(s)**

Michail Tsagris and Christos Adam.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Christos Adam <pada4m4@gmail.com>.

**References**

Kurt Hornik and Bettina Grün (2014). movMF: An R Package for Fitting Mixtures of von Mises-Fisher Distributions <http://cran.r-project.org/web/packages/movMF/vignettes/movMF.pdf>

**See Also**

[vmf.kerncontour](#), [vmf.contour](#), [mixvmf.mle](#)

**Examples**

```
k <- runif(2, 4, 20)
prob <- c(0.4, 0.6)
mu <- matrix( rnorm(6), ncol = 3 )
mu <- mu / sqrt( rowSums(mu^2) )
x <- rmixvmf(200, prob, mu, k)$x
mod <- mixvmf.mle(x, 2)
y <- euclid.inv(x)
mixvmf.contour(y, mod)
```

---

Contour plot of spherical data using a von Mises-Fisher kernel density estimate  
*Contour plot of spherical data using a von Mises-Fisher kernel density estimate*

---

**Description**

Contour plot of spherical data using a von Mises-Fisher kernel density estimate.

**Usage**

```
vmf.kerncontour(u, thumb = "none", den.ret = FALSE, full = FALSE, ngrid = 100)
```

**Arguments**

<code>u</code>	A two column matrix. The first column is the latitude and the second is the longitude.
<code>thumb</code>	This is either 'none' (default), or 'rot' for the rule of thumb suggested by Garcia-Portugues (2013). If it is "none" it is estimated via cross validation, with the fast function <a href="#">vmfkde.tune</a> .
<code>den.ret</code>	If FALSE (default), plots the contours of the density along with the individual points. If TRUE, will instead return a list with the Longitudes, Latitudes and Densities. Look at the 'value' section for details.
<code>full</code>	If FALSE (default), uses the range of positions from 'u' to calculate and optionally plot densities. If TRUE, calculates densities covering the entire sphere.
<code>ngrid</code>	Sets the resolution of the density calculation.

**Details**

It calculates the contour plot using a von Mises-Fisher kernel for spherical data only.

**Value**

The contour lines of the data. If "den.ret" was set to TRUE a list including:

lat	The latitude values.
long	The longitude values.
h	The optimal bandwidth.
den	The kernel density estimate contour points.

**Author(s)**

Michail Tsagris, Micah J. Waldstein and Christos Adam.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>, Micah J. Waldstein <micah@waldste.in> and Christos Adam <pada4m4@gmail.com>.

**References**

Garcia Portuges, E. (2013). Exact risk improvement of bandwidth selectors for kernel density estimation with directional data. *Electronic Journal of Statistics*, 7, 1655–1685.

**See Also**

[vmf.kde](#), [vmfkde.tune](#), [vmf.contour](#), [kent.datacontour](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 15)
x <- euclid.inv(x)

vmf.kerncontour(x, "rot")
```

---

Contour plot of the Kent distribution for some data  
*Contour plot of the Kent distribution for some data*

---

**Description**

The contour plot of the Kent distribution on the sphere for some data is produced.

**Usage**

```
kent.datacontour(x)
```



**Arguments**

`x` A two column matrix, where the first column is the latitude and the second column is the longitude. If the matrix has two columns, it is assumed to have unit vectors and in this case it is turned into latitude and longitude.

**Details**

MLE of the parameters of the Kent distribution are calculated, then the contour plot is plotted using these estimates and finally the data are also plotted.

**Value**

A plot containing the contours of the distribution along with the data.

**Author(s)**

Michail Tsagris and Christos Adam.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Christos Adam <pada4m4@gmail.com>.

**References**

Kent John (1982). The Fisher-Bingham distribution on the sphere. *Journal of the Royal Statistical Society, Series B*, 44(1): 71-80.

**See Also**

[kent.contour](#), [kent.mle](#), [vmf.kerncontour](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 10)
kent.mle(x)
y <- euclid.inv(x)

kent.datacontour(y)
```

---

Contour plot of the Kent distribution without any data

*Contour plot of the Kent distribution without any data*

---

**Description**

The contour plot of the Kent distribution on the sphere is produced. The user can see how the shape and ovalness change as he/she changes the ovalness parameter.

**Usage**

```
kent.contour(k, b)
```

**Arguments**

k	The concentration parameter.
b	The ovalness parameter. It has to be less than $k/2$ in order for the distribution to be unimodal. Otherwise it is bimodal.

**Details**

The goal of this function is for the user to see how the Kent distribution looks like.

**Value**

A plot containing the contours of the distribution.

**Author(s)**

Michail Tsagris and Christos Adam.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Christos Adam <pada4m4@gmail.com>.

**References**

Kent John (1982). The Fisher-Bingham distribution on the sphere. *Journal of the Royal Statistical Society, Series B*, 44(1): 71-80.

**See Also**

[kent.datacontour](#), [kent.mle](#), [vmf.contour](#), [vmf.kerncontour](#)

**Examples**

```
kent.contour(10, 4)
```

---

Contour plots of the von Mises-Fisher distribution

*Contour plots of the von Mises-Fisher distribution on the sphere*

---

**Description**

Contour plots of the von Mises-Fisher distribution on the sphere.

**Usage**

```
vmf.contour(k)
```

**Arguments**

k                    The concentration parameter.

**Details**

The user specifies the concentration parameter only and not the mean direction or data. This is for illustration purposes only. The graph will always contain circles, as the von Mises-Fisher distribution is the analogue of a bivariate normal in two dimensions with a zero covariance.

**Value**

A contour plot of the von Mises-Fisher distribution.

**Author(s)**

Michail Tsagris and Christos Adam.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Christos Adam <pada4m4@gmail.com>.

**See Also**

[rvmf](#), [vmf.mle](#), [vmf.kerncontour](#), [kent.contour](#), [sphereplot](#)

**Examples**

```
vmf.contour(5)
```

---

Conversion of cosines to azimuth and plunge  
*Conversion of cosines to azimuth and plunge*

---

**Description**

Conversion of cosines to azimuth and plunge.

**Usage**

```
cosap(x,y,z)
```

**Arguments**

x	x component of cosine.
y	y component of cosine.
z	z component of cosine.

**Details**

Orientation: x>0 is 'eastward', y>0 is 'southward', and z>0 is 'downward'.

**Value**

A list including:

A	The azimuth
P	The plunge

**Author(s)**

Eli Amson

R implementation and documentation: Eli Amson <eli.amson1988@gmail.com>

**References**

Amson E, Arnold P, Van Heteren AH, Cannoville A, Nyakatura JA. Trabecular architecture in the forelimb epiphyses of extant xenarthrans (Mammalia). *Frontiers in Zoology*.

**See Also**

[euclid](#), [euclid.inv](#), [eul2rot](#)

**Examples**

```
cosap(-0.505, 0.510, -0.696)
```

---

Converting a rotation matrix on  $SO(3)$  to an unsigned unit quaternion

*Converting a rotation matrix on  $SO(3)$  to an unsigned unit quaternion*

---

## Description

It returns an unsigned unit quaternion in  $S^3$  (the four-dimensional sphere) from a  $3 \times 3$  rotation matrix on  $SO(3)$ .

## Usage

```
rot2quat(X)
```

## Arguments

X                      A rotation matrix in  $SO(3)$ .

## Details

Firstly construct a system of linear equations by equating the corresponding components of the theoretical rotation matrix proposed by Prentice (1986), and given a rotation matrix. Finally, the system of linear equations are solved by following the tricks mentioned in second reference here in order to achieve numerical accuracy to get quaternion values.

## Value

A unsigned unit quaternion.

## Author(s)

Anamul Sajib

R implementation and documentation: Anamul Sajib <sajibstat@du.ac.bd>

## References

Prentice, M. J. (1986). Orientation statistics without parametric assumptions. *Journal of the Royal Statistical Society. Series B: Methodological* 48(2). //http://www.euclideanspace.com/maths/geometry/rotations/conversions

## See Also

[quat2rot](#), [rotation](#), [Arotation](#) \ [link{rot.matrix}](#)

**Examples**

```
x <- rnorm(4)
x <- x/sqrt( sum(x^2) ) ## an unit quaternion in R4 ##
R <- quat2rot(x)
R
x
rot2quat(R) ## sign is not exact as you can see
```

---

Converting an unsigned unit quaternion to rotation matrix on  $SO(3)$

*Converting an unsigned unit quaternion to rotation matrix on  $SO(3)$*

---

**Description**

It forms a (3 x 3) rotation matrix on  $SO(3)$  from an unsigned unit quaternion in  $S^3$  (the four-dimensional sphere).

**Usage**

```
quat2rot(x)
```

**Arguments**

x                    An unsigned unit quaternion in  $S^3$ .

**Details**

Given an unsigned unit quaternion in  $S^3$  it forms a rotation matrix on  $SO(3)$ , according to the transformation proposed by Prentice (1986).

**Value**

A rotation matrix.

**Author(s)**

Anamul Sajib

R implementation and documentation: Anamul Sajib <sajibstat@du.ac.bd>

**References**

Prentice, M. J. (1986). Orientation statistics without parametric assumptions. *Journal of the Royal Statistical Society. Series B: Methodological* 48(2).

**See Also**

[rot2quat](#), [rotation](#), [Arotation rot.matrix](#)

**Examples**

```
x <- rnorm(4)
x <- x/sqrt( sum(x^2) )
x          ## an unit quaternion in R4 ##
quat2rot(x)
```

---

Cross validation for estimating the classification rate

*Cross validation for estimating the classification rate*

---

**Description**

Cross validation for estimating the classification rate.

**Usage**

```
dirda.cv(x, ina, folds = NULL, nfolds = 10, k = 2:10, stratified = FALSE,
         type = c("vmf", "iag", "esag", "kent", "knn"),
         seed = NULL, B = 1000, parallel = FALSE)
```

**Arguments**

<code>x</code>	A matrix with the data in Euclidean coordinates, i.e. unit vectors. The matrix must have three columns, only spherical data are currently supported.
<code>ina</code>	A variable indicating the groupings.
<code>folds</code>	Do you already have a list with the folds? If not, leave this NULL.
<code>nfolds</code>	How many folds to create?
<code>k</code>	If you choose to use k-NN, what will be the k values?
<code>stratified</code>	Should the folds be created in a stratified way? i.e. keeping the distribution of the groups similar through all folds?
<code>seed</code>	If seed is TRUE, the results will always be the same.
<code>type</code>	The type of classifier to use. The available options are "vmf" (von Mises-Fisher distribution), "esag" (ESAG distribution), "kent" (Kent distribution), "knn" (k-NN algorithm). You can choose any of them or all of them. Note that "esag" and "kent" work only with spherical data.
<code>B</code>	If you used k-NN, should a bootstrap correction of the bias be applied? If yes, 1000 is a good value.
<code>parallel</code>	If you want the standard -NN algorithm to take place in parallel set this equal to TRUE.

**Details**

Cross-validation for the estimation of the performance of a classifier.

The estimated performance of the best classifier is overestimated. After the cross-validation procedure, the predicted values produced by all classifiers are collected, from all folds, in an  $n \times M$  matrix, where  $n$  is the number of samples and  $M$  the number of all classifiers used. We sample rows (predictions) with replacement from  $P$  and denote them as the in-sample values. The non re-sampled rows are denoted as out-of-sample values. The performance of each classifier in the in-sample rows is calculated and the classifier with the optimal performance is selected, followed by the calculation of performance in the out-of-sample values. This process is repeated  $B$  times and the average performance is returned. The only computational overhead is with the repetitive resampling and calculation of the performance, i.e. no model or classifier is fitted nor trained. For more information see Tsamardinos et al. (2018). This procedure though takes place only for the  $k$ -NN algorithm.

The good thing with the function is that you can run any method you want by supplying the folds yourselves using the command `makefolds`. Then suppose you want to run another method. By supplying the same folds you will be able to have comparative results for all methods.

**Value**

A list including:

<code>perf</code>	A vector with the estimated performance of each classifier.
<code>best</code>	The classifier with the optimal performance.
<code>boot.perf</code>	The bootstrap bias corrected performance.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <[mtsagris@uoc.gr](mailto:mtsagris@uoc.gr)>.

**References**

- Tsagris M. and Alenazi A. (2019). Comparison of discriminant analysis methods on the sphere. *Communications in Statistics: Case Studies, Data Analysis and Applications*, 5(4), 467–491.
- Mardia, K. V. and Jupp, P. E. (2000). *Directional statistics*. Chichester: John Wiley & Sons.
- Paine P.J. Preston S.P. & Tsagris M. and Wood A.T.A. (2018). An Elliptically Symmetric Angular Gaussian Distribution. *Statistics and Computing*, 28(3):689–697.
- Morris J. E. & Laycock P. J. (1974). Discriminant analysis of directional data. *Biometrika*, 61(2): 335-341.
- Tsamardinos I., Greasidou E. & Borboudakis G. (2018). *Machine Learning*, 107(12): 1895-1922.

**See Also**

[esag.da](#), [vmfda.pred](#), [dirknn](#), [knn.reg](#)



**Examples**

```
x <- rvmf(300, rnorm(3), 10)
ina <- sample.int(4, 300, replace = TRUE)
dirda.cv(x, ina, B = 1000)
```

---

Cross validation in von Mises-Fisher discriminant analysis

*Cross validation for estimating the classification rate of a discriminant analysis for directional data assuming a von Mises-Fisher distribution*

---

**Description**

Cross validation for estimating the classification rate of a discriminant analysis for directional data assuming a von Mises-Fisher distribution.

**Usage**

```
vmf.da(x, ina, fraction = 0.2, R = 200, seed = NULL)
```

**Arguments**

x	A matrix with the data in Euclidean coordinates, i.e. unit vectors.
ina	A variable indicating the groupings.
fraction	The fraction of data to be used as test set.
R	The number of repetitions.
seed	If seed is TRUE, the results will always be the same.

**Details**

A repeated cross validation procedure is performed to estimate the rate of correct classification.

**Value**

A list including:

percent	The estimated percent of correct classification and two estimated standard deviations. The one is the standard deviation of the rates and the other is assuming a binomial distribution.
ci	Three types of confidence intervals, the standard one, another one based on the binomial distribution and the third one is the empirical one, which calculates the upper and lower 2.5% of the rates.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

- Tsagris M. and Alenazi A. (2019). Comparison of discriminant analysis methods on the sphere. *Communications in Statistics: Case Studies, Data Analysis and Applications*, 5(4), 467–491.
- Morris J. E. and Laycock P. J. (1974). Discriminant analysis of directional data. *Biometrika*, 61(2): 335-341.

**See Also**

[vmfda.pred](#), [mixvmf.mle](#), [vmf.mle](#), [dirknn](#)

**Examples**

```
x <- rvmf(100, rnorm(4), 15)
ina <- rep(1:2, each = 50)
vmf.da(x, ina, fraction = 0.2, R = 200)
```

---

Cross validation with ESAG discriminant analysis

*Cross validation for estimating the classification rate of a discriminant analysis for directional data assuming an ESAG distribution*

---

**Description**

Cross validation for estimating the classification rate of a discriminant analysis for directional data assuming an ESAG distribution.

**Usage**

```
esag.da(y, ina, fraction = 0.2, R = 100, seed = NULL)
```

**Arguments**

y	A matrix with the data in Eulclidean coordinates, i.e. unit vectors. The matrix must have three columns, only spherical data are currently supported.
ina	A variable indicating the groupings.
fraction	The fraction of data to be used as test set.
R	The number of repetitions.
seed	You can specify your own seed number here or leave it NULL.

**Details**

A repeated cross validation procedure is performed to estimate the rate of correct classification.

**Value**

A list including:

percent	The estimated percent of correct classification and two estimated standard deviations. The one is the standard deviation of the rates and the other is assuming a binomial distribution.
ci	Three types of confidence intervals, the standard one, another one based on the binomial distribution and the third one is the empirical one, which calculates the upper and lower 2.5% of the rates.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**References**

Tsagris M. and Alenazi A. (2019). Comparison of discriminant analysis methods on the sphere. *Communications in Statistics: Case Studies, Data Analysis and Applications*, 5(4), 467–491.

Paine P.J., Preston S.P., Tsagris M. and Wood A.T.A. (2018). An Elliptically Symmetric Angular Gaussian Distribution. *Statistics and Computing*, 28(3):689–697.

Mardia, K. V. and Jupp, P. E. (2000). *Directional statistics*. Chichester: John Wiley & Sons.

