

Advanced case study options

GMSE: an R package for generalised management strategy evaluation (Supporting Information 4)

A. Bradley Duthie^{1,3}, Jeremy J. Cusack¹, Isabel L. Jones¹, Jeroen Minderman¹, Erlend B. Nilsen², Rocío A. Pozo¹, O. Sarobidy Rakotonarivo¹, Bram Van Moorter², and Nils Bunnefeld¹

[1] *Biological and Environmental Sciences, University of Stirling, Stirling, UK* [2] *Norwegian Institute for Nature Research, Trondheim, Norway* [3] *alexander.duthie@stir.ac.uk*

Fine-tuning simulation conditions using `gmse_apply`

Here we demonstrate how simulations in GMSE can be more fine-tuned to specific empirical situations through the use of `gmse_apply`. To do this, we use the same scenario described in [SI3](#); we first recreate the basic scenario run in `gmse` using `gmse_apply`, and then build in additional modelling details including (1) [custom placement of user land](#), (2) [parameterisation of individual user budgets](#), and (3) [density-dependent movement of resources](#). We emphasise that these simulations are provided only to demonstrate the use of GMSE, and specifically to show the flexibility of the `gmse_apply` function, not to accurately recreate the dynamics of a specific system or make management recommendations.

We reconsider the case of a protected waterfowl population that exploits agricultural land (e.g., [Fox and Madsen, 2017](#); [Mason et al., 2017](#); [Tulloch et al., 2017](#); [Cusack et al., 2018](#)). The manager attempts to keep the waterfowl at a target abundance, while users (farmers) attempt to maximise agricultural yield on the land that they own. We again parameterise our model using demographic information from the Taiga Bean Goose (*Anser fabalis fabalis*), as reported by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#). Relevant parameter values are listed in the table below.

Table 1: GMSE simulation parameter values inspired by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#)

Parameter	Value	Description
<code>remove_pr</code>	0.122	Goose density-independent mortality probability
<code>lambda</code>	0.275	Expected offspring production per time step
<code>res_death_K</code>	93870	Goose carrying capacity (on adult mortality)
<code>RESOURCE_ini</code>	35000	Initial goose abundance
<code>manage_target</code>	70000	Manager’s target goose abundance
<code>res_death_type</code>	3	Mortality (density and density-independent sources)

Additionally, we continue to use the following values for consistency, except in the case of `stakeholders`, where we reduce the number of farmers to `stakeholders = 8`. This is done to for two reasons. First, it speeds up simulations for the purpose of demonstration; second, it makes the presentation of our custom landscape ownership easier to visualise (see below).

Table 2: Non-default GMSE parameter values chosen by authors

Parameter	Value	Description
<code>manager_budget</code>	10000	Manager’s budget for setting policy options
<code>user_budget</code>	10000	Users’ budgets for actions
<code>public_land</code>	0.4	Proportion of the landscape that is public

Parameter	Value	Description
stakeholders	8	Number of stakeholders
land_ownership	TRUE	Users own landscape cells
res_consume	0.02	Landscape cell output consumed by a resource
observe_type	3	Observation model type (survey)
agent_view	1	Cells managers can see when conducting a survey

All other values are set to GMSE defaults, except where specifically noted otherwise.

Re-creating gmse simulations using gmse_apply

We now recreate the simulations in [SI3](#), which were run using the `gmse` function, in `gmse_apply`. Doing so requires us to first initialise simulations using one call of `gmse_apply`, then loop through multiple time steps that again call `gmse_apply`; results of interest are recorded in a data frame (`sim_sum_1`). Following the protocol introduced in [SI2](#), we can call the initialising simulation `sim_old`, and use the code below to read in the relevant parameter values.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 100000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200);
```

Note that the argument `get_res = "Full"` causes `sim_old` to retain all of the relevant data structures for simulating a new time step and recording simulation results. This includes the key simulation output, which is located in `sim_old$basic_output`, which is printed below.

