

# Package ‘LSC’

February 19, 2015

**Type** Package

**Title** Local Statistical Complexity - Automatic Pattern Discovery in Spatio-Temporal Data

**Version** 0.1.5

**Date** 2014-01-20

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**Description** Estimators and visualization for local statistical complexity of (N+1)D fields. In particular for 0, 1 and 2 dimensional space this package provides useful visualization.

**License** GPL-2

**Depends** R (>= 2.12.1), LICORS, RColorBrewer, fields, gam, Matrix

**URL** <http://www.gmge.org>

**Collate** 'LICORS2LSC.R' 'LSC-utils.R' 'plot\_LSC\_1plus1D.R' 'plot\_LSC\_2plus1D.R' 'states2LSC.R' 'states2probs.R' 'LSC-package.R' 'plot\_LSC\_0plus1D.R'

**NeedsCompilation** no

**Repository** CRAN

**Date/Publication** 2014-01-24 08:01:49

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LSC-package

*Local Statistical Complexity - Automated Pattern Discovery in Spatio-Temporal Data*


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## Description

A package to estimate local statistical complexity (LSC), a measure for automated pattern discovery in spatio-temporal data using optimal predictors (see References).

This package is very tightly linked to the **LICORS** package, which can be used to estimate these optimal predictors and state space from data. The **LSC** builds on a known or estimated state space; most estimation is handled by **LICORS** (see ?LICORS).

There are two ways the state space can be represented: either as a unique state label or as a vector of weights. These two are the principal arguments in the functions of this package:

`weight.matrix` an  $N \times K$  matrix, where  $N$  are the samples and  $K$  are the states. That is, each row contains a vector of length  $K$  that adds up to one (the mixture weights).

`states` a vector of length  $N$  with entry  $i$  being the label  $k = 1, \dots, K$  of PLC  $i$

This is an early release: some function names and arguments might/will (slightly) change in the future, so regularly check with new package updates.

## Author(s)

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## References

Shalizi, C. R., R. Haslinger, J.-B. Rouquier, K. L. Klinkner, and C. Moore (2006). "Automatic filters for the detection of coherent structure in spatiotemporal systems." *Physical Review E* 73, 036104

Shalizi, C. R., K. L. Klinkner, and R. Haslinger (2004a). "Quantifying self-organization with optimal predictors." *Physical Review Letters* 93, 118701.

## See Also

The main functions in this package are

- [states2LSC](#) to estimate LSC from the state space, and
- [LICORS2LSC](#) which is a wrapper for estimating LSC from a "LICORS" class estimate.

Since pattern discovery without visualization is only of very limited use, the [plot.LSC](#) function shows informative plots for  $(1 + 1)D$  and  $(2 + 1)D$  systems.

**Examples**

```
## known predictive state space with a state-vector
data(contCA00)
ll <- states2LSC(states = contCA00$predictive_states - min(contCA00$predictive_states) +
  1)
image2(ll, density = TRUE, legend = FALSE)

# An example using estimates from LICORS
## Not run:
example(LICORS) # this will give an object 'mod' of class 'LICORS'
image2(LICORS2LSC(mod))

## End(Not run)
```

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LICORS2LSC

*Estimates LSC from a LICORS estimate*


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**Description**

A wrapper of [states2LSC](#) for a 'LICORS' estimate from the **LICORS** package (in particular the output from the [mixed\\_LICORS](#) function). Converts LICORS estimates into an array with LSC.

**Usage**

```
LICORS2LSC(object, type = c("weights", "argmax"))
```

**Arguments**

object	an object of class "LICORS"
type	should marginal state probabilities be computed based on the unique state space assignment ("argmax") or using the soft thresholding from the weight matrix ("weights").

**Value**

An object of class "LSC"

**See Also**

[states2LSC](#), [LSC-utils](#)

**Examples**

```
## Not run:
# see 2nd example in 'LSC-package'

## End(Not run)
```

## Description

The "LSC" class lies at the core of this package as it describes spatio-temporal patterns in the data. It is usually an array with the same spatio-temporal resolution as the original dataset.

`plot.LSC` plots LSC of  $(1 + 1)D$  and  $(2 + 1)D$  systems.