**See Also**

[vmf.da](#), [vmfda.pred](#), [dirknn](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 15)
ina <- rep(1:2, each = 50)
esag.da(x, ina, fraction = 0.2, R = 50)
```

---

Density of some (hyper-)spherical distributions

*Density of some (hyper-)spherical distributions*

---

**Description**

Density of some (hyper-)spherical distributions.

**Usage**

```
dvmf(y, k, mu, logden = FALSE )
iagd(y, mu, logden = FALSE)
dpurka(y, a, theta, logden = FALSE)
```

**Arguments**

y	A matrix or a vector with the data expressed in Euclidean coordinates, i.e. unit vectors.
k	The concentration parameter of the von Mises-Fisher distribution.
a	The concentration parameter of the Purkayastha distribution.
mu	The mean direction (unit vector) of the von Mises-Fisher distribution or the mean direction of the IAG distribution.
theta	The median direction for the Purkayastha distribution.
logden	If you the logarithm of the density values set this to TRUE.

**Details**

The density of the von Mises-Fisher, of the IAG or of the Purkayastha distribution is computed.

**Value**

A vector with the (log) density values of y.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**References**

- Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chicester: John Wiley & Sons.
- Kent John (1982). The Fisher-Bingham distribution on the sphere. Journal of the Royal Statistical Society, Series B, 44(1): 71-80.
- Purkayastha S. (1991). A Rotationally Symmetric Directional Distribution: Obtained through Maximum Likelihood Characterization. The Indian Journal of Statistics, Series A, 53(1): 70-83
- Cabrera J. and Watson G. S. (1990). On a spherical median related distribution. Communications in Statistics-Theory and Methods, 19(6): 1973-1986.

**See Also**

[kent.mle](#), [rkent](#), [esag.mle](#)

**Examples**

```
m <- colMeans( as.matrix( iris[,1:3] ) )
y <- rvmf(1000, m = m, k = 10)
dvmf(y, k=10, m )
```

---

Density of some circular distributions

*Density of some circular distributions*

---

## Description

Density of some circular distributions.

## Usage

```
dvm(x, m, k, rads = FALSE, logden = FALSE)
dspml(x, mu, rads = FALSE, logden = FALSE)
dwrapcauchy(x, m, rho, rads = FALSE, logden = FALSE)
dcircpurka(x, m, a, rads = FALSE, logden = FALSE)
dggvm(x, param, rads = FALSE, logden = FALSE)
dcircbeta(x, m, a, b, rads = FALSE, logden = FALSE)
dcardio(x, m, rho, rads = FALSE, logden = FALSE)
```

## Arguments

x	A vector with circular data.
m	The mean value of the von Mises distribution and of the cardioid, a scalar. This is the median for the circular Purkayastha distribution.
mu	The mean vector, a vector with two values for the "spml".
k	The concentration parameter.
rho	The <i>rho</i> parameter of the wrapped Cauchy distribution.
a	The $\alpha$ parameter of the circular Purkayastha distribution or the $\alpha$ parameter of the circular beta distribution.
b	The $\beta$ parameter of the circular beta distribution.
param	The vector of parameters of the GGVM distribution as returned by the function <a href="#">ggvm.mle</a> .
rads	If the data are in rads, then this should be TRUE, otherwise FALSE.
logden	If you the logarithm of the density values set this to TRUE.

## Details

The density of the von Mises, bivariate projected normal, wrapped Cauchy or the circular Purkayastha distributions is computed.

## Value

A vector with the (log) density values of x.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**References**

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.

**See Also**

[dkent](#), [rvonmises](#), [desag](#)

**Examples**

```
x <- rvonmises(500, m = 2.5, k = 10, rads = TRUE)
mod <- circ.summary(x, rads = TRUE, plot = FALSE)
den <- dvm(x, mod$mesos, mod$kappa, rads = TRUE, logden = TRUE )
mod$loglik
sum(den)
```

---

Density of the spherical Kent and ESAG distributions

*Density of the spherical Kent and ESAG distributions*

---

**Description**

Density of the spherical Kent and ESAG distributions.

**Usage**

```
dkent(y, G, param, logden = FALSE )
desag(y, mu, gam, logden = FALSE)
```

**Arguments**

y	A matrix or a vector with the data expressed in Euclidean coordinates, i.e. unit vectors.
G	For the Kent distribution only, a 3 x 3 matrix whose first column is the mean direction. The second and third columns are the major and minor axes respectively.
param	For the Kent distribution a vector with the concentration $\kappa$ and ovalness $\beta$ parameters. The $\psi$ has been absorbed inside the matrix G.
mu	The mean vector the ESAG distribution, a vector in $R^3$ .
gam	The two gamma parameters of the ESAG distribution.
logden	If you the logarithm of the density values set this to TRUE.

**Details**

The density of the spherical Kent or spherical ESAG distribution is computed.

**Value**

A vector with the (log) density values of  $y$ .

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <[mtsagris@uoc.gr](mailto:mtsagris@uoc.gr)>

**References**

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.

Kent John (1982). The Fisher-Bingham distribution on the sphere. Journal of the Royal Statistical Society, Series B, 44(1): 71-80.

Paine P.J., Preston S.P., Tsagris M. and Wood A.T.A. (2018). An Elliptically Symmetric Angular Gaussian Distribution. Statistics and Computing, 28(3):689–697.

**See Also**

[kent.mle](#), [rkent](#), [esag.mle](#)

**Examples**

```
m <- colMeans( as.matrix( iris[,1:3] ) )
y <- rkent(1000, k = 10, m = m, b = 4)
mod <- kent.mle(y)
dkent( y, G = mod$G, param = mod$param )
```

---

Euclidean transformation

*Euclidean transformation*

---

**Description**

It transforms the data from the spherical coordinates to Euclidean coordinates.

**Usage**

```
euclid(u)
```

**Arguments**

**u** A two column matrix or even one single vector, where the first column (or element) is the latitude and the second is the longitude. The order is important.

**Details**

It takes the matrix of unit vectors of latitude and longitude and transforms it to unit vectors.

**Value**

A three column matrix:

U                      The Euclidean coordinates of the latitude and longitude.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**See Also**

[euclid.inv](#), [Arotation](#), [lambert](#)

**Examples**

```
x <- rvmf(10, rnorm(3), 10)
u <- euclid.inv(x)
euclid(u)
x
```

---

Euler angles from a rotation matrix on  $SO(3)$

*Compute the Euler angles from a rotation matrix on  $SO(3)$ .*

---

**Description**

It calculates three euler angles  $(\theta_{12}, \theta_{13}, \theta_{23})$  from a  $(3 \times 3)$  rotation matrix  $X$ , where  $X$  is defined as  $X = R_z(\theta_{12}) \times R_y(\theta_{13}) \times R_x(\theta_{23})$ . Here  $R_x(\theta_{23})$  means a rotation of  $\theta_{23}$  radians about the x axis.

**Usage**

```
rot2eul(X)
```

**Arguments**

X                      A rotation matrix which is defined as a product of three elementary rotations mentioned above. Here  $\theta_{12}, \theta_{23} \in (-\pi, \pi)$  and  $\theta_{13} \in (-\pi/2, \pi/2)$ .



**Details**

Given a rotation matrix  $X$ , euler angles are computed by equating each element in  $X$  with the corresponding element in the matrix product defined above. This results in nine equations that can be used to find the euler angles.

**Value**

For a given rotation matrix, there are two equivalent sets of euler angles.

**Author(s)**

Anamul Sajib<sajibstat@du.ac.bd>

R implementation and documentation: Anamul Sajib<sajibstat@du.ac.bd>

**References**

Green, P. J. and Mardia, K. V. (2006). Bayesian alignment using hierarchical models, with applications in proteins bioinformatics. *Biometrika*, 93(2):235–254.

<http://www.staff.city.ac.uk/~sbbh653/publications/euler.pdf>

**See Also**

[eul2rot](#)

**Examples**

```
# three euler angles

theta.12 <- sample( seq(-3, 3, 0.3), 1 )
theta.23 <- sample( seq(-3, 3, 0.3), 1 )
theta.13 <- sample( seq(-1.4, 1.4, 0.3), 1 )

theta.12 ; theta.23 ; theta.13

X <- eul2rot(theta.12, theta.23, theta.13)
X ## A rotation matrix

e <- rot2eul(X)$v1

theta.12 <- e[3]
theta.23 <- e[2]
theta.13 <- e[1]

theta.12 ; theta.23 ; theta.13
```

---

Forward Backward Early Dropping selection for circular data using the SPML regression  
*Forward Backward Early Dropping selection for circular data using  
the SPML regression*

---

### Description

Forward Backward Early Dropping selection for circular data using the SPML regression.

### Usage

```
spml.fbed(y, x, alpha = 0.05, K = 0, backward = FALSE,
          parallel = FALSE, tol = 1e-07, maxiters = 100)
```

### Arguments

y	The response variable, a numeric vector expressed in rads.
x	A matrix with continuous independent variables.
alpha	The significance threshold value for assessing p-values. Default value is 0.05.
K	How many times should the process be repeated? The default value is 0.
backward	After the Forward Early Dropping phase, the algorithm proceeds with the usual Backward Selection phase. The default value is set to TRUE. It is advised to perform this step as maybe some variables are false positives, they were wrongly selected. This is rather experimental now and there could be some mistakes in the indices of the selected variables. <b>Do not use it for now.</b>
parallel	If you want the algorithm to run in parallel set this TRUE.
tol	The tolerance value to terminate the Newton-Raphson algorithm.
maxiters	The maximum number of iterations Newton-Raphson will perform.

### Details

The algorithm is a variation of the usual forward selection. At every step, the most significant variable enters the selected variables set. In addition, only the significant variables stay and are further examined. The non significant ones are dropped. This goes until no variable can enter the set. The user has the option to re-do this step 1 or more times (the argument K). In the end, a backward selection is performed to remove falsely selected variables. Note that you may have specified, for example, K=10, but the maximum value FBED used can be 4 for example.

### Value

If K is a single number a list including:

Note, that the "gam" argument must be the same though.

res	A matrix with the selected variables and their test statistic.
info	A matrix with the number of variables and the number of tests performed (or models fitted) at each round (value of K). This refers to the forward phase only.
runtime	The runtime required.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**References**

Borboudakis G. and Tsamardinos I. (2019). Forward-backward selection with early dropping. *Journal of Machine Learning Research*, 20(8): 1-39.

Tsagis M. (2018). Guide on performing feature selection with the R package MXM. <https://f1000research.com/articles/7-1505>

Presnell Brett, Morrison Scott P. and Littell Ramon C. (1998). Projected multivariate linear models for directional data. *Journal of the American Statistical Association*, 93(443): 1068-1077.

**See Also**

[spml.reg](#), [spml.regs](#), [spml.mle](#)

**Examples**

```
x <- matrix( runif(100 * 50, 1, 100), ncol = 50 )
y <- runif(100)
a <- spml.fbed(y, x)
```

---

Generate random folds for cross-validation

*Generate random folds for cross-validation*

---

**Description**

Random folds for use in a cross validation are generated. There is the option for stratified splitting as well.

**Usage**

```
makefolds(ina, nfolds = 10, stratified = TRUE, seed = NULL)
```

**Arguments**

<code>ina</code>	A variable indicating the groupings.
<code>nfolds</code>	The number of folds to produce.
<code>stratified</code>	A boolean variable specifying whether stratified random (TRUE) or simple random (FALSE) sampling is to be used when producing the folds.
<code>seed</code>	You can specify your own seed number here or leave it NULL.

**Details**

I was inspired by the command in the package **TunePareto** in order to do the stratified version.

**Value**

A list with `nfolds` elements where each elements is a fold containing the indices of the data.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**See Also**

[dirda.cv](#)

**Examples**

```
a <- makefolds(iris[, 5], nfolds = 5, stratified = TRUE)
table(iris[a[[1]], 5]) ## 10 values from each group
```

---

Generation of unit vector(s) with a given angle

*Generation of unit vector(s) with a given angle*

---

**Description**

Generation of unit vector(s) with a given angle from a given unit vector.

**Usage**

```
vec(x, n = 1, deg = 90)
```

**Arguments**

<code>x</code>	A unit vector. If it is not a unit vector it becomes one.
<code>n</code>	The number of unit vectors to return.
<code>deg</code>	The angle between the given vector and the <code>n</code> vectors to be returned. This must be in degrees and it has to be between 0 and 180 degrees. If the angle is 0, the same unit vector will be returned. If the angle is 180, the same unit vector with the signs changed will be returned.

**Details**

The user provides a unit vector and the degrees. The function will return `n` unit vectors whose angle with the given unit vector equals the degrees given. For example, if you want 10 unit vectors perpendicular to the `x` put `vec(x, 10, 90)`.

**Value**

A list including:

runtime	The runtime of the procedure.
crit	The calculated angle between the given unit vector and each of the generated unit vectors.
mat	A matrix with the n unit vectors.

**Author(s)**

Michail Tsagris R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**See Also**

[rvmf](#), [rbingham](#), [rfb](#)

**Examples**

```
x <- rnorm(10)
x <- x / sqrt( sum(x^2) )
a <- vec(x, 20, 90)
```

---

Goodness of fit test for grouped data  
*Goodness of fit test for grouped data*

---

**Description**

Goodness of fit test for grouped data.

**Usage**

```
group.gof(g, ni, m, k, dist = "vm", rads = FALSE, R = 999, ncores = 1)
```

**Arguments**

g	A vector with the group points, either in radians or in degrees.
ni	The frequency of each or group class.
m	The mean direction in radians or in degrees.
k	The concentration parameter, $\kappa$ .
dist	The distribution to be tested, it can be either "vm" or "uniform".
rads	If the data are in radians, this should be TRUE and FALSE otherwise.
R	The number of bootstrap simulations to perform, set to 999 by default.
ncores	The number of cores to use.

**Details**

When you have grouped data, you can test whether the data come from the von Mises-Fisher distribution or from a uniform distribution.

**Value**

A list including:

info	A vector with two elements, the test statistic value and the bootstrap p-value.
runtime	The runtime of the procedure.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Arthur Pewsey, Markus Neuhauser, and Graeme D. Ruxton (2013). Circular Statistics in R.

**See Also**

[pvm](#), [circ.summary](#), [rvonmises](#)

**Examples**

```
x <- rvonmises(100, 2, 10)
g <- seq(min(x) - 0.1, max(x) + 0.1, length = 6)
ni <- as.vector( table( cut(x, g) ) )
group.gof(g, ni, 2, 10, dist = "vm", rads = TRUE, R = 299, ncores = 1)
group.gof(g, ni, 2, 5, dist = "vm", rads = TRUE, R = 299, ncores = 1)
```

---

Habeck's rotation matrix generation

*Generation of three-dimensional random rotations using Habeck's algorithm.*

---

**Description**

It generates random rotations in three-dimensional space that follow a probability distribution, matrix Fisher distribution, arising in fitting and matching problem.

**Usage**

```
habeck.rot(F)
```

**Arguments**

F An arbitrary 3 x 3 matrix represents the parameter matrix of this distribution.

**Details**

Firstly rotation matrices  $\mathbf{X}$  are chosen which are the closest to F, and then parameterized using euler angles. Then a Gibbs sampling algorithm is implemented to generate rotation matrices from the resulting distribution of the euler angles.

**Value**

A simulated rotation matrix.

**Author(s)**

Anamul Sajib<sajibstat@du.ac.bd>

R implementation and documentation: Anamul Sajib<sajibstat@du.ac.bd>

**References**

Habeck M (2009). Generation of three-dimensional random rotations in fitting and matching problems. *Computational Statistics*, 24, 719–731.

**Examples**

```
F <- 10^(-1) * matrix( c(85, 11, 41, 78, 39, 60, 43, 64, 48), ncol = 3 ) ## Arbitrary F matrix
X <- habeck.rot(F)
det(X)
```

---

Haversine distance matrix

*Havesine distance matrix*

---

**Description**

Haversine distance matrix.

**Usage**

```
haversine.dist(x)
```

**Arguments**

x A a matrix of two columns. The first column is the latitude and the second the longitude.

**Details**

The function computes the haversine distance between all observations.

**Value**

A matrix with the haversine distances between all observations.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

[https://en.wikipedia.org/wiki/Haversine\\_formula](https://en.wikipedia.org/wiki/Haversine_formula)

**See Also**

[cosnn](#), [dirknn](#)

**Examples**

```
x <- rvmf(10, rnorm(3), 10)
x <- euclid.inv(x)
haversine.dist(x)
```

---

Hypothesis test for IAG distribution over the ESAG distribution

*Hypothesis test for IAG distribution over the ESAG distribution*

---

**Description**

The null hypothesis is whether an IAG distribution fits the data well, where the alternative is that ESAG distribution is more suitable.

**Usage**

```
iagesag(x, B = 1, tol = 1e-07)
```

**Arguments**

x	A numeric matrix with three columns containing the data as unit vectors in Euclidean coordinates.
B	The number of bootstrap re-samples. By default is set to 999. If it is equal to 1, no bootstrap is performed and the p-value is obtained through the asymptotic distribution.
tol	The tolerance to accept that the Newton-Raphson algorithm used in the IAG distribution has converged.



**Details**

Essentially it is a test of rotational symmetry, whether the two  $\gamma$  parameters are equal to zero. This works for spherical data only.

**Value**

A vector including:

test	The value of the test statistic.
p-value or Bootstrap p-value	The p-value of the test.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**References**

Paine P.J., Preston S.P., Tsagris M. and Wood A.T.A. (2018). An Elliptically Symmetric Angular Gaussian Distribution. *Statistics and Computing*, 28(3):689–697.

**See Also**

[fishkent](#), [esag.mle](#), [kent.mle](#), [iag.mle](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 15)
iagesag(x)
fishkent(x, B = 1)
```

---

Hypothesis test for von Mises-Fisher distribution over Kent distribution  
*Hypothesis test for von Mises-Fisher distribution over Kent distribu-  
tion*

---

**Description**

The null hypothesis is whether a von Mises-Fisher distribution fits the data well, where the alternative is that Kent distribution is more suitable.