```
## $resource_results
## [1] 34096
##
## $observation_results
## [1] 34096
##
## $manager_results
##      resource_type scaring culling castration feeding help_offspring
## policy_1          1      NA     533          NA      NA             NA
##
## $user_results
##      resource_type scaring culling castration feeding help_offspring
## Manager          1      NA      0          NA      NA             NA
## user_1            1      NA    182          NA      NA             NA
## user_2            1      NA    183          NA      NA             NA
## user_3            1      NA    183          NA      NA             NA
## user_4            1      NA    181          NA      NA             NA
## user_5            1      NA    181          NA      NA             NA
## user_6            1      NA    182          NA      NA             NA
## user_7            1      NA    182          NA      NA             NA
## user_8            1      NA    183          NA      NA             NA
##      tend_crops kill_crops
```

```
## Manager      NA      NA
## user_1       NA      NA
## user_2       NA      NA
## user_3       NA      NA
## user_4       NA      NA
## user_5       NA      NA
## user_6       NA      NA
## user_7       NA      NA
## user_8       NA      NA
```

We can then loop over 30 time steps to recreate the simulations from [SI3](#). In these simulations, we are specifically interested in the resource and observation outputs, as well as the manager policy and user actions for culling, which we record below in the data frame `sim_sum_1`. The inclusion of the argument `old_list` tells `gmse_apply` to use parameters and values from the list `sim_old` in the new time step.

```
sim_sum_1 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_1[time_step, 1] <- time_step;
  sim_sum_1[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_1[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_1[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_1[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_1) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
                        "Cull_count");
print(sim_sum_1);
```

```
##      Time Pop_size Pop_est Cull_cost Cull_count
## [1,]  1    32706  32706     863      908
## [2,]  2    32158  32158     938      839
## [3,]  3    32502  32502     954      825
## [4,]  4    33046  33046     983      801
## [5,]  5    37070  37070    1002      785
## [6,]  6    38232  38232     996      790
## [7,]  7    39550  39550     996      788
## [8,]  8    41106  41106     991      793
## [9,]  9    42871  42871     991      793
## [10,] 10    44990  44990    1000      786
## [11,] 11    47284  47284    1003      785
## [12,] 12    49774  49774     988      794
## [13,] 13    52181  52181    1008      778
## [14,] 14    54806  54806    1000      786
## [15,] 15    57555  57555    1006      781
## [16,] 16    60730  60730     991      793
## [17,] 17    64258  64258     997      787
## [18,] 18    67676  67676    1010      778
## [19,] 19    71346  71346      10      29284
## [20,] 20    44970  44970    1010      778
## [21,] 21    47016  47016     994      793
## [22,] 22    49373  49373    1004      784
## [23,] 23    52070  52070     992      793
## [24,] 24    54577  54577    1005      783
## [25,] 25    57388  57388     994      793
```

```
## [26,] 26 60843 60843 1007 778
## [27,] 27 64116 64116 996 788
## [28,] 28 67559 67559 993 793
## [29,] 29 71356 71356 10 29112
## [30,] 30 45095 45095 1010 778
```

The above output from `sim_sum_1` shows the data frame that holds the information we were interested in pulling out of our simulation results. All of this information was available under the list element `sim_new$basic_output`, but other list elements of `sim_new` might also be useful to record. It is important to remember that this example of `gmse_apply` is using the default resource, observation, manager, and user sub-models. Custom sub-models could produce different outputs in `sim_new` (see [SI2](#) for examples). For default sub-models, there are some list elements that might be especially useful. These elements can potentially be edited *within the above loop* to dynamically adjust simulations. For more explanation of built-in GMSE data arrays, see [SI7](#).

- `sim_new$resource_array`: A table holding all information on resources. Rows correspond to discrete resources, and columns correspond to resource properties: (1) ID, (2-4) types (not currently in use), (5) x-location, (6) y-location, (7) movement parameter, (8) time, (9) density independent mortality parameter (`remove_pr`), (10) reproduction parameter (`lambda`), (11) offspring number, (12) age, (13-14) observation columns, (15) consumption rate (`res_consume`), and (16-20) recorded experiences of user actions (e.g., was the resource culled or scared?).
- `sim_new$AGENTS`: A table holding basic information on agents (manager and users). Rows correspond to a unique agent, and columns correspond to agent properties: (1) ID, (2) type (0 for the manager, 1 for users), (3-4) additional type options not currently in use, (5-6), x and y locations (usually ignored), (7) movement parameter (usually ignored), (8) time, (9) agent's viewing ability in cells (`agent_view`), (10) error parameter, (11-12) values for holding marks and tallies of resources, (13-15) values for holding observations, (16) yield from landscape cells, (17) budget (`manager_budget` and `user_budget`).
- `sim_new$observation_vector`: Estimate of total resource number from the observation model (`observation_array` also holds this information in a different way depending on `observe_type`)
- `sim_new$LAND`: The landscape on which interactions occur, which is stored as a 3D array with `land_dim_1` rows, `land_dim_2` columns, and 3 layers. Layer 1 (`sim_new$LAND[,1]`) is not currently used in default sub-models, but could be used to store values that affect resources and agents. Layer 2 (`sim_new$LAND[,2]`) stores crop yield from a cell, and layer 3 (`sim_new$LAND[,3]`) stores the owner of the cell (value corresponds to the agent's ID).
- `sim_new$manage_vector`: The cost of each action as set by the manager. For even more fine-tuning, individual costs for the actions of each agent can be set for each user in `sim_new$manager_array`.
- `sim_new$user_vector`: The total number of actions performed by each user. A more detailed breakdown of actions by individual users is held in `sim_new$user_array`.

Next, we show how to adjust the landscape to manually set land ownership in `gmse_apply`.

1. Custom placement of user land

By default, all farmers in GMSE are allocated the same number of landscape cells, which are simply placed in order of the farmer's ID. Public land is produced by placing landscape cells that are technically owned by the manager, and therefore have landscape cell values of 1. The image below shows this landscape for the eight farmers from `sim_old`.

```
image(x = sim_old$LAND[,3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```

We can change the ownership of cells by manipulating `sim_old$LAND[,3]`. First we initialise a new `sim_old` below.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_d4eath_K = 93870, RESOURCE_ini = 35000,
```



Figure 1: Default position of land ownership by farmers.

```

manage_target = 70000, res_death_type = 3,
manager_budget = 10000, user_budget = 10000,
public_land = 0.4, stakeholders = 8, res_consume = 0.02,
res_birth_K = 200000, land_ownership = TRUE,
observe_type = 3, agent_view = 1, converge_crit = 0.01,
ga_mingen = 200);

```

Because we have not specified landscape dimensions in the above, the landscape reverts to the default size of 100 by 100 cells. We can then manually assign landscape cells to the eight farmers, whose IDs range from 2-9 (ID value 1 is the manager). Below we do this to make eight different sized farms.