**Usage**

```
fishkent(x, B = 999)
```

**Arguments**

x	A numeric matrix containing the data as unit vectors in Euclidean coordinates.
B	The number of bootstrap re-samples. By default is set to 999. If it is equal to 1, no bootstrap is performed and the p-value is obtained through the asymptotic distribution.

**Details**

Essentially it is a test of rotational symmetry, whether Kent's ovalness parameter ( $\beta$ ) is equal to zero. This works for spherical data only.

**Value**

A vector including:

test	The value of the test statistic
p-value or Bootstrap p-value	The p-value of the test.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>.

**References**

Rivest, L. P. (1986). Modified Kent's statistics for testing goodness of fit for the Fisher distribution in small concentrated samples. *Statistics & probability letters*, 4(1): 1-4.

**See Also**

[iagesag](#), [vmf.mle](#), [kent.mle](#), [rkent](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 15)
fishkent(x)
fishkent(x, B = 1)
iagesag(x)
```

---

Interactive 3D plot of spherical data  
*Interactive 3D plot of spherical data*

---

**Description**

Interactive 3D plot of spherical data.

**Usage**

```
sphereplot(x, col = NULL)
```

**Arguments**

<code>x</code>	A matrix with three columns, unit-vectors, spherical data.
<code>col</code>	If you want the points to appear with different colours put numbers here, otherwise leave it NULL.

**Value**

An interactive 3D plot of the spherical data will appear.

**Author(s)**

Michail Tsagris R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**See Also**

[lambert](#), [vmf.contour](#), [euclid](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 5)
sphereplot(x)
ina <- rbinom(100, 1, 0.5) + 1
sphereplot(x, col = ina)
```

---

Inverse of Lambert's equal area projection  
*Inverse of Lambert's equal area projection*

---

### Description

It takes some points from the cartesian coordinates and maps them onto the sphere. The inverse of the Lambert's equal area projection.

### Usage

```
lambert.inv(z, mu)
```

### Arguments

z	A two- column matrix containing the Lambert's equal area projected data.
mu	The mean direction of the data on the sphere.

### Details

The data are first mapped on the sphere with mean direction equal to the north pole. Then, they are rotated to have the given mean direction. It is the inverse of the Lambert's equal area projection.

### Value

A matrix containing spherical data (unit vectors).

### Author(s)

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

### References

Kent, John T. (1982). The Fisher-Bingham distribution on the sphere. Journal of the Royal Statistical Society. Series B (Methodological) 44(1):71-80.

### See Also

[lambert](#)

**Examples**

```
m <- rnorm(3)
m <- m / sqrt( sum(m^2) )
x <- rvmf(20, m, 19)
mu <- vmf.mle(x)$mu
y <- lambert( euclid.inv(x) )
lambert.inv(y, mu)
euclid.inv(x)
```

---

Inverse of the Euclidean transformation

*Inverse of the Euclidean transformation*

---

**Description**

It transforms the data from the Euclidean coordinates to latitude and longitude.

**Usage**

```
euclid.inv(U)
```

**Arguments**

U                    A matrix of unit vectors, or even one single unit vector in three dimensions.

**Details**

It takes the matrix of unit vectors and back transforms it to latitude and longitude.

**Value**

A two column matrix:

u                    The first column is the latitude and the second is the longitude, both expressed in degrees.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**See Also**

[euclid](#), [Arotation](#), [lambert](#)

**Examples**

```
x <- rvmf(10, rnorm(3), 10)
euclid.inv(x)
euclid( euclid.inv(x) )
x
```

---

k-NN algorithm using the arc cosinus distance

*k-NN algorithm using the arc cosinus distance*

---

**Description**

It classifies new observations to some known groups via the k-NN algorithm.

**Usage**

```
dirknn(xnew, ina, x, k = 5, mesos = TRUE, parallel = FALSE, rann = FALSE)
```

**Arguments**

xnew	The new data whose membership is to be predicted, a numeric matrix with unit vectors.
ina	A variable indicating the groups of the data x.
x	The data, a numeric matrix with unit vectors.
k	The number of nearest neighbours, set to 5 by default. It can also be a vector with many values.
mesos	A boolean variable used only in the case of the non standard algorithm (type="NS"). Should the average of the distances be calculated (TRUE) or not (FALSE)? If it is FALSE, the harmonic mean is calculated.
parallel	If you want the standard -NN algorithm to take place in parallel set this equal to TRUE.
rann	If you have large scale datasets and want a faster k-NN search, you can use kd-trees implemented in the R package "RANN". In this case you must set this argument equal to TRUE.

**Details**

The standard algorithm is to keep the k nearest observations and see the groups of these observations. The new observation is allocated to the most frequent seen group. The non standard algorithm is to calculate the classical mean or the harmonic mean of the k nearest observations for each group. The new observation is allocated to the group with the smallest mean distance.

**Value**

A vector including:

g	A matrix with the predicted group(s). It has as many columns as the values of k.
---	--

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

Tsagris M. and Alenazi A. (2019). Comparison of discriminant analysis methods on the sphere. *Communications in Statistics: Case Studies, Data Analysis and Applications*, 5(4), 467–491.

**See Also**

[dirknn.tune](#), [vmfda.pred](#), [mixvmf.mle](#)

**Examples**

```
k <- runif(4, 4, 20)
prob <- c(0.2, 0.4, 0.3, 0.1)
mu <- matrix(rnorm(16), ncol = 4)
mu <- mu / sqrt( rowSums(mu^2) )
da <- rmixvmf(200, prob, mu, k)
nu <- sample(1:200, 180)
x <- da$x[nu, ]
ina <- da$id[nu]
xx <- da$x[-nu, ]
id <- da$id[-nu]
a1 <- dirknn(xx, ina, x, k = 5, mesos = TRUE)
a2 <- dirknn(xx, ina, x, k = 5, mesos = FALSE)
b <- vmfda.pred(xx, x, ina)
table(id, a1)
table(id, a2)
```

---

k-NN regression	<i>k-NN regression with Euclidean or (hyper-)spherical response and or predictor variables</i>
-----------------	--

---

**Description**

k-NN regression with Euclidean or (hyper-)spherical response and or predictor variables.

**Usage**

```
knn.reg(xnew, y, x, k = 5, res = "eucl", estim = "arithmetic")
```

**Arguments**

<code>xnew</code>	The new data, new predictor variables values. A matrix with either euclidean (univariate or multivariate) or (hyper-)spherical data. If you have a circular response, say $u$ , transform it to a unit vector via $(\cos(u), \sin(u))$ . If $xnew = x$ , you will get the fitted values.
<code>y</code>	The currently available data, the response variables values. A matrix with either euclidean (univariate or multivariate) or (hyper-)spherical data. If you have a circular response, say $u$ , transform it to a unit vector via $(\cos(u), \sin(u))$ .
<code>x</code>	The currently available data, the predictor variables values. A matrix with either euclidean (univariate or multivariate) or (hyper-)spherical data. If you have a circular response, say $u$ , transform it to a unit vector via $(\cos(u), \sin(u))$ .
<code>k</code>	The number of nearest neighbours, set to 5 by default. This can also be a vector with many values.
<code>res</code>	The type of the response variable. If it is Euclidean, set this argument equal to "res". If it is a unit vector set it to <code>res="spher"</code> .
<code>estim</code>	Once the $k$ observations with the smallest distance are discovered, what should the prediction be? The arithmetic average of the corresponding $y$ values be used <code>estim="arithmetic"</code> or their harmonic average <code>estim="harmonic"</code> .

**Details**

This function covers a broad range of data, Euclidean and spherical, along with their combinations.

**Value**

A list with as many elements as the number of values of  $k$ . Each element in the list contains a matrix (or a vector in the case of Euclidean data) with the predicted response values.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**See Also**

[knnreg.tune](#), [spher.reg](#), [spml.reg](#)

**Examples**

```

y <- iris[, 1]
x <- as.matrix(iris[, 2:4])
x <- x / sqrt( rowSums(x^2) ) ## Euclidean response
a <- knn.reg(x, y, x, k = 5, res = "eucl", estim = "arithmetic")

y <- iris[, 2:4]
y <- y / sqrt( rowSums(y^2) ) ## Spherical response
x <- iris[, 1]
a <- knn.reg(x, y, x, k = 5, res = "spher", estim = "arithmetic")

```



---

Lambert's equal area projection  
*Lambert's equal area projection*

---

**Description**

It calculates the Lambert's equal area projection.

**Usage**

```
lambert(y)
```

**Arguments**

`y` A two column matrix with the data. The first column is the altitude and the second is the longitude.

**Details**

The spherical data are first rotated so that their mean direction is the north pole and then are projected on the plane tangent to the sphere at the north pole.

**Value**

A two-column matrix with the projected points.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Kent, John T. (1982). The Fisher-Bingham distribution on the sphere. Journal of the Royal Statistical Society. Series B (Methodological) 44(1):71-80.

**See Also**

[euclid](#), [lambert.inv](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 20)
x <- euclid.inv(x)
a <- lambert(x)
plot(a)
```

---

Logarithm of the Kent distribution normalizing constant  
*Logarithm of the Kent distribution normalizing constant*

---

**Description**

Logarithm of the Kent distribution normalizing constant.

**Usage**

```
kent.logcon(k, b, j = 100)
```

**Arguments**

k	The concentration parameter, $\kappa$ .
b	The ovalness parameter, $\beta$ .
j	The number of the terms in the sum to use. By default this is 100.

**Details**

It calculates logarithm of the normalising constant of the Kent distribution.

**Value**

The value of the logarithm of the normalising constant of the Kent distribution.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Kent John (1982). The Fisher-Bingham distribution on the sphere. Journal of the Royal Statistical Society, Series B, 44(1): 71-80.

**See Also**

[fb.saddle](#), [kent.mle](#)

**Examples**

```
kent.logcon(10, 2)  
fb.saddle( c(0, 10, 0), c(0, -2, 2) )
```

---

Many simple circular or angular regressions  
*Many simple circular or angular regressions*

---

**Description**

Many regressions with one circular dependent variable and one Euclidean independent variable.

**Usage**

```
spml.regs(y, x, tol = 1e-07, logged = FALSE, maxiters = 100, parallel = FALSE)
```

**Arguments**

y	The dependent variable, it can be a numerical vector with data expressed in radians or it can be a matrix with two columns, the cosinus and the sinus of the circular data. The benefit of the matrix is that if the function is to be called multiple times with the same response, there is no need to transform the vector every time into a matrix.
x	A matrix with independent variable.
tol	The tolerance value to terminate the Newton-Raphson algorithm.
logged	Do you want the logarithm of the p-value be returned? TRUE or FALSE.
maxiters	The maximum number of iterations to implement.
parallel	Do you want the calculations to take place in parallel? The default value is FALSE.

**Details**

The Newton-Raphson algorithm is fitted in these regression as described in Presnell et al. (1998). For each column of x a circular regression model is fitted and the hypothesis testing of no association between y and this variable is performed.

**Value**

A matrix with two columns, the test statistics and their associated (log) p-values.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

Presnell Brett, Morrison Scott P. and Littell Ramon C. (1998). Projected multivariate linear models for directional data. *Journal of the American Statistical Association*, 93(443): 1068-1077.

**See Also**

[spml.reg](#), [spml.mle](#), [iag.mle](#)

**Examples**

```
x <- rnorm(200)
z <- cbind(3 + 2 * x, 1 -3 * x)
y <- cbind( rnorm(100,z[, 1], 1), rnorm(100, z[, 2], 1) )
y <- y / sqrt( rowSums(y^2) )
x <- matrix( rnorm(100 * 50), ncol = 50 )
a <- Directional::spml.regs(y, x)
x <- NULL
```

---

Maps of the world and the continents

*maps of the world and the continents*

---

**Description**

It produces maps of the world and the continents.

**Usage**

```
asia(title = "Asia", coords = NULL)
africa(title = "Africa", coords = NULL)
europe(title = "Europe", coords = NULL)
north.america(title = "North America", coords = NULL)
oceania(title = "Oceania", coords = NULL)
south.america(title = "South America", coords = NULL)
worldmap(title = "World map", coords = NULL)
```

**Arguments**

<code>title</code>	A character vector with the title of the map.
<code>coords</code>	If you want specific points to appear on the plot give the coordinates as a matrix, where the first column contains the longitude and the second column contains the latitude, in degrees.

**Details**

Maps of the world or the continents are produced. This are experimental functions and plot the countries with specific colouring at the moment. More functionalities will be added in the future.

**Value**

A map of the selected continent or the whole world.

**Author(s)**

Christos Adam.

R implementation and documentation: Christos Adam <pada4m4@gmail.com> and Michail Tsagris.

**See Also**

[sphereplot](#)

**Examples**

```
oceania()
```

---

Mixtures of Von Mises-Fisher distributions

*Mixtures of Von Mises-Fisher distributions*

---

**Description**

It performs model based clustering for circular, spherical and hyperspherical data assuming von Mises-Fisher distributions.

**Usage**

```
mixvmf.mle(x, g, n.start = 10)
```

**Arguments**

x	A matrix with the data expressed as unit vectors.
g	The number of groups to fit. It must be greater than or equal to 2.
n.start	The number of random starts to try. See also R's built-in function <a href="#">kmeans</a> for more information about this.

**Details**

The initial step of the algorithm is not based on a spherical k-means, but on simple k-means. The results are comparable to the package `movMF`.

**Value**

A list including:

param	A matrix with the mean direction, the concentrations parameter and mixing probability of each group.
loglik	The value of the maximised log-likelihood.

pred	The predicted group of each observation.
iter	The number of iteration required by the EM algorithm.
runtime	The run time of the algorithm. A numeric vector. The first element is the user time, the second element is the system time and the third element is the elapsed time.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Kurt Hornik and Bettina Grün (2014). movMF: An R Package for Fitting Mixtures of von Mises-Fisher Distributions <http://cran.r-project.org/web/packages/movMF/vignettes/movMF.pdf>

**See Also**

[rmixvmf](#), [bic.mixvmf](#), [mixvmf.contour](#)

**Examples**

```
k <- runif(4, 4, 6)
prob <- c(0.2, 0.4, 0.3, 0.1)
mu <- matrix(rnorm(16), ncol = 4)
mu <- mu / sqrt( rowSums(mu^2) )
x <- rmixvmf(200, prob, mu, k)$x
mixvmf.mle(x, 3)
mixvmf.mle(x, 4)
mixvmf.mle(x, 5)
```

---

MLE of (hyper-)spherical distributions

*MLE of (hyper-)spherical distributions*

---

**Description**

MLE of (hyper-)spherical distributions.

**Usage**