```

sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1; # Public land
image(x = sim_old$LAND[, ,3], col = topo.colors(9), xaxt = "n", yaxt = "n");

```

The above image shows the modified landscape stored in `sim_old`, which can now be incorporated into simulations using `gmse_apply`. We can think of all the plots on the left side of the landscape as farms of various sizes, while the blue area of the landscape on the right is public land.

2. Parameterisation of individual user budgets

Perhaps we want to assume that farmers have different budgets, which are correlated in some way to the number of landscape cells that they own. Custom user budgets can be set by manipulating `sim_old$AGENTS`, the last column of which (column 17) holds the budget for each user. Agent IDs (as stored on the landscape above) correspond to rows of `sim_old$AGENTS`, so individual budgets can be directly input as desired. We can do this manually (e.g., `sim_old$AGENTS[2, 17] <- 4000`), or, alternatively, if farmer budget positively

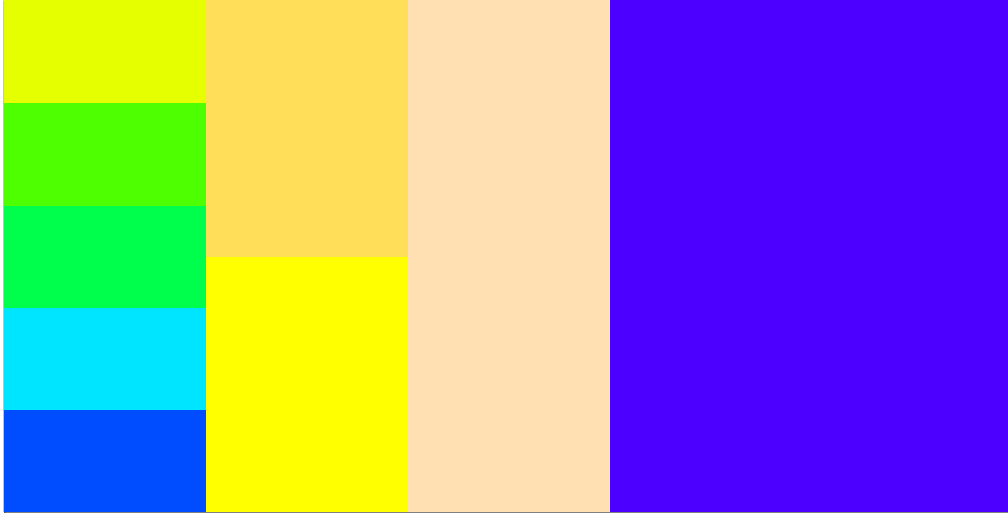


Figure 2: Land ownership by farmers as customised in `gmse_apply`.

correlates to landscape owned, we can use a loop to input values as below.

```
for(ID in 2:9){
  cells_owned      <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}
```

The number of cells owned by the manager (1) and each farmer (2-8) is therefore listed in the table below.

ID	1	2	3	4	5	6	7	8	9
Budget	10000	4000	4000	4000	4000	4000	10000	10000	20000

As with `sim_old$LAND` values, changes to `sim_old$AGENTS` will be retained in simulations looped through `gmse_apply`.

3. Density-dependent movement of resources

Lastly, we consider a more nuanced change to simulations, in which the rules for movement of resources are modified to account for density-dependence. Assume that geese tend to avoid aggregating, such that if a goose is located on the same cell as too many other geese, then it will move at the start of a time step. Programming this movement rule can be accomplished by creating a new function to apply to the resource data array `sim_old$resource_array`. Below, a custom function is defined that causes a goose to move up to 5 cells in any direction if it finds itself on a cell with more than 10 other geese. As with default GMSE simulations, movement is based on a torus landscape (where no landscape edge exists, so that if resources move off of one side of the landscape they appear on the opposite side).

```

avoid_aggregation <- function(goose_table, land_dim_1 = 100, land_dim_2 = 100){
  goose_number <- dim(goose_table)[1] # How many geese are there?
  for(goose in 1:goose_number){ # Loop through all rows of geese
    x_loc <- goose_table[goose, 5];
    y_loc <- goose_table[goose, 6];
    shared <- sum(goose_table[,5] == x_loc & goose_table[,6] == y_loc);
    if(shared > 10){
      new_x <- x_loc + sample(x = -5:5, size = 1);
      new_y <- y_loc + sample(x = -5:5, size = 1);
      if(new_x < 0){ # The 'if' statements below apply the torus
        new_x <- land_dim_1 + new_x;
      }
      if(new_x >= land_dim_1){
        new_x <- new_x - land_dim_1;
      }
      if(new_y < 0){
        new_y <- land_dim_2 + new_x;
      }
      if(new_y >= land_dim_2){
        new_y <- new_y - land_dim_2;
      }
      goose_table[goose, 5] <- new_x;
      goose_table[goose, 6] <- new_y;
    }
  }
  return(goose_table);
}

```

With the above function written, we can apply the new movement rule along with our [custom farm placement](#) and [custom farmer budgets](#) to the simulation of goose population dynamics.

Simulation with custom farms, budgets, and goose movement

Below shows an example of `gmse_apply` with custom landscapes, farmer budgets, and density-dependent goose movement rules.