```
vmf.mle(x, fast = FALSE, tol = 1e-07)
multivmf.mle(x, ina, tol = 1e-07, ell = FALSE)
acg.mle(x, tol = 1e-07)
iag.mle(x, tol = 1e-07)
spcauchy.mle(x, tol = 1e-06)
```

**Arguments**

<code>x</code>	A matrix with directional data, i.e. unit vectors.
<code>fast</code>	IF you want a faster version, but with fewer information returned, set this equal to TRUE.
<code>ina</code>	A numerical vector with discrete numbers starting from 1, i.e. 1, 2, 3, 4,... or a factor variable. Each number denotes a sample or group. If you supply a continuous valued vector the function will obviously provide wrong results.
<code>ell</code>	This is for the <code>multivmf.mle</code> only. Do you want the log-likelihood returned? The default value is TRUE.
<code>tol</code>	The tolerance value at which to terminate the iterations.

**Details**

The `vmf.mle` estimates the mean direction and concentration of a fitted von Mises-Fisher distribution.

The von Mises-Fisher distribution for groups of data is also implemented.

The `acg.mle` fits the angular central Gaussian distribution. There is a constraint on the estimated covariance matrix; its trace is equal to the number of variables. An iterative algorithm takes place and convergence is guaranteed.

The `iag.mle` implements MLE of the spherical projected normal distribution, for spherical data only.

The `sPCAuchy.mle` estimates the parameters of the spherical Cauchy distribution, for any dimension. The name sounds confusing, but it is implemented for arbitrary dimensions, not only the sphere.

**Value**

For the von Mises-Fisher a list including:

<code>loglik</code>	The maximum log-likelihood value.
<code>mu</code>	The mean direction.
<code>kappa</code>	The concentration parameter.

For the multi von Mises-Fisher a list including:

<code>loglik</code>	A vector with the maximum log-likelihood values if <code>ell</code> is set to TRUE. Otherwise NULL is returned.
<code>mi</code>	A matrix with the group mean directions.
<code>ki</code>	A vector with the group concentration parameters.

For the angular central Gaussian a list including:

<code>iter</code>	The number of iterations required by the algorithm to converge to the solution.
<code>cova</code>	The estimated covariance matrix.

For the spherical projected normal a list including:

<code>iters</code>	The number of iteration required by the Newton-Raphson.
--------------------	---

mesi	A matrix with two rows. The first row is the mean direction and the second is the mean vector. The first comes from the second by normalising to have unit length.
param	A vector with the elements, the norm of mean vector, the log-likelihood and the log-likelihood of the spherical uniform distribution. The third value helps in case you want to do a log-likelihood ratio test for uniformity.

For the spherical Cauchy a list including:

mu	The mean direction.
rho	The concentration parameter, this takes values in [0, 1).
loglik	The log-likelihood value.

### Author(s)

Michail Tsagris R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

### References

- Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chicester: John Wiley & Sons.
- Sra, S. (2012). A short note on parameter approximation for von Mises-Fisher distributions: and a fast implementation of  $Is(x)$ . Computational Statistics, 27(1): 177–190.
- Tyler D. E. (1987). Statistical analysis for the angular central Gaussian distribution on the sphere. Biometrika 74(3): 579-589.
- Paine P.J., Preston S.P., Tsagris M and Wood A.T.A. (2018). An Elliptically Symmetric Angular Gaussian Distribution. Statistics and Computing, 28: 689-697.
- Kato S. and McCullagh P. (2018). Mobius transformation and a Cauchy family on the sphere. arXiv preprint arXiv:1510.07679.

### See Also

[racg](#), [vm.mle](#), [rvmf](#)

### Examples

```
m <- c(0, 0, 0, 0)
s <- cov(iris[, 1:4])
x <- racg(100, s)
mod <- acg.mle(x)
mod
cov2cor(mod$cova) ## estimated covariance matrix turned into a correlation matrix
cov2cor(s) ## true covariance matrix turned into a correlation matrix
vmf.mle(x)
x <- rbind( rvmf(100,rnorm(4), 10), rvmf(100,rnorm(4), 20) )
a <- multivmf.mle(x, rep(1:2, each = 100) )
```



---

MLE of some circular distributions

*MLE of some circular distributions*


---

**Description**

MLE of some circular distributions.

**Usage**

```

spml.mle(x, rads = FALSE, tol = 1e-07)
wrapcauchy.mle(x, rads = FALSE, tol = 1e-07)
circexp.mle(x, rads = FALSE, tol = 1e-06)
circbeta.mle(x, rads = FALSE)
cardio.mle(x, rads = FALSE)
ggvm.mle(phi, rads = FALSE)

```

**Arguments**

x	A numerical vector with the circular data. They can either be expressed in radians or in degrees.
phi	A numerical vector with the circular data. They can either be expressed in radians or in degrees.
rads	If the data are in radians set this to TRUE.
tol	The tolerance level to stop the iterative process of finding the MLEs.

**Details**

The parameters of the bivariate angular Gaussian (spml.mle), wrapped Cauchy, circular exponential, cardioid, circular beta and geometrically generalised von Mises distributions are estimated. For the Wrapped Cauchy, the iterative procedure described by Kent and Tyler (1988) is used. The Newton-Raphson algorithm for the angular Gaussian is described in the regression setting in Presnell et al. (1998). The circular exponential is also known as wrapped exponential distribution.

**Value**

A list including:

iters	The iterations required until convergence.
loglik	The value of the maximised log-likelihood.
param	A vector consisting of the estimates of the two parameters, the mean direction for both distributions and the concentration parameter <i>kappa</i> and the <i>rho</i> for the von Mises and wrapped Cauchy respectively. For the circular beta this contains the mean angle and the $\alpha$ and $\beta$ parameters. For the cardioid distribution this contains the $\mu$ and <i>rho</i> parameters. For the generalised von Mises this is a vector consisting of the $\zeta$ , $\kappa$ , $\mu$ and $\alpha$ parameters of the generalised von Mises distribution as described in Equation (2.7) of Dietrich and Richter (2017).

gamma	The norm of the mean vector of the angular Gaussian distribution.
mu	The mean vector of the angular Gaussian distribution.
mumu	In the case of "angular Gaussian distribution this is the mean angle in radians.
lambda	The lambda parameter of the circular exponential distribution.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

- Mardia K. V. and Jupp P. E. (2000). Directional statistics. Chicester: John Wiley & Sons.
- Sra S. (2012). A short note on parameter approximation for von Mises-Fisher distributions: and a fast implementation of  $I_s(x)$ . Computational Statistics, 27(1): 177-190.
- Presnell Brett, Morrison Scott P. and Littell Ramon C. (1998). Projected multivariate linear models for directional data. Journal of the American Statistical Association, 93(443): 1068-1077.
- Kent J. and Tyler D. (1988). Maximum likelihood estimation for the wrapped Cauchy distribution. Journal of Applied Statistics, 15(2): 247-254.
- Dietrich T. and Richter W. D. (2017). Classes of geometrically generalized von Mises distributions. Sankhya B, 79(1): 21-59.
- [https://en.wikipedia.org/wiki/Wrapped\\_exponential\\_distribution](https://en.wikipedia.org/wiki/Wrapped_exponential_distribution)

**See Also**

[circ.summary](#), [purka.mle](#), [rvonmises](#), [vmf.mle](#), [rvmf](#)

**Examples**

```
x <- rvonmises(1000, 3, 9)
spml.mle(x, rads = TRUE)
wrapcauchy.mle(x, rads = TRUE)
circexp.mle(x, rads = TRUE)
ggvm.mle(x, rads = TRUE)
```

---

MLE of some circular distributions with multiple samples

*MLE of some circular distributions with multiple samples*

---

**Description**

MLE of some circular distributions with multiple samples.

**Usage**

```
multivm.mle(x, ina, tol = 1e-07, ell = FALSE)
multispml.mle(x, ina, tol = 1e-07, ell = FALSE)
```

**Arguments**

x	A numerical vector with the circular data. They must be expressed in radians. For the "spml.mle" this can also be a matrix with two columns, the cosine and the sinus of the circular data.
ina	A numerical vector with discrete numbers starting from 1, i.e. 1, 2, 3, 4,... or a factor variable. Each number denotes a sample or group. If you supply a continuous valued vector the function will obviously provide wrong results.
tol	The tolerance level to stop the iterative process of finding the MLEs.
ell	Do you want the log-likelihood returned? The default value is FALSE.

**Details**

The parameters of the von Mises and of the bivariate angular Gaussian distributions are estimated for multiple samples.

**Value**

A list including:

iters	The iterations required until convergence. This is returned in the wrapped Cauchy distribution only.
loglik	A vector with the value of the maximised log-likelihood for each sample.
mi	For the von Mises, this is a vector with the means of each sample. For the angular Gaussian (spml), a matrix with the mean vector of each sample
ki	A vector with the concentration parameter of the von Mises distribution at each sample.
gi	A vector with the norm of the mean vector of the angular Gaussian distribution at each sample.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

- Mardia K. V. and Jupp P. E. (2000). Directional statistics. Chicester: John Wiley & Sons.
- Sra S. (2012). A short note on parameter approximation for von Mises-Fisher distributions: and a fast implementation of  $I_s(x)$ . Computational Statistics, 27(1): 177-190.
- Presnell Brett, Morrison Scott P. and Littell Ramon C. (1998). Projected multivariate linear models for directional data. Journal of the American Statistical Association, 93(443): 1068-1077.
- Kent J. and Tyler D. (1988). Maximum likelihood estimation for the wrapped Cauchy distribution. Journal of Applied Statistics, 15(2): 247-254.

**See Also**

[colspml.mle](#), [purka.mle](#)

**Examples**

```
y <- rcauchy(100, 3, 1)
x <- y
ina <- rep(1:2, 50)
multivm.mle(x, ina)
multispml.mle(x, ina)
```

---

MLE of the ESAG distribution

*MLE of the ESAG distribution*

---

**Description**

MLE of the ESAG distribution.

**Usage**

```
esag.mle(y, full = FALSE, tol = 1e-06)
```

**Arguments**

<code>y</code>	A matrix with the data expressed in Euclidean coordinates, i.e. unit vectors.
<code>full</code>	If you want some extra information, the inverse of the covariance matrix, the <i>rho</i> parameter (smallest eigenvalue of the covariance matrix) and the angle of rotation $\psi$ set this equal to TRUE. Otherwise leave it FALSE.
<code>tol</code>	A tolerance value to stop performing successive optimizations.

**Details**

MLE of the MLE of the ESAG distribution, on the sphere, is implemented. ESAG stands for Elliptically Symmetric Angular Gaussian and it was suggested by Paine et al. (2017). Unlike the projected normal distribution this is rotationally symmetric and is a competitor of the spherical Kent distribution (which is also non rotational symmetric).

**Value**

A list including:

<code>mu</code>	The mean vector in $R^3$ .
<code>gam</code>	The two gamma parameters.
<code>loglik</code>	The log-likelihood value.
<code>vinv</code>	The inverse of the covariance matrix. It is returned if the argument "full" is TRUE.

rho	The <i>rho</i> parameter (smallest eigenvalue of the covariance matrix). It is returned if the argument "full" is TRUE.
psi	The angle of rotation $\psi$ set this equal to TRUE. It is returned if the argument "full" is TRUE.
iag.loglik	The log-likelihood value of the isotropic angular Gaussian distribution. That is, the projected normal distribution which is rotational symmetric.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**References**

Paine P.J., Preston S.P., Tsagris M. and Wood A.T.A. (2018). An Elliptically Symmetric Angular Gaussian Distribution. *Statistics and Computing*, 28(3):689–697.

Mardia, K. V. and Jupp, P. E. (2000). *Directional statistics*. Chichester: John Wiley & Sons.

**See Also**

[desag](#), [resag](#), [iag.mle](#), [kent.mle](#), [acg.mle](#), [circ.summary](#), [sphereplot](#)

**Examples**

```
m <- colMeans( as.matrix( iris[,1:3] ) )
y <- resag(1000, m, c(1,0.5) )
esag.mle(y)
```

---

MLE of the Kent distribution

*MLE of the Kent distribution*

---

**Description**

It estimates the concentration and the ovalness parameter of some directional data assuming the Kent distribution. The mean direction and major and minor axes are also estimated.

**Usage**

```
kent.mle(x)
```

**Arguments**

x                    A matrix containing spherical data in Euclidean coordinates.

**Details**

The Kent distribution is fitted to some data and its parameters are estimated.

**Value**

A list including:

runtime	The run time of the procedure.
G	A 3 x 3 matrix whose first column is the mean direction. The second and third columns are the major and minor axes respectively.
param	A vector with the concentration $\kappa$ and ovalness $\beta$ parameters and the angle $\psi$ used to rotate $\mathbf{H}$ and hence estimate $\mathbf{G}$ as in Kent (1982).
logcon	The logarithm of the normalising constant, using the third type approximation (Kume and Wood, 2005).
loglik	The value of the log-likelihood.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Kent John (1982). The Fisher-Bingham distribution on the sphere. Journal of the Royal Statistical Society, Series B, 44(1): 71-80.

Kume Alfred and Wood Andrew T.A. (2005). Saddlepoint approximations for the Bingham and Fisher-Bingham normalizing constants. Biometrika, 92(2):465-476

**See Also**

[kent.mle](#), [fb.saddle](#), [vmf.mle](#), [wood.mle](#), [sphereplot](#)

**Examples**

```
x <- rvmf(200, rnorm(3), 15)
kent.mle(x)
vmf.mle(x)
A <- diag( c(-5, 0, 5) )
x <- rfb(200, 15, rnorm(3), A)
kent.mle(x)
vmf.mle(x)
```

---

MLE of the Matrix Fisher distribution on  $SO(3)$

*MLE of the Matrix Fisher distribution on  $SO(3)$*

---

### Description

It returns the maximum likelihood estimate of the Matrix Fisher parameter  $F(3 \times 3)$ .

### Usage

```
matrixfisher.mle(X)
```

### Arguments

$X$  An array containing rotation matrices in  $SO(3)$ .

### Value

The components of  $svd(\bar{X})$ .

### Author(s)

Anamul Sajib & Chris Fallaize.

R implementation and documentation: Anamul Sajib <sajibstat@du.ac.bd> & Chris Fallaize.

### References

Prentice M. J. (1986). Orientation statistics without parametric assumptions. *Journal of the Royal Statistical Society. Series B: Methodological* 48(2).

### See Also

[rmatrixfisher](#)

### Examples

```
F <- 10^(-1) * matrix( c(85, 11, 41, 78, 39, 60, 43, 64, 48), ncol = 3 ) ### An arbitrary F matrix
X <- rmatrixfisher(5000, F)
matrixfisher.mle(X)
svd(F)
```

---

MLE of the Purkayashta distribution

*MLE of the Purkayashta distribution*

---

### Description

MLE of the Purkayashta distribution.

### Usage

```
purka.mle(x, tol = 1e-07)
```

### Arguments

x	A numerical vector with data expressed in radians or a matrix with spherical data.
tol	The tolerance value to terminate the Brent algorithm.

### Details

MLE of the Purkayastha distribution is performed.

### Value

A list including:

theta	The median direction.
alpha	The concentration parameter.
loglik	The log-likelihood.
alpha.sd	The standard error of the concentration parameter.

### Author(s)

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

### References

Purkayastha S. (1991). A Rotationally Symmetric Directional Distribution: Obtained through Maximum Likelihood Characterization. *The Indian Journal of Statistics, Series A*, 53(1): 70-83

Cabrera J. and Watson G. S. (1990). On a spherical median related distribution. *Communications in Statistics-Theory and Methods*, 19(6): 1973-1986.

### See Also

[circ.cor1](#)



**Examples**

```
x <- cbind( rnorm(100,1,1), rnorm(100, 2, 1) )
x <- x / sqrt(rowSums(x^2))
purka.mle(x)
```

---

MLE of the Wood bimodal distribution on the sphere

*MLe of the Wood bimodal distribution on the sphere*

---

**Description**

It estimates the parameters of the Wood bimodal distribution.

**Usage**

```
wood.mle(y)
```

**Arguments**

**y** A matrix containing two columns. The first one is the latitude and the second is the longitude, both expressed in degrees.

**Details**

The Wood distribution is fitted to some data and its parameters are estimated. It is a bimodal distribution which contains 5 parameters, just like the Kent distribution.

**Value**

A list including:

<b>info</b>	A 5 x 3 matrix containing the 5 parameters, $\gamma$ , $\delta$ , $\alpha$ , $\beta$ and $\kappa$ along with their corresponding 95% confidence intervals all expressed in degrees.
<b>modes</b>	The two axis of the modes of the distribution expressed in degrees.
<b>unitvectors</b>	A 3 x 3 matrix with the 3 unitvectors associated with the gamma and delta parameters.
<b>loglik</b>	The value of the log-likelihood.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>.

**References**

Wood A.T.A. (1982). A bimodal distribution on the sphere. Journal of the Royal Statistical Society, Series C, 31(1): 52-58.

**See Also**

[kent.mle](#), [esag.mle](#), [vmf.mle](#), [sphereplot](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 15)
x <- euclid.inv(x)
wood.mle(x)
```

---

Naive Bayes classifiers for circular data

*Naive Bayes classifiers for directional data*

---

**Description**

Naive Bayes classifiers for directional data.

**Usage**

```
vm.nb(xnew = NULL, x, ina, tol = 1e-07)
spm1.nb(xnew = NULL, x, ina, tol = 1e-07)
```

**Arguments**

xnew	A numerical matrix with new predictor variables whose group is to be predicted. Each column refers to an angular variable.
x	A numerical matrix with observed predictor variables. Each column refers to an angular variable.
ina	A numerical vector with strictly positive numbers, i.e. 1,2,3 indicating the groups of the dataset. Alternatively this can be a factor variable.
tol	The tolerance value to terminate the Newton-Raphson algorithm.

**Details**

Each column is supposed to contain angular measurements. Thus, for each column a von Mises distribution or an circular angular Gaussian distribution is fitted. The product of the densities is the joint multivariate distribution.

**Value**

A list including:

mu	A matrix with the mean vectors expressed in radians.
mu1	A matrix with the first set of mean vectors.
mu2	A matrix with the second set of mean vectors.

<code>kappa</code>	A matrix with the kappa parameters for the vonMises distribution or with the norm of the mean vectors for the circular angular Gaussian distribution.
<code>ni</code>	The sample size of each group in the dataset.
<code>est</code>	The estimated group of the xnew observations. It returns a numerical value back regardless of the target variable being numerical as well or factor. Hence, it is suggested that you do <code>\`as.numeric(ina)\`</code> in order to see what is the predicted class of the new data.

### Author(s)

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

### See Also

[vmnb.pred](#), [weibull.nb](#)

### Examples

```
x <- matrix( runif( 100, 0, 1 ), ncol = 2 )
ina <- rbinom(50, 1, 0.5) + 1
a <- vm.nb(x, x, ina)
```

---

Normalised spatial median for directional data

*Normalised spatial median for directional data*

---

### Description

Normalised spatial median for directional data.

### Usage

```
nsmedian(x, tol = 1e-07)
```

### Arguments

<code>x</code>	A matrix with Euclidean data, continuous variables.
<code>tol</code>	A tolerance level to terminate the process.

### Details

The spatial median, using a fixed point iterative algorithm, for Euclidean data is calculated. It is a robust location estimate. Then it is normalised to become a unit vector. Generally speaking this might be a better alternative than then [mediandir](#).

**Value**

A vector with the spatial median.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

Ducharme G. R. and Milasevic P. (1987). Spatial median and directional data. *Biometrika*, 74(1), 212-215.

Jyrki Mottonen, Klaus Nordhausen and Hannu Oja (2010). Asymptotic theory of the spatial median. In *Nonparametrics and Robustness in Modern Statistical Inference and Time Series Analysis: A Festschrift in honor of Professor Jana Jureckova*.

T. Karkkainen and S. Ayrano (2005). On computation of spatial median for robust data mining. *Evolutionary and Deterministic Methods for Design, Optimization and Control with Applications to Industrial and Societal Problems, EUROGEN 2005*, R. Schilling, W.Haase, J. Periaux, H. Baier, G. Bugeda (Eds) FLM, Munich. [http://users.jyu.fi/~samiayr/pdf/ayramo\\_eurogen05.pdf](http://users.jyu.fi/~samiayr/pdf/ayramo_eurogen05.pdf)

**See Also**

[mediandir](#)

**Examples**

```
m <- rnorm(3)
m <- m / sqrt( sum(m^2) )
x <- rvmf(100, m, 10)
nsmedian(x)
mediandir(x)
```

---

Permutation based 2-sample mean test for (hyper-)spherical data

*Permutation based 2-sample mean test for (hyper-)spherical data*

---

**Description**

Permutation based 2-sample mean test for (hyper-)spherical data.

**Usage**

```
hcf.perm(x1, x2, B = 999)
lr.perm(x1, x2, B = 999)
hclr.perm(x1, x2, B = 999)
embed.perm(x1, x2, B = 999)
het.perm(x1, x2, B = 999)
```

**Arguments**

x1	A matrix with the data in Euclidean coordinates, i.e. unit vectors.
x2	A matrix with the data in Euclidean coordinates, i.e. unit vectors.
B	The number of permutations to perform.

**Details**

The high concentration (`hcf.perm`), log-likelihood ratio (`lr.perm`), high concentration log-likelihood ratio (`hclr.perm`), embedding approach (`embed.perm`) or the non equal concentration parameters approach (`het.perm`) is used.

**Value**

A vector including:

test	The test statistic value.
p-value	The p-value of the F test.
kappa	The common concentration parameter kappa based on all the data.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <[mtsagris@uoc.gr](mailto:mtsagris@uoc.gr)>.

**References**

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chicester: John Wiley & Sons.

Rumcheva P. and Presnell B. (2017). An improved test of equality of mean directions for the Langevin-von Mises-Fisher distribution. Australian & New Zealand Journal of Statistics, 59(1), 119-135.

Tsagris M. and Alenazi A. (2022). An investigation of hypothesis testing procedures for circular and spherical mean vectors. Communications in Statistics-Simulation and Computation (Accepted for publication).

**See Also**

[hcf.boot](#), [hcf.aov](#), [spherconc.test](#), [conc.test](#)

**Examples**

```
x <- rvmf(60, rnorm(3), 15)
ina <- rep(1:2, each = 30)
x1 <- x[ina == 1, ]
x2 <- x[ina == 2, ]
hcf.perm(x1, x2)
lr.perm(x1, x2)
het.boot(x1, x2)
```

---

Permutation based 2-sample mean test for circular data

*Permutation based 2-sample mean test for circular data*

---

## Description

Permutation based 2-sample mean test for circular data.

## Usage

```
hfcirc.perm(u1, u2, rads = TRUE, B = 999)
hetcirc.perm(u1, u2, rads = TRUE, B = 999)
lrcirc.perm(u1, u2, rads = TRUE, B = 999)
hclrcirc.perm(u1, u2, rads = TRUE, B = 999)
embedcirc.perm(u1, u2, rads = TRUE, B = 999)
```

## Arguments

u1	A numeric vector containing the data of the first sample.
u2	A numeric vector containing the data of the first sample.
rads	If the data are in radians, this should be TRUE and FALSE otherwise.
B	The number of permutations to perform.

## Details

The high concentration (`hfcirc.perm`), log-likelihood ratio (`lrcirc.perm`), high concentration log-likelihood ratio (`hclrcirc.perm`), embedding approach (`embedcirc.perm`) or the non equal concentration parameters approach (`hetcirc.perm`) is used.

## Value

A vector including:

test	The value of the test statistic.
p-value	The p-value of the test.
kappa	The concentration parameter based on all the data. If the <code>hetcirc.perm</code> is used this argument is not returned.

## Author(s)

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

## References

- Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.
- Rumcheva P. and Presnell B. (2017). An improved test of equality of mean directions for the Langevin-von Mises-Fisher distribution. Australian & New Zealand Journal of Statistics, 59(1), 119-135.
- Tsagris M. and Alenazi A. (2022). An investigation of hypothesis testing procedures for circular and spherical mean vectors. Communications in Statistics-Simulation and Computation (Accepted for publication).

## See Also

[hcf.circaov](#), [het.aov](#)

## Examples

```
u1 <- rvonmises(20, 2.4, 5)
u2 <- rvonmises(20, 2.4, 10)
hcfcirc.perm(u1, u2)
lrcirc.perm(u1, u2)
```

---

Prediction in discriminant analysis based on ESAG distribution  
*Prediction of a new observation using discriminant analysis based on ESAGdistribution*

---

## Description

Prediction of a new observation using discriminant analysis based on ESAG distribution.

## Usage

```
esagda.pred(ynew, y, ina)
```

## Arguments

ynew	The new observation(s) (unit vector(s)) whose group is to be predicted.
y	A data matrix with unit vectors, i.e. spherical directional data.
ina	A vector indicating the groups of the data y.

## Details

Prediction of the class of a new spherical vector assuming ESAG distribution.

## Value

A vector with the predicted group of each new observation.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

Tsagris M. and Alenazi A. (2019). Comparison of discriminant analysis methods on the sphere. *Communications in Statistics: Case Studies, Data Analysis and Applications*, 5(4), 467–491.

Paine P.J., Preston S.P., Tsagris M. and Wood A.T.A. (2017). An Elliptically Symmetric Angular Gaussian Distribution. *Statistics and Computing*, 28(3):689–697.

Mardia, K. V. and Jupp, P. E. (2000). *Directional statistics*. Chichester: John Wiley & Sons.

**See Also**

[esag.da](#), [vmfda.pred](#), [dirknn](#), [knn.reg](#)

**Examples**

```
m1 <- rnorm(3)
m2 <- rnorm(3) + 0.5
y <- rbind( rvmf(100, m1, 3), rvmf(80, m2, 5) )
ina <- c( rep(1,100), rep(2, 80) )
ynew <- rbind(rvmf(10, m1, 10), rvmf(10, m2, 5))
id <- rep(1:2, each = 10)
g <- esagda.pred(ynew, y, ina)
table(id, g)
```

---

Prediction in discriminant analysis based on von Mises-Fisher distribution  
*Prediction of a new observation using discriminant analysis based on  
von Mises-Fisher distribution*

---

**Description**

Prediction of the class of a new observation using discriminant analysis based on von Mises-Fisher distribution.

**Usage**

```
vmfda.pred(xnew, x, ina)
```

**Arguments**

xnew	The new observation(s) (unit vector(s)) whose group is to be predicted.
x	A data matrix with unit vectors, i.e. directional data.
ina	A vector indicating the groups of the data x.



**Details**

Discriminant analysis assuming von Mises-Fisher distributions.

**Value**

A vector with the predicted group of each new observation.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

Tsagris M. and Alenazi A. (2019). Comparison of discriminant analysis methods on the sphere. *Communications in Statistics: Case Studies, Data Analysis and Applications*, 5(4), 467–491.

Morris J. E. and Laycock P. J. (1974). Discriminant analysis of directional data. *Biometrika*, 61(2): 335-341.

**See Also**

[vmf.da](#), [mixvmf.mle](#), [dirknn](#), [knn.reg](#)

**Examples**

```
m1 <- rnorm(5)
m2 <- rnorm(5)
x <- rbind( rvmf(100, m1, 5), rvmf(80, m2, 10) )
ina <- c( rep(1,100), rep(2, 80) )
y <- rbind(rvmf(10, m1, 10), rvmf(10, m2, 5))
id <- rep(1:2, each = 10)
g <- vmfda.pred(y, x, ina)
table(id, g)
```

---

Prediction with some naive Bayes classifiers for circular data

*Prediction with some naive Bayes classifiers for circular data*

---

**Description**

Prediction with some naive Bayes classifiers for circular data.

**Usage**

```
vmnb.pred(xnew, mu, kappa, ni)
spm1nb.pred(xnew, mu1, mu2, ni)
```

**Arguments**

xnew	A numerical matrix with new predictor variables whose group is to be predicted. Each column refers to an angular variable.
mu	A matrix with the mean vectors expressed in radians.
mu1	A matrix with the first set of mean vectors.
mu2	A matrix with the second set of mean vectors.
kappa	A matrix with the kappa parameters for the vonMises distribution or with the norm of the mean vectors for the circular angular Gaussian distribution.
ni	The sample size of each group in the dataset.

**Details**

Each column is supposed to contain angular measurements. Thus, for each column a von Mises distribution or an circular angular Gaussian distribution is fitted. The product of the densities is the joint multivariate distribution.

**Value**

A numerical vector with 1, 2, ... denoting the predicted group.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**See Also**

[vm.nb](#), [weibullnb.pred](#)

**Examples**

```
x <- matrix( runif( 100, 0, 1 ), ncol = 2 )
ina <- rbinom(50, 1, 0.5) + 1
a <- vm.nb(x, x, ina)
a2 <- vmnb.pred(x, a$mu, a$kappa, a$ni)
```

---

Probability density function of the von Mises-Fisher distribution

*Probability density function of the von Mises-Fisher distribution*

---

**Description**

Probability density function of the von Mises-Fisher distribution.

**Usage**

```
pvm(theta, m, k, rads = FALSE)
```

**Arguments**

theta	A numerical value, either in radians or in degrees.
m	The mean direction in radians or in degrees.
k	The concentration parameter, $\kappa$ .
rads	If the data are in radians, this should be TRUE and FALSE otherwise.

**Details**

This value calculates the probability of  $x$  being less than theta and is used by [group.gof](#).

**Value**

The probability that of  $x$  being less than theta, where  $x$  follows the von Mises-Fisher distribution.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <[mtsagris@uoc.gr](mailto:mtsagris@uoc.gr)> and Giorgos Athineou <[gioathineou@gmail.com](mailto:gioathineou@gmail.com)>

**References**

Arthur Pewsey, Markus Neuhauser, and Graeme D. Ruxton (2013). Circular Statistics in R.

**See Also**

[group.gof](#), [circ.summary](#), [rvonmises](#)

**Examples**

```
pvm(1, 2, 10, rads = TRUE)
pvm(2, 2, 10, rads = TRUE)
```

---

Random sample of matrices in  $SO(p)$

*Random sample of matrices in  $SO(p)$*

---

**Description**

Random sample of matrices in  $SO(p)$ .

**Usage**

```
rsop(n, p)
```

**Arguments**

n	The sample size, the number of matrices you want to generate.
p	The dimensionality of the matrices.

**Details**

The idea is very simple. Start with a unit vector pointing at the north pole (1,0,...,0). Then generate random numbers from a standard normal and scale them so that they have a unit length. To put it differently, a sample of n values from the uniform distribution on the sphere is generated. Then calculate the rotation matrix required to go from the north pole to each of a generated vector.

**Value**

If n = 1 one matrix is returned. If n is greater than 1, an array with n matrices inside.

**Author(s)**

Michail Tsagris R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

G. J. A. Amaral, I. L. Dryden & Andrew T. A. Wood (2007). Pivotal Bootstrap Methods for k-Sample Problems in Directional Statistics and Shape Analysis. *Journal of the American Statistical Association*, 102(478): 695-707.

**See Also**

[rotation](#), [Arotation](#), [rot.matrix](#)

**Examples**

```
x1 <- rsop(1, 3)
x2 <- rsop(10, 3)
x3 <- rsop(100, 10)
```

---

Rayleigh's test of uniformity

*Rayleigh's test of uniformity*

---

**Description**

It checks whether the data are uniformly distributed on the sphere or hypersphere.

**Usage**

```
rayleigh(x, modif = TRUE, B = 999)
```

**Arguments**

x	A matrix containing the data, unit vectors.
modif	If modif is TRUE, the modification as suggested by Jupp (2001) is used.
B	If B is greater than 1, bootstrap calibration is performed. If it is equal to 1, classical theory is used.

**Details**

The Rayleigh test of uniformity is not the best, when there are two antipodal mean directions. In this case it will fail. It is good to test whether there is one mean direction or not. To put it differently, it tests whether the concentration parameter of the Fisher distribution is zero or not.

**Value**

A vector including:

test	The value of the test statistic.
p-value or Bootstrap p-value	The (bootstrap) p-value of the test.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

- Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.
- Jupp, P. E. (2001). Modifications of the rayleigh and bingham tests for uniformity of directions. *Journal of Multivariate Analysis*, 77(2):1-20.
- Rayleigh, L. (1919). On the problem of random vibrations, and of random flights in one, two, or three dimensions. *The London, Edinburgh, and Dublin Philosophical Magazine and Journal of Science*, 37(220):321-347.

**See Also**

[vmf.mle](#), [meandir.test](#), [acg.mle](#)

**Examples**

```
x <- rvmf(100, rnorm(5), 1) ## Fisher distribution with low concentration
rayleigh(x)
```

---

Read a file as a Filebacked Big Matrix

*Read a file as a Filebacked Big Matrix*

---

## Description

Read a file as a Filebacked Big Matrix.

## Usage

```
read.fbm(file, select)
```

## Arguments

file	The File to read.
select	Indices of columns to read (sorted). The length of select will be the number of columns of the resulting FBM.

## Details

The functions read a file as a Filebacked Big Matrix object. For more information see the "bigstatsr" package.

## Value

A Filebacked Big Matrix object.

## Author(s)

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

## See Also

[vmf.mle](#), [kent.mle](#)

## Examples

```
dataset <- matrix( runif(100 * 50, 1, 100), ncol = 50 )
write.csv(dataset, "dataset.csv")
a <- read.fbm("dataset.csv", select = 1:50)
```

---

Rotation axis and angle of rotation given a rotation matrix

*Rotation axis and angle of rotation given a rotation matrix*

---

**Description**

Given a 3 x 3 rotation matrix, the angle and the axis of rotation are calculated.

**Usage**

```
Arotation(A)
```

**Arguments**

A                    A 3 x 3 rotation matrix.

**Details**

If the user does not supply a rotation matrix a message will appear.

**Value**

A list including:

angle	The angle of rotation expressed in degrees.
axis	The axis of rotation. A vector of two components, latitude and longitude, expressed in degrees.