```

# First initialise a simulation
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 10000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200, res_move_type = 0);

# By setting `res_move_type = 0`, no resource movement will occur in gmse_apply
# Adjust the landscape ownership below
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;

```

```

sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1;
# Change the budgets of each farmer based on the land they own
for(ID in 2:9){
  cells_owned          <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}
# Begin simulating time steps for the system
sim_sum_2 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  # Apply the new movement rules at the beginning of the loop
  sim_old$resource_array <- avoid_aggregation(sim_old$resource_array);
  # Next, move on to simulate (old_list remembers that res_move_type = 0)
  sim_new                <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_2[time_step, 1] <- time_step;
  sim_sum_2[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_2[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_2[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_2[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old                 <- sim_new;
}
colnames(sim_sum_2) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
                        "Cull_count");
print(sim_sum_2);

```

```

##      Time Pop_size Pop_est Cull_cost Cull_count
## [1,]    1  33800  33800     771         74
## [2,]    2  34013  34013     882         64
## [3,]    3  34955  34955     933         61
## [4,]    4  36476  36476     979         60
## [5,]    5  41856  41856     984         60
## [6,]    6  43899  43899     996         57
## [7,]    7  46343  46343     997         57
## [8,]    8  49017  49017    1004         52
## [9,]    9  52071  52071     996         57
## [10,]  10  55725  55725    1010         52
## [11,]  11  59822  59822     997         57
## [12,]  12  63798  63798     994         57
## [13,]  13  68088  68088    1003         52
## [14,]  14  72812  72812     466        124
## [15,]  15  77966  77966     390        149
## [16,]  16  83593  83593     444        131
## [17,]  17  89228  89228     410        141
## [18,]  18  95269  95269     420        137
## [19,]  19 100711 100711     438        131
## [20,]  20 102102 102102     416        138
## [21,]  21 102941 102941     438        132
## [22,]  22 102747 102747     418        137
## [23,]  23 103098 103098     438        133
## [24,]  24 103284 103284     416        140
## [25,]  25 103390 103390     445        128
## [26,]  26 103622 103622     403        141
## [27,]  27 103557 103557     429        137

```


## [28,]	28	103410	103410	432	136
## [29,]	29	103485	103485	430	137
## [30,]	30	103511	103511	431	136

Conclusions

In this example, we showed how the built-in resource, observation, manager, and user sub-models can be customised by manipulating the data within the data structures that they use. The goal was to show how software users can work with these existing sub-models and data structures to customise GMSE simulations. Readers seeking even greater flexibility (e.g., replacing an entire built-in sub-model with a custom sub-model) should refer to [SI2](#) that introduces `gmse_apply` more generally. Future versions of GMSE are likely to expand on the built-in options available for simulation; requests for such expansions, or contributions, can be submitted to [GitHub](#).

References

- AEWA (2016). International single species action plan for the conservation of the Taiga Bean Goose (*Anser fabalis fabalis*).
- Cusack, J. J., Duthie, A. B., Rakotonarivo, S., Pozo, R. A., Mason, T. H. E., Månsson, J., Nilsson, L., Tombre, I. M., Eythórsson, E., Madsen, J., Tulloch, A., Hearn, R. D., Redpath, S., and Bunnefeld, N. (2018). Time series analysis reveals synchrony and asynchrony between conflict management effort and increasing large grazing bird populations in northern Europe. *Conservation Letters*, page e12450.
- Fox, A. D. and Madsen, J. (2017). Threatened species to super-abundance: The unexpected international implications of successful goose conservation. *Ambio*, 46(s2):179–187.
- Johnson, F. A., Alhainen, M., Fox, A. D., Madsen, J., and Guillemain, M. (2018). Making do with less: Must sparse data preclude informed harvest strategies for European waterbirds. *Ecological Applications*, 28(2):427–441.
- Mason, T. H., Keane, A., Redpath, S. M., and Bunnefeld, N. (2017). The changing environment of conservation conflict: geese and farming in Scotland. *Journal of Applied Ecology*, pages 1–12.
- Tulloch, A. I. T., Nicol, S., and Bunnefeld, N. (2017). Quantifying the expected value of uncertain management choices for over-abundant Greylag Geese. *Biological Conservation*, 214:147–155.