**Author(s)**

Michail Tsagris R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Course webpage of Howard E. Haber. [http://scipp.ucsc.edu/~haber/ph216/rotation\\_12.pdf](http://scipp.ucsc.edu/~haber/ph216/rotation_12.pdf)  
Ted Chang (1986). Spherical Regression. *Annals of Statistics*, 14(3): 907-924.

**See Also**

[rot.matrix](#), [rotation](#), [rsop](#)

**Examples**

```
ksi <- c(25.31, 24.29)
theta <- 2.38
A <- rot.matrix(ksi, theta, rads = FALSE)
A
Arotation(A)
```

---

Rotation matrix from a rotation axis and angle of rotation  
*Rotation matrix from a rotation axis and angle of rotation*

---

**Description**

It calculates a rotation matrix from a rotation axis and angle of rotation.

**Usage**

```
rot.matrix(ksi, theta, rads = FALSE)
```

**Arguments**

ksi	The rotation axis, a vector with two elements, the first is the latitude and the second is the longitude.
theta	The angle of rotation.
rads	If both the ksi and theta are in rads, this should be TRUE. If both the ksi and theta are in degrees, this should be FALSE.

**Details**

The function accepts as arguments the rotation axis and the angle of rotation and it calculates the requested rotation matrix.

**Value**

A 3 x 3 rotation matrix.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Course webpage of Howard E. Haber. [http://scipp.ucsc.edu/~haber/ph216/rotation\\_12.pdf](http://scipp.ucsc.edu/~haber/ph216/rotation_12.pdf)

Ted Chang (1986). Spherical Regression. *Annals of Statistics*, 14(3): 907-924.

**See Also**

[Arotation](#), [rotation](#), [rsop](#)



**Examples**

```
ksi <- c(25.31, 24.29)
theta <- 2.38
A <- rot.matrix(ksi, theta, rads = FALSE)
A
Arotation(A)
```

---

Rotation matrix on  $SO(3)$  from three Euler angles

*Construct a rotation matrix on  $SO(3)$  from the Euler angles.*

---

**Description**

It forms a rotation matrix  $X$  on  $SO(3)$  by using three Euler angles  $(\theta_{12}, \theta_{13}, \theta_{23})$ , where  $X$  is defined as  $X = R_z(\theta_{12}) \times R_y(\theta_{13}) \times R_x(\theta_{23})$ . Here  $R_x(\theta_{23})$  means a rotation of  $\theta_{23}$  radians about the  $x$  axis.

**Usage**

```
eul2rot(theta.12, theta.23, theta.13)
```

**Arguments**

theta.12	An Euler angle, a number which must lie in $(-\pi, \pi)$ .
theta.23	An Euler angle, a number which must lie in $(-\pi, \pi)$ .
theta.13	An Euler angle, a number which must lie in $(-\pi/2, \pi/2)$ .

**Details**

Given three euler angles a rotation matrix  $X$  on  $SO(3)$  is formed using the transformation according to Green and Mardia (2006) which is defined above.

**Value**

A rotation matrix.

**Author(s)**

Anamul Sajib<sajibstat@du.ac.bd>

R implementation and documentation: Anamul Sajib <sajibstat@du.ac.bd>

**References**

Green, P. J. and Mardia, K. V. (2006). Bayesian alignment using hierarchical models, with applications in proteins bioinformatics. *Biometrika*, 93(2):235–254.

**See Also**[rot2eul](#)**Examples**

```
# three euler angles

theta.12 <- sample( seq(-3, 3, 0.3), 1 )
theta.23 <- sample( seq(-3, 3, 0.3), 1 )
theta.13 <- sample( seq(-1.4, 1.4, 0.3), 1 )

theta.12 ; theta.23 ; theta.13

X <- eul2rot(theta.12, theta.23, theta.13)
X # A rotation matrix
det(X)

e <- rot2eul(X)$v1

theta.12 <- e[3]
theta.23 <- e[2]
theta.13 <- e[1]

theta.12 ; theta.23 ; theta.13
```

---

Rotation matrix to rotate a spherical vector along the direction of another  
*Rotation matrix to rotate a spherical vector along the direction of another*

---

**Description**

A rotation matrix is calculated to rotate a unit vector along the direction of another.

**Usage**

```
rotation(a, b)
```

**Arguments**

a	The initial unit vector.
b	The target unit vector.

**Details**

The function calculates a rotation matrix given two vectors. This rotation matrix is the connection between the two spherical only, vectors.

**Value**

A rotation matrix whose dimension is equal to the length of the unit vectors.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

G. J. A. Amaral, I. L. Dryden & Andrew T. A. Wood (2007). Pivotal Bootstrap Methods for k-Sample Problems in Directional Statistics and Shape Analysis. *Journal of the American Statistical Association*, 102(478): 695-707.

**See Also**

[Arotation](#), [rot.matrix](#), [lambert](#), [lambert.inv](#), [rsop](#)

**Examples**

```
a <- rnorm(3)
a <- a/sqrt(sum(a^2))
b <- rnorm(3)
b <- b/sqrt(sum(b^2))
A <- rotation(a, b)
A
a ; b
a %*% t(A)
```

```
a <- rnorm(7)
a <- a/sqrt(sum(a^2))
b <- rnorm(7)
b <- b/sqrt(sum(b^2))
A <- rotation(a, b)
A
a ; b
a %*% t(A)
```

---

Saddlepoint approximations of the Fisher-Bingham distributions  
*Saddlepoint approximations of the Fisher-Bingham distributions*

---

**Description**

It calculates the logarithm of the normalising constant of the Fisher-Bingham distribution.

**Usage**

```
fb.saddle(gam, lam)
```

**Arguments**

gam	A numeric vector containing the parameters of the Fisher part.
lam	All the eigenvalues of the Bingham part. Not just the non zero ones.

**Details**

It calculate the three approximations given by Kume and Wood (2005) and it uses the Fisher-Bingham parametrization of that paper.

**Value**

A list including:

first oder	The first order approximation
second oder	The second order approximation
third oder	The third order approximation

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Kume Alfred and Wood Andrew T.A. (2005). Saddlepoint approximations for the Bingham and Fisher-Bingham normalizing constants. *Biometrika*, 92(2):465-476

**See Also**

[kent.logcon](#), [rfb](#), [kent.mle](#), [rbingham](#)

**Examples**

```
p <- 3 ; k <- 1
0.5 * p * log(2 * pi) - (p/2 - 1) * log(k) + log( besseli(k, p/2 - 1, expon.scaled = TRUE) ) + k
## normalising constant of the
## von Mises-Fisher distribution
fb.saddle( c(0, k, 0), c(0, 0, 0) ) ## saddlepoint approximation

## Normalising constant of the Kent distribution
fb.saddle( c(0, 10, 0), c(0, -2, 2) )
kent.logcon(10, 2)
```

---

Simulation from a Bingham distribution using any symmetric matrix A  
*Simulation from a Bingham distribution using any symmetric matrix A*

---

### Description

It simulates random values from a Bingham distribution with any given symmetric matrix.

### Usage

```
rbingham(n, A)
```

### Arguments

n	The sample size.
A	A symmetric matrix.

### Details

The eigenvalues are first calculated and then Chris Fallaize and Theo Kypraio's code (`f.rbing`) is used. The resulting simulated data are then right multiplied by the eigenvectors of the matrix A.

### Value

A matrix with the simulated data.

### Author(s)

Michail Tsagris

R implementation and documentation: Michail Tsagris <[mtsagris@uoc.gr](mailto:mtsagris@uoc.gr)> and Giorgos Athineou <[gioathineou@gmail.com](mailto:gioathineou@gmail.com)>

### References

Kent J.T., Ganeiber A.M. and Mardia K.V. (2013). A new method to simulate the Bingham and related distributions in directional data analysis with applications <http://arxiv.org/pdf/1310.8110v1.pdf>  
C.J. Fallaize and T. Kypraios (2014). Exact Bayesian Inference for the Bingham Distribution. Statistics and Computing (To appear). <http://arxiv.org/pdf/1401.2894v1.pdf>

### See Also

[f.rbing](#), [rfb](#), [rvmf](#), [rkent](#)

### Examples

```
A <- cov(iris[, 1:3])  
x <- rbingham(100, A)
```

---

Simulation from a Matrix Fisher distribution on  $SO(3)$

*Simulation from a Matrix Fisher distribution on  $SO(3)$*

---

### Description

It simulates random samples (rotation matrices) from a Matrix Fisher distribution with any given parameter matrix,  $F$  ( $3 \times 3$ ).

### Usage

```
rmatrixfisher(n, F)
```

### Arguments

n	the sample size.
F	An arbitrary $3 \times 3$ matrix.

### Details

Firstly corresponding Bingham parameter  $A$  is determined for a given Matrix Fisher parameter  $F$  using John Kent (2013) algorithm and then Bingham samples for parameter  $A$  are generated using `rbingham` code. Finally convert Bingham samples to Matrix Fisher samples according to the Kent (2013) transformation.

### Value

An array with simulated rotation matrices.

### Author(s)

Anamul Sajib & Chris Fallaize.

R implementation and documentation: Anamul Sajib <sajibstat@du.ac.bd> & Chris Fallaize.

### References

Kent J.T., Ganeiber A.M. and Mardia K.V. (2013). A new method to simulate the Bingham and related distributions in directional data analysis with applications. <http://arxiv.org/pdf/1310.8110v1.pdf>

### See Also

[matrixfisher.mle](#)

### Examples

```
F <- matrix( c(85, 11, 41, 78, 39, 60, 43, 64, 48), ncol = 3) / 10 ### An arbitrary F matrix
a <- rmatrixfisher(10, F)
```

---

Simulation of random values from a Bingham distribution  
*Simulating from a Bingham distribution*

---

### Description

It simulates from a Bingham distribution using the code suggested by Kent et al. (2013).

### Usage

```
f.rbing(n, lam, fast = FALSE)
```

### Arguments

n	Sample size.
lam	Eigenvalues of the diagonal symmetric matrix of the Bingham distribution.
fast	If you want a fast, efficient simulation set this to TRUE.

### Details

The user must have calculated the eigenvalues of the diagonal symmetric matrix of the Bingham distribution. The function accepts the  $q-1$  eigenvalues only. This means, that the user must have subtracted the lowest eigenvalue from the rest and give the non zero ones. The function uses rejection sampling and it was written by Chris Fallaize and Theo Kypraios (University of Nottingham) and kindly offered. Any questions on the code can be addressed to one of the two aforementioned people. It is slightly different than the one Ketn et al. (2013) suggests.

### Value

A list including:

x	The simulated data.
avtry	The estimate of M in the rejection sampling. The average number of simulated values before a value is accepted. If the argument fast is set to TRUE this information will not appear.

### Author(s)

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

### References

Kent J.T., Ganeiber A.M. and Mardia K.V. (2013). A new method to simulate the Bingham and related distributions in directional data analysis with applications. <http://arxiv.org/pdf/1310.8110v1.pdf>  
C.J. Fallaize and T. Kypraios (2014). Exact Bayesian Inference for the Bingham Distribution. Statistics and Computing (No volum assigned yet). <http://arxiv.org/pdf/1401.2894v1.pdf>

**See Also**

[rfb](#), [rvmf](#), [rbingham](#), [rkent](#), `link{rsop}`

**Examples**

```
x <- f.rbing( 100, c(1, 0.6, 0.1) )
x
```

---

Simulation of random values from a mixture of von Mises-Fisher distributions  
*Simulation of random values from a mixture of von Mises-Fisher distributions*

---

**Description**

The function simulates random values simulation from a given mixture of von Mises-Fisher distributions.

**Usage**

```
rmixvmf(n, prob, mu, k)
```

**Arguments**

<code>n</code>	The sample size.
<code>prob</code>	This is a vector with the mixing probability of each group.
<code>mu</code>	A matrix with the mean direction of each group.
<code>k</code>	A vector with the concentration parameter of each group.

**Details**

The function simulates random values simulation from a given mixture of von Mises-Fisher distributions using the `rvmf` function.

**Value**

A list including:

<code>id</code>	An indicator of the group of each simulated vector.
<code>x</code>	A matrix with the simulated data.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>



## References

Kurt Hornik and Bettina Grün (2014). movMF: An R Package for Fitting Mixtures of von Mises-Fisher Distributions <http://cran.r-project.org/web/packages/movMF/vignettes/movMF.pdf>

## See Also

[mixvmf.mle](#), [rvmf](#), [bic.mixvmf](#)

## Examples

```
k <- runif(4, 4, 20)
prob <- c(0.2, 0.4, 0.3, 0.1)
mu <- matrix(rnorm(16), ncol = 4)
mu <- mu / sqrt( rowSums(mu^2) )
x <- rmixvmf(200, prob, mu, k)$x
bic.mixvmf(x, 5)
```

---

Simulation of random values from a spherical Fisher-Bingham distribution  
*Simulation of random values from a spherical Fisher-Bingham distribution*

---

## Description

Simulation of random values from a spherical Fisher-Bingham distribution.

## Usage

```
rfb(n, k, m, A)
```

## Arguments

n	The sample size.
k	The concentration parameter (Fisher part). It has to be greater than 0.
m	The mean direction (Fisher part).
A	A symmetric matrix (Bingham part).

## Details

Random values from a spherical Fisher-Bingham distribution are generated. This function also included the option of simulating from a Kent distribution also.

## Value

A matrix with the simulated data.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Kent J.T., Ganeiber A.M. and Mardia K.V. (2013). A new method to simulate the Bingham and related distributions in directional data analysis with applications. <http://arxiv.org/pdf/1310.8110v1.pdf>

**See Also**

[rbingham](#), [rvmf](#), [rkent](#), [f.rbing](#)

**Examples**

```
k <- 15
mu <- rnorm(3)
mu <- mu / sqrt( sum(mu^2) )
A <- cov(iris[, 1:3])
x <- rfb(50, k, mu, A)
vmf.mle(x) ## fits a von Mises-Fisher distribution to the simulated data
## Next we simulate from a Kent distribution
A <- diag( c(-5, 0, 5) )
n <- 100
x <- rfb(n, k, mu, A) ## data follow a Kent distribution
kent.mle(x) ## fits a Kent distribution
vmf.mle(x) ## fits a von Mises-Fisher distribution
A <- diag( c(5, 0, -5) )
n <- 100
x <- rfb(n, k, mu, A) ## data follow a Kent distribution
kent.mle(x) ## fits a Kent distribution
vmf.mle(x) ## fits a von Mises-Fisher distribution
```

---

Simulation of random values from a spherical Kent distribution

*Simulation of random values from a spherical Kent distribution*

---

**Description**

Simulation of random values from a spherical Kent distribution.

**Usage**

```
rkent(n, k, m, b)
```

**Arguments**

n	The sample size.
k	The concentration parameter $\kappa$ . It has to be greater than 0.
m	The mean direction (Fisher part).
b	The ovalness parameter, $\beta$ .

**Details**

Random values from a Kent distribution on the sphere are generated. The function generates from a spherical Kent distribution using `rfb` with an arbitrary mean direction and then rotates the data to have the desired mean direction.

**Value**

A matrix with the simulated data.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Kent J.T., Ganeiber A.M. and Mardia K.V. (2013). A new method to simulate the Bingham and related distributions in directional data analysis with applications. <http://arxiv.org/pdf/1310.8110v1.pdf>

**See Also**

`rfb`, `rbingham`, `rvmf`, `f.rbing`

**Examples**

```
k <- 15
mu <- rnorm(3)
mu <- mu / sqrt( sum(mu^2) )
A <- diag( c(-5, 0, 5) )
x <- rfb(500, k, mu, A)
kent.mle(x)
y <- rkent(500, k, mu, A[3, 3])
kent.mle(y)
```

---

Simulation of random values from rotationally symmetric distributions

*Simulation of random values from rotationally symmetric distributions*

---

## Description

Simulation of random values from rotationally symmetric distributions. The data can be spherical or hyper-spherical.

## Usage

```
rvmf(n, mu, k)
riag(n, mu)
```

## Arguments

n	The sample size.
mu	A unit vector showing the mean direction for the von Mises-Fisher distribution. The mean vector of the Independent Angular Gaussian distribution. This does not have to be a unit vector.
k	The concentration parameter of the von Mises-Fisher distribution. If $k = 0$ , random values from the spherical uniform will be drawn.

## Details

The von Mises-Fisher uses the rejection sampling suggested by Andrew Wood (1994). For the Independent Angular Gaussian, values are generated from a multivariate normal distribution with the given mean vector and the identity matrix as the covariance matrix. Then each vector becomes a unit vector.

## Value

A matrix with the simulated data.

## Author(s)

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

## References

Wood A. T. A. (1994). Simulation of the von Mises Fisher distribution. *Communications in statistics-simulation and computation*, 23(1): 157–164.

Dhillon I. S. & Sra S. (2003). Modeling data using directional distributions. Technical Report TR-03-06, Department of Computer Sciences, The University of Texas at Austin. <http://citeseerx.ist.psu.edu/viewdoc/download?>

**See Also**

[vmf.mle](#), [iag.mle](#) [rfb](#), [racg](#), [rvonmises](#), [rmixvmf](#)

**Examples**

```
m <- rnorm(4)
m <- m/sqrt(sum(m^2))
x <- rvmf(100, m, 25)
m
vmf.mle(x)
```

---

Simulation of random values from some circular distributions

*Simulation of random values from some circular distributions*

---

**Description**

Simulation of random values from some circular distributions.

**Usage**

```
rvonmises(n, m, k, rads = TRUE)
rwrapcauchy(n, m, rho, rads = TRUE)
rspml(n, mu, rads = TRUE)
rcircbeta(n, m, a, b, rads = TRUE)
```

**Arguments**

n	The sample size.
m	The mean angle expressed in radians or degrees.
mu	The mean vector of the SPML in $R^2$ .
k	The concentration parameter of the von Mises distribution. If k is zero the sample will be generated from the uniform distribution over $(0, 2\pi)$ .
rho	The $\rho$ parameter of the Wrapped Cauchy distribution.
a	The $\alpha$ parameter of the beta distribution
b	The $\beta$ parameter of the beta distribution
rads	If the mean angle is expressed in radians, this should be TRUE and FALSE otherwise. The simulated data will be expressed in radians or degrees depending on what the mean angle is expressed.

**Details**

For the von Mises distribution, the mean direction is transformed to the Euclidean coordinates (i.e. unit vector) and then the `rvmf` function is employed. It uses a rejection sampling as suggested by Andrew Wood in 1994. I have mentioned the description of the algorithm as I found it in Dhillon and Sra in 2003. Finally, the data are transformed to radians or degrees.

For the wrapped Cauchy distribution the function generates Cauchy values  $x$  and then wraps around the circle  $x = x(\text{mod}2\pi)$ . For the circular beta the function has some extra steps (see Zheng Sun's master thesis).

**Value**

A vector with the simulated data.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Wood, A. T. (1994). Simulation of the von Mises Fisher distribution. *Communications in statistics-simulation and computation*, 23(1): 157-164.

Dhillon, I. S., & Sra, S. (2003). Modeling data using directional distributions. Technical Report TR-03-06, Department of Computer Sciences, The University of Texas at Austin. <http://citeseerx.ist.psu.edu/viewdoc/download?>

Zheng Sun (2006). Comparing measures of fit for circular distributions. Master thesis, University of Victoria. [https://dspace.library.uvic.ca/bitstream/handle/1828/2698/zhengsun\\_master\\_thesis.pdf;sequence=1](https://dspace.library.uvic.ca/bitstream/handle/1828/2698/zhengsun_master_thesis.pdf;sequence=1)

Lai, M. (1994). Some results in the statistical analysis of directional data. Master thesis, University of Hong Kong.

Presnell Brett, Morrison Scott P. and Littell Ramon C. (1998). Projected multivariate linear models for directional data. *Journal of the American Statistical Association*, 93(443): 1068-1077.

**See Also**

[circ.summary](#), [rvmf](#), [racg](#)

**Examples**

```
x <- rvonmises(100, 2, 25, rads = TRUE)
circ.summary(x, rads = TRUE)
```

---

Simulation of random values from the ESAG distribution  
*Simulation of random values from the ESAG distribution*

---

**Description**

Simulation of random values from the ESAG distribution.

**Usage**

```
resag(n, mu, gam)
```

**Arguments**

n	A number; how many vectors you want to generate.
mu	The mean vector the ESAG distribution, a vector in $R^3$ .
gam	The two gamma parameters of the ESAG distribution.

**Details**

A random sample from the ESAG distribution is generated. In case the gammas are zero, the sample is drawn from the Independent Angular Gaussian (or projected normal).

**Value**

An  $n \times 3$  matrix with the simulated unit vectors.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.  
Paine P.J., Preston S.P., Tsagris M. and Wood A.T.A. (2018). An Elliptically Symmetric Angular Gaussian Distribution. *Statistics and Computing*, 28(3):689–697.

**See Also**

[esag.mle](#), [desag](#), [spml.mle](#), [acg.mle](#), [circ.summary](#)

**Examples**

```
m <- colMeans( as.matrix( iris[,1:3] ) )  
y <- resag(1000, m, c(1, 0.5) )  
esag.mle(y)
```

---

Spherical and hyperspherical median

*Fast calculation of the spherical and hyperspherical median*

---

## Description

It calculates, very fast, the (hyper-)spherical median of a sample.

## Usage

```
mediandir(x)  
mediandir_2(x)
```

## Arguments

x                    The data, a numeric matrix with unit vectors.

## Details

The "mediandir" employs a fixed point iterative algorithm stemming from the first derivative (Cabrera and Watson, 1990) to find the median direction as described by Fisher (1985) and Fisher, Lewis and Embleton (1987). In the big samples this is much much faster than "mediandir\_2", since the search is based on iterations.

## Value

The median direction.

## Author(s)

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

## References

Fisher N. I. (1985). Spherical medians. *Journal of the Royal Statistical Society. Series B*, 47(2): 342-348.

Fisher N. I., Lewis T. and Embleton B. J. (1987). *Statistical analysis of spherical data*. Cambridge university press.

Cabrera J. and Watson G. S. (1990). On a spherical median related distribution. *Communications in Statistics-Theory and Methods*, 19(6): 1973-1986.

## See Also

[nsmedian](#), [vmf.mle](#), [kent.mle](#)



**Examples**

```

m <- rnorm(3)
m <- m / sqrt( sum(m^2) )
x <- rvmf(100, m, 10)
mediandir(x)
mediandir_2(x)
nsmedian(x)

```

---

Spherical regression using the projected normal or the von Mises-Fisher distribution  
*Spherical regression using the projected normal or the von Mises-Fisher distribution*

---

**Description**

Spherical regression using the projected normal or the von Mises-Fisher distribution.

**Usage**

```

iag.reg(y, x, con = TRUE, xnew = NULL, tol = 1e-06)
vmf.reg(y, x, con = TRUE, xnew = NULL, tol = 1e-06)

```

**Arguments**

<code>y</code>	A matrix with 3 columns containing the (unit vector) spherical data.
<code>x</code>	The predictor variable(s), they can be continuous, spherical, categorical or a mix of them.
<code>con</code>	Do you want the constant term in the regression?
<code>xnew</code>	If you have new data use it, otherwise leave it NULL.
<code>tol</code>	A tolerance value to decide when to stop the successive optimizations.

**Details**

The second parametrization of the projected normal and of the von Mises-Fisher regression (Paine et al., 2019) is applied. For more information see the paper by Paine et al. (2019).

**Value**

A list including:

<code>loglik</code>	The log-likelihood of the regression model.
<code>fit</code>	This is a measure of fit of the estimated values, defined as $\sum_{i=1}^n y_i^T \hat{y}_i$ . This appears if the argument "xnew" is NULL.
<code>beta</code>	The beta coefficients.
<code>seb</code>	The standard error of the beta coefficients.

<code>ki</code>	The norm of the fitted values. In the von Mises-Fisher regression this is the concentration parameter of each observation. In the projected normal this are the norms of the fitted values before being projected onto the sphere. This is returned if the argument "xnew" is NULL.
<code>est</code>	The fitted values of xnew if "xnew" is NULL. If it is not NULL, the fitted values for the "xnew" you supplied will be returned.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>

**References**

P. J. Paine, S. P. Preston, M. Tsagris and Andrew T. A. Wood (2019). Spherical regression models with general covariates and anisotropic errors. *Statistics and Computing* (to appear). <https://link.springer.com/content/pdf/10.1007/s11222-019-09888-1>

**See Also**

[esag.mle](#), [vmf.mle](#), [spml.reg](#)

**Examples**

```
y <- rvmf(150, rnorm(3), 5)
a1 <- iag.reg(y, iris[, 4])
a2 <- iag.reg(y, iris[, 4:5])

b1 <- vmf.reg(y, iris[, 4])
b2 <- vmf.reg(y, iris[, 4:5])
```

---

Spherical-spherical correlation  
*Spherical-spherical correlation*

---

**Description**

Correlation between two spherical variables.

**Usage**

```
spher.cor(x, y)
```

**Arguments**

<code>x</code>	A spherical variable. A matrix with three columns, each row is a unit vector.
<code>y</code>	A spherical variable. A matrix with three columns, each row is a unit vector.

**Details**

A very similar to the classical correlation is calculated. In addition, a hypothesis test for no correlation is performed. Note, that this is a squared correlation actually, so negative values will never be returned.

**Value**

A vector including:

R-squared	The value of the squared correlation.
p-value	The p-value of the no correlation hypothesis testing.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Kanti V. Mardia and Peter E. Jupp. Directional statistics, pg. 254–255.

**See Also**

[spher.reg](#), [vmf.mle](#), [circ.cor1](#), [circ.cor2](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 10)
y <- rvmf(100, rnorm(3), 10)
spher.cor(x, y)
```

---

Spherical-spherical regression  
*Spherical-Spherical regression*

---

**Description**

It performs regression when both the dependent and independent variables are spherical.

**Usage**

```
spher.reg(y, x, rads = FALSE)
```

**Arguments**

y	The dependent variable; a matrix with either two columns, latitude and longitude, either in radians or in degrees. Alternatively it is a matrix with three columns, unit vectors.
x	The dependent variable; a matrix with either two columns, latitude and longitude, either in radians or in degrees. Alternatively it is a matrix with three columns, unit vectors. The two matrices must agree in the scale and dimensions.
rads	If the data are expressed in latitude and longitude then it matter to know if they are in radians or degrees. If they are in radians, then this should be TRUE and FALSE otherwise. If the previous argument, euclidean, is TRUE, this one does not matter what its value is.

**Details**

Spherical regression as proposed by Chang (1986) is implemented. If the estimated rotation matrix has a determinant equal to -1, singular value decomposition is performed and the last unit vector of the second matrix is multiplied by -1.

**Value**

A list including:

A	The estimated rotation matrix.
fitted	The fitted values in Euclidean coordinates (unit vectors).

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Ted Chang (1986). Spherical Regression. *Annals of Statistics*, 14(3): 907–924.

**See Also**

[spher.cor](#), [spml.reg](#), [circ.cor1](#), [circ.cor2](#), [sphereplot](#)

**Examples**

```
mx <- rnorm(3)
mx <- mx/sqrt( sum(mx^2) )
my <- rnorm(3)
my <- my/sqrt( sum(my^2) )
x <- rvmf(100, mx, 15)
A <- rotation(mx, my)
y <- x %*% t(A)
```

```

mod <- spher.reg(y, x)
A
mod$A ## exact match, no noise
y <- x %*% t(A)
y <- y + rvmf(100, colMeans(y), 40)
mod <- spher.reg(y, x)
A
mod$A ## noise added, more realistic example

```

---

Summary statistics for circular data

*Summary statistics for circular data*

---

## Description

It produces a few summary measures for circular data.

## Usage

```
circ.summary(u, rads = FALSE, fast = FALSE, tol = 1e-07, plot = FALSE)
```

## Arguments

<code>u</code>	A vector with circular data.
<code>rads</code>	If the data are in rads, then this should be TRUE, otherwise FALSE.
<code>fast</code>	A boolean variable to do a faster implementation.
<code>tol</code>	The tolerance level to stop the Newton-Raphson algorithm for finding kappa.
<code>plot</code>	If you want to see the data plotted on a circle make this TRUE.

## Details

It returns the circular mean, mean resultant length, variance, standard deviation and concentration parameter. So, basically it returns the estimated values of the parameters of the von Mises distribution.

## Value

If `fast = FALSE` a list including all the following. If `fast = TRUE` less items are returned.

<code>mesos</code>	The circular mean direction.
<code>confint</code>	The 95% confidence interval for the circular mean direction.
<code>kappa</code>	The concentration parameter.
<code>MRL</code>	The mean resultant length.
<code>circvariance</code>	The circular variance.
<code>circstd</code>	The circular standard deviation.
<code>loglik</code>	The log-likelihood of the fitted von Mises distribution.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.

**See Also**

[spml.mle](#), [rvonmises](#), [vm.kde](#), [vmf.mle](#), [group.vm](#), [hcf.circaov](#)

**Examples**

```
x <- rvonmises(50, 2.5, 15, rads = TRUE)
circ.summary(x, rads = TRUE, plot = TRUE)
```

---

Summary statistics for grouped circular data  
*Summary statistics for grouped circular data*

---

**Description**

It produces a few summary measures for grouped circular data.

**Usage**

```
group.vm(group, fi, rads = FALSE)
```

**Arguments**

<code>group</code>	A matrix denoting the classes. Each row consists of two numbers, the lower and upper points of each class.
<code>fi</code>	The frequency of each class of data.
<code>rads</code>	If the data are in rads, then this should be TRUE, otherwise FALSE.

**Details**

It returns the circular mean, mean resultant length, variance, standard deviation and concentration parameter. So, basically it returns the estimated values of the parameters of the von Mises distribution. The mean resultant length though is group corrected.

**Value**

A list including:

mesos	The circular mean direction.
confint	The 95% confidence interval for the circular mean direction.
kappa	The concentration parameter.
MRL	The mean resultant length.
circvariance	The circular variance.
circstd	The circular standard deviation.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Pewsey Arthur, Markus Neuhauser and Graeme D. Ruxton (2013). Circular statistics in R. Oxford University Press.

Mardia K. V. and Jupp P. E. (2000). Directional statistics. Chicester: John Wiley & Sons.

**See Also**

[circ.summary](#), [rvonmises](#), [vm.kde](#)

**Examples**

```
x <- rvonmises(200, 3, 10)
a <- circ.summary(x, rads = TRUE, plot = FALSE)
group <- seq(min(x) - 0.1, max(x) + 0.1, length = 6)
y <- cut(x, breaks = group, length = 6)
group <- matrix( c( group[1], rep(group[2:5], each = 2), group[6]), ncol = 2, byrow = TRUE)
fi <- as.vector( table(y) )
b <- group.vm(group, fi, rads = TRUE)
a
b
```

---

Test for a given mean direction

*Test for a given mean direction*

---

### Description

A log-likelihood ratio test for testing whether the sample mean direction is equal to some predefined one.

### Usage

```
meandir.test(x, mu, B = 999)
```

### Arguments

x	A matrix with the data, unit vectors.
mu	A unit vector with the hypothesized mean direction.
B	A number either 1, so no bootstrap calibration is performed or more than 1, so bootstrap calibration is performed.

### Details

The log-likelihood ratio test is performed.

### Value

A list including:

mean.dir	The sample mean direction
pvalue	The p-value of the test.

### Author(s)

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>.

### References

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.

### See Also

[vmf.mle](#), [kent.mle](#), [rayleigh](#)



**Examples**

```
mu <- rnorm(5)
mu <- mu / sqrt( sum(mu^2) )
x <- rvmf(100, mu, 10)
meandir.test(x, mu, 1)
meandir.test(x, mu, 499)
```

---

Test for equality of concentration parameters for spherical data  
*Test for equality of concentration parameters for spherical data*

---

**Description**

This tests the equality of concentration parameters for spherical data only.

**Usage**

```
spherconc.test(x, ina)
```

**Arguments**

x	A matrix with the data in Euclidean coordinates, i.e. unit vectors
ina	A variable indicating the groupings of the observations.

**Details**

The test is designed for spherical data only.

**Value**

A list including:

mess	A message stating the value of the mean resultant and which test statistic was used, U1, U2 or U3.
res	A vector containing the test statistic and its p-value.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Kanti V. Mardia and Peter E. Jupp. Directional statistics, pg. 226-227.

**See Also**

[het.aov](#), [lr.aov](#), [embed.aov](#), [hcf.aov](#), [conc.test](#), [sphereplot](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 15)
ina <- rep(1:4, each = 25)
spherconc.test(x, ina)
```

---

Test of equality of the concentration parameters for circular data

*A test for testing the equality of the concentration parameter among g samples, where  $g \geq 2$  for circular data*

---

**Description**

A test for testing the equality of the concentration parameter among g samples, where  $g \geq 2$  for circular data.

**Usage**

```
conc.test(u, ina, rads = FALSE)
```

**Arguments**

u	A numeric vector containing the values of all samples.
ina	A numerical variable or factor indicating the groups of each value.
rads	If the data are in radians this should be TRUE and FALSE otherwise.

**Details**

This test works for circular data.

**Value**

A list including:

mess	A message informing the use of the test statistic used.
res	A numeric vector containing the value of the test statistic and its associated p-value.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Mardia, K. V. and Jupp, P. E. (2000). Directional statistics. Chichester: John Wiley & Sons.

**See Also**

[embed.circaov](#), [hcf.circaov](#), [lr.circaov](#), [het.circaov](#)

**Examples**

```
x <- rvonmises(100, 2.4, 15)
ina <- rep(1:4,each = 25)
conc.test(x, ina, rads = TRUE)
```

---

The k-nearest neighbours using the cosinus distance

*The k-nearest neighbours using the cosinus distance*

---

**Description**

The k-nearest neighbours using the cosinus distance.

**Usage**

```
cosnn(xnew, x, k = 5, index = FALSE, rann = FALSE)
```

**Arguments**

xnew	The new data whose k-nearest neighbours are to be found.
x	The data, a numeric matrix with unit vectors.
k	The number of nearest neighbours, set to 5 by default. It can also be a vector with many values.
index	If you want the indices of the closest observations set this equal to TRUE.
rann	If you have large scale datasets and want a faster k-NN search, you can use kd-trees implemented in the R package "RANN". In this case you must set this argument equal to TRUE.

**Details**

The shortest distances or the indices of the k-nearest neighbours using the cosinus distance are returned.

**Value**

A matrix with the shortest distance of each xnew from x, if index is FALSE, or the indices of the nearest neighbours of each xnew from x, if index is TRUE.

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <[mtsagris@uoc.gr](mailto:mtsagris@uoc.gr)>.

**References**

Tsagris M. and Alenazi A. (2019). Comparison of discriminant analysis methods on the sphere. *Communications in Statistics: Case Studies, Data Analysis and Applications*, 5(4), 467–491.

**See Also**

[dirknn](#), [dirknn.tune](#)

**Examples**

```
xnew <- rvmf(10, rnorm(3), 5)
x <- rvmf(50, rnorm(3), 5)
a <- cosnn(xnew, x, k = 5)
b <- cosnn(xnew, x, k = 5, index = TRUE)
```

---

Transform unit vectors to angular data

*Transform unit vectors to angular data*

---

**Description**

Transform unit vectors to angular data.

**Usage**

```
etoa(x)
```

**Arguments**

`x` A numerical matrix with directional data, i.e. unit vectors.

**Details**

from the Euclidean coordinates the data are mapped to angles, expressed in rads.

**Value**

A list including:

`mu` A matrix with angles. The number of columns is one less than that of the original matrix.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.

**References**

[https://en.wikipedia.org/wiki/N-sphere#Spherical\\_coordinates](https://en.wikipedia.org/wiki/N-sphere#Spherical_coordinates)

**See Also**

[vmb.pred](#), [weibull.nb](#)

**Examples**

```
x <- rvmf(10, rnorm(3), 5)
y <- etoa(x)
```

---

Tuning of the bandwidth parameter in the von Mises kernel

*Tuning of the bandwidth parameter in the von Mises kernel for circular data*

---

**Description**

Tuning of the bandwidth parameter in the von Mises kernel for circular data. Cross validation is used.

**Usage**

```
vmkde.tune(u, low = 0.1, up = 1, rads = TRUE)
```

**Arguments**

u	The data, a numerical vector.
low	The lower value of h to search.
up	The upper value of h to search.
rads	If the data are in radians this should be TRUE and FALSE otherwise.

**Details**

Tuning of the bandwidth parameter in the von Mises kernel for circular data via cross validation. The procedure is fast because an optimiser is used.

**Value**

A vector including two elements:

Optimal h	The best H found.
cv	The value of the maximised pseudo-likelihood.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Taylor C. C. (2008). Automatic bandwidth selection for circular density estimation. *Computational Statistics & Data Analysis*, 52(7), 3493–3500.

Wand M. P., & Jones M. C. (1994). *Kernel smoothing*. CrC Press.

**See Also**

[vm.kde](#), [vmfkde.tune](#), [vmf.kde](#)

**Examples**

```
u <- rvonmises(100, 2.4, 10, rads = TRUE)
vmkde.tune(u)
```

---

Tuning of the bandwidth parameter in the von Mises-Fisher kernel  
*Tuning of the bandwidth parameter in the von Mises-Fisher kernel for  
(hyper-)spherical data*

---

**Description**

Tuning of the bandwidth parameter in the von Mises-Fisher kernel for (hyper-)spherical data with cross validation.

**Usage**

```
vmfkde.tune(x, low = 0.1, up = 1)
```

**Arguments**

x	A matrix with the data in Euclidean coordinates, i.e. unit vectors.
low	The lower value of the bandwidth to search.
up	The upper value of the bandwidth to search.

**Details**

Fast tuning of the bandwidth parameter in the von Mises-Fisher kernel for (hyper-)spherical data via cross validation.

**Value**

A vector including two elements:

Optimal h	The best H found.
cv	The value of the maximised pseudo-likelihood.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Garcia Portugues E. (2013). Exact risk improvement of bandwidth selectors for kernel density estimation with directional data. *Electronic Journal of Statistics*, 7, 1655–1685.

Wand M. P., and Jones M. C. (1994). *Kernel smoothing*. Crc Press.

**See Also**

[vmf.kde](#), [vmf.kerncontour](#), [vm.kde](#), [vmkde.tune](#)

**Examples**

```
x <- rvmf(100, rnorm(3), 15)
vmfkde.tune(x)
```

---

Tuning of the  $k$ -NN algorithm using the arc cosinus distance  
 *$k$ -NN algorithm using the arc cosinus distance. Tuning the  $k$  neighbours*

---

**Description**

It estimates the percentage of correct classification via an  $m$ -fold cross validation.

**Usage**

```
dirknn.tune(ina, x, k = 2:10, mesos = TRUE, nfolds = 10, folds = NULL,  
parallel = FALSE, stratified = TRUE, seed = NULL, rann = FALSE)
```

**Arguments**

x	The data, a numeric matrix with unit vectors.
ina	A variable indicating the groups of the data x.
nfolds	How many folds to create?
k	A vector with the number of nearest neighbours to consider.
mesos	A boolean variable used only in the case of the non standard algorithm (type="NS"). Should the average of the distances be calculated (TRUE) or not (FALSE)? If it is FALSE, the harmonic mean is calculated.
folds	Do you already have a list with the folds? If not, leave this NULL.
parallel	If you want the standard -NN algorithm to take place in parallel set this equal to TRUE.
stratified	Should the folds be created in a stratified way? i.e. keeping the distribution of the groups similar through all folds?
seed	If seed is TRUE, the results will always be the same.
rann	If you have large scale datasets and want a faster k-NN search, you can use kd-trees implemented in the R package "RANN". In this case you must set this argument equal to TRUE.

**Details**

The standard algorithm is to keep the k nearest observations and see the groups of these observations. The new observation is allocated to the most frequent seen group. The non standard algorithm is to calculate the classical mean or the harmonic mean of the k nearest observations for each group. The new observation is allocated to the group with the smallest mean distance.

We have made an efficient (not very much efficient though) memory allocation. Even if you have hundreds of thousands of observations, the computer will not clush, it will only take longer. Instead of calculate the distance matrix once in the beginning we calcualte the distances of the out-of-sample observations from the rest. If we calculated the distance matrix in the beginning, once, the resulting matrix could have dimensions thousands by thousands. This would not fit into the memory. If you have a few hundres of observations, the runtime is about the same (maybe less, maybe more) as calculating the distance matrix in the first place.

**Value**

A list including:

per	The average percent of correct classification across the neighbours.
percent	The bias corrected percent of correct classification.
runtime	The run time of the algorithm. A numeric vector. The first element is the user time, the second element is the system time and the third element is the elapsed time.

**Author(s)**

Michail Tsagris R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr>.



**References**

Tsagris M. and Alenazi A. (2019). Comparison of discriminant analysis methods on the sphere. *Communications in Statistics: Case Studies, Data Analysis and Applications*, 5(4), 467–491.

**See Also**

[dirknn](#), [vmf.da](#), [mixvmf.mle](#)

**Examples**

```
k <- runif(4, 4, 20)
prob <- c(0.2, 0.4, 0.3, 0.1)
mu <- matrix(rnorm(16), ncol = 4)
mu <- mu / sqrt( rowSums(mu^2) )
da <- rmixvmf(200, prob, mu, k)
x <- da$x
ina <- da$id
dirknn.tune(ina, x, k = 2:6, nfolds = 5, mesos = TRUE)
dirknn.tune(ina, x, k = 2:6, nfolds = 10, mesos = TRUE)
```

---

Tuning of the k-NN regression

*Tuning of the k-NN regression with Euclidean or (hyper-)spherical response and or predictor variables*

---

**Description**

Tuning of the k-NN regression with Euclidean or (hyper-)spherical response and or predictor variables. It estimates the percentage of correct classification via an m-fold cross validation. The bias is estimated as well using the algorithm suggested by Tibshirani and Tibshirani (2009) and is subtracted.

**Usage**

```
knnreg.tune(y, x, nfolds = 10, A = 10, ncores = 1, res = "eucl",
  estim = "arithmetic", folds = NULL, seed = NULL, graph = FALSE)
```

**Arguments**

y	The currently available data, the response variables values. A matrix with either euclidean (univariate or multivariate) or (hyper-)spherical data. If you have a circular response, say u, transform it to a unit vector via (cos(u), sin(u)).
x	The currently available data, the predictor variables values. A matrix with either euclidean (univariate or multivariate) or (hyper-)spherical data. If you have a circular response, say u, transform it to a unit vector via (cos(u), sin(u)).
nfolds	How many folds to create?

A	The maximum number of nearest neighbours, set to 5 by default, starting from the 1 nearest neighbor.
ncores	How many cores to use. This is taken into account only when the predictor variables are spherical.
res	The type of the response variable. If it is Euclidean, set this argument equal to "res". If it is a unit vector set it to res="spher".
estim	Once the k observations with the smallest distance are discovered, what should the prediction be? The arithmetic average of the corresponding y values be used estim="arithmetic" or their harmonic average estim="harmonic".
folds	Do you already have a list with the folds? If not, leave this NULL.
seed	You can specify your own seed number here or leave it NULL.
graph	If this is TRUE a graph with the results will appear.

### Details

Tuning of the k-NN regression with Euclidean or (hyper-)spherical response and or predictor variables. It estimates the percentage of correct classification via an m-fold cross validation. The bias is estimated as well using the algorithm suggested by Tibshirani and Tibshirani (2009) and is subtracted. The sum of squares of prediction is used in the case of Euclidean responses. In the case of spherical responses the  $\sum \hat{y}_i^T y_i$  is calculated.

### Value

A list including:

crit	The value of the criterion to minimise/maximise for all values of the nearest neighbours.
best_k	The best value of the nearest neighbours.
performance	The bias corrected optimal value of the criterion, along with the estimated bias. For the case of Euclidean response this will be higher than the crit and for the case of spherical responses it will be lower than crit.
runtime	The run time of the algorithm. A numeric vector. The first element is the user time, the second element is the system time and the third element is the elapsed time.

### Author(s)

Michail Tsagris R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

### See Also

[knn.reg](#), [spher.reg](#), [dirknn.tune](#)

**Examples**

```

y <- iris[, 1]
x <- iris[, 2:4]
x <- x/ sqrt( rowSums(x^2) ) ## Euclidean response and spherical predictors
knnreg.tune(y, x, A = 5, res = "eucl", estim = "arithmetic")

y <- iris[, 1:3]
y <- y/ sqrt( rowSums(y^2) ) ## Spherical response and Euclidean predictor
x <- iris[, 2]
knnreg.tune(y, x, A = 5, res = "spher", estim = "arithmetic")

```

---

Uniformity test for circular data

*Uniformity tests for circular data.*

---

**Description**

Hypothesis tests of uniformity for circular data.

**Usage**

```
kuiper(u, rads = FALSE, R = 1)
```

```
watson(u, rads = FALSE, R = 1)
```

**Arguments**

u	A numeric vector containing the circular data, which can be expressed in degrees or radians.
rads	A boolean variable. If the data are in radians, put this TRUE. If the data are expressed in degrees make this FALSE.
R	If R = 1 the asymptotic p-value will be calculated. If R is greater than 1 the bootstrap p-value is returned.

**Details**

The high concentration (hcf.circaov), log-likelihood ratio (lr.circaov), embedding approach (embed.circaov) or the non equal concentration parameters approach (het.circaov) is used.

**Value**

A vector including:

Test	The value of the test statistic.
p-value	The p-value of the test (bootstrap or asymptotic depends upon the value of the argument R).

**Author(s)**

Michail Tsagris.

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>.

**References**

Jammalamadaka, S. Rao and SenGupta, A. (2001). Topics in Circular Statistics, pg. 153-55 (Kuiper's test) & 156-157 (Watson's test).

**See Also**

[rayleigh](#), [vmf.mle](#), [rvonmises](#)

**Examples**

```
x <- rvonmises(n = 40, m = 2, k = 10)
kuiper(x, rads = TRUE)
watson(x, rads = TRUE)
x <- rvonmises(40, m = 2, k = 0)
kuiper(x, rads = TRUE)
watson(x, rads = TRUE)
```

---

von Mises kernel density estimation

*Kernel density estimation of circular data with a von Mises kernel*

---

**Description**

Kernel density estimation of circular data with a von Mises kernel.

**Usage**

```
vm.kde(u, h, thumb = "none", rads = TRUE)
```

**Arguments**

u	A numeric vector containing the data.
h	The bandwidth.
thumb	It can be either "none", so the bandwidth the user has set will be used, "tay" for the method of Taylor (2008) or "rot" for the method of Garcia-Portugues (2013).
rads	If the data are in radians, this should be TRUE and FALSE otherwise.

**Details**

The user has the option to use a bandwidth he/she has found in some way (cross-validation) or estimate it as Taylor (2008) or Garcia-Portugues (2013).

**Value**

A list including:

- |   |  |
|---|--|
| h | The bandwidth. If the user chose one of "tay" or "rot" the estimated bandwidth will be returned. |
| f | The kernel density estimate at the observed points.  |

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Taylor, C. C. (2008). Automatic bandwidth selection for circular density estimation. *Computational Statistics & Data Analysis*, 52(7): 3493-3500.

Garcia Portugues, E. (2013). Exact risk improvement of bandwidth selectors for kernel density estimation with directional data. *Electronic Journal of Statistics*, 7, 1655-1685.

**See Also**

[vmkde.tune](#), [vmfkde.tune](#), [vmf.kde](#)

**Examples**

```
x <- rvonmises(100, 2.4, 10, rads = TRUE)
hist(x, freq = FALSE)
f1 <- vm.kde(x, h = 0.1, thumb = "rot", rads = TRUE)$f
f2 <- vm.kde(x, h = 0.1, thumb = "tay", rads = TRUE)$f
h <- vmkde.tune(x)[1]
f3 <- vm.kde(x, h = h, thumb = "none", rads = TRUE)$f
points(x, f1, col = 1)
points(x, f2, col = 2)
points(x, f3, col = 3)
```

---

von Mises-Fisher kernel density estimation for (hyper-)spherical data  
*Kernel density estimation for (hyper-)spherical data using a von Mises-Fisher kernel*

---

**Description**

A von Mises-Fisher kernel is used for the non parametric density estimation.

**Usage**

```
vmf.kde(x, h, thumb = "none")
```

**Arguments**

x	A matrix with unit vectors, i.e. the data being expressed in Euclidean coordinates.
h	The bandwidth to be used.
thumb	If this is "none", the given bandwidth is used. If it is "rot" the rule of thumb suggested by Garcia-Portugues (2013) is used.

**Details**

A von Mises-Fisher kernel is used for the non parametric density estimation.

**Value**

A list including:

h	The bandwidth used.
f	A vector with the kernel density estimate calculated for each of the data points.

**Author(s)**

Michail Tsagris

R implementation and documentation: Michail Tsagris <mtsagris@uoc.gr> and Giorgos Athineou <gioathineou@gmail.com>

**References**

Garcia Portugues, E. (2013). Exact risk improvement of bandwidth selectors for kernel density estimation with directional data. *Electronic Journal of Statistics*, 7, 1655-1685.

**See Also**

[vmfkde.tune](#), [vm.kde](#), [vmf.mle](#), [vmkde.tune](#)

**Examples**

```
x <- rvmf(100, rnorm(5), 15)
h <- vmfkde.tune(x)[1]
f1 <- vmf.kde(x, h = h, thumb = "none")
f2 <- vmf.kde(x, h = h, thumb = "rot")
f1$h ; f2$h
```

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