`plot_LSC_1plus1D` plots LSC for a  $(1+1)D$  field.

`plot_LSC_2plus1D` plots LSC for a  $(2+1)D$  field.

`plot_LSC_0plus1D` plots LSC for a  $(0+1)D$  field, i.e., a time series.

## Usage

```
## S3 method for class 'LSC'
plot(x, ...)

plot_LSC_1plus1D(z, col = NULL, lsc.unit = "bits", heights = c(2, 5), widths = c(5,
  2))

plot_LSC_2plus1D(z, type = "temporal", time.frames = NULL, zlim = NULL, heights = NULL,
  lsc.unit = "bits", data = NULL, col = NULL)

plot_LSC_0plus1D(z, col = NULL, lsc.unit = "bits", ...)
```

## Arguments

<code>x</code>	an object of class "LSC"
<code>...</code>	optional arguments passed to <code>plot_LSC_2plus1D</code> or <code>plot_LSC_1plus1D</code> .
<code>widths</code>	passed to <code>layout</code> for dividing the plotting region horizontally. A vector of length 2: image (left) & temporal average (right)
<code>z</code>	an object of class "LSC"
<code>type</code>	a "temporal" or a "spatial" summary plot of LSC
<code>time.frames</code>	a vector of length $\leq 6$ to indicate what frames should be displayed (only for <code>type = "temporal"</code> ). If <code>NULL</code> (default) then it chooses them automatically based on valleys and peaks in the spatial average LSC.
<code>zlim</code>	minimum and maximum <code>z</code> values for which colors should be plotted, defaulting to the range of the finite values of <code>z</code> .
<code>lsc.unit</code>	character string (default: "bits") to write next to the color legend
<code>col</code>	colors: either a string describing a palette from the <code>RColorBrewer</code> package (see also <a href="http://colorbrewer2.org/">http://colorbrewer2.org/</a> ), or a list of colors (see <code>image</code> for suggestions).
<code>data</code>	(optional) original data to compare to LSC (relevant only for <code>type = "spatial"</code> )
<code>heights</code>	passed to <code>layout</code> for dividing the plotting region vertically. If <code>data = NULL</code> a vector of length 2; otherwise a vector of length 3.

**See Also**

[plot.mixed\\_LICORS](#), [plot\\_LSC\\_2plus1D](#), [plot\\_LSC\\_1plus1D](#)

**Examples**

```
## Not run:
data(contCA00)

temp_lsc <- states2LSC(states = contCA00$predictive_states -
  min(contCA00$predictive_states) + 1)
class(temp_lsc) <- c("LSC", "LSC_1plus1D")
plot_LSC_1plus1D(temp_lsc)

## End(Not run)
## Not run:
data(contCA00)

temp_lsc <- states2LSC(states = contCA00$predictive_states -
  min(contCA00$predictive_states) + 1)
temp_lsc_3D <- array(temp_lsc, dim = c(25, 20, 40))
class(temp_lsc_3D) <- c("LSC", "LSC_2plus1D")
plot_LSC_2plus1D(temp_lsc_3D, type = "temporal")
plot_LSC_2plus1D(temp_lsc_3D, type = "spatial")

## End(Not run)
state.sim <- rpois(100, 1)

lsc.est <- states2LSC(states = state.sim)
class(lsc.est) <- c("LSC", "LSC_0plus1D")
plot_LSC_0plus1D(lsc.est)

weights.sim <- matrix(runif(10000, 0, 1), ncol = 10)
weights.sim <- normalize(weights.sim)
lsc.est <- states2LSC(weight.matrix = weights.sim)
plot_LSC_0plus1D(lsc.est)
```

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states2LSC

*Estimate local statistical complexity (LSC) from states*

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**Description**

Converts states (either as a size  $N$  array of labels or an  $N \times K$  weight matrix) into  $N$  local statistical complexities (LSC) per state.

If states is a matrix - representing the state space in the dimensions of the original data - then the LSC output will be formatted automatically to an array of the same shape and dimension.

**Usage**

```
states2LSC(weight.matrix = NULL, states = NULL, base = 2, type = c("MLE"))
```

**Arguments**

weight.matrix  $N \times K$  weight matrix  
 states array of size  $N$  with entry  $i$  being the label  $k = 1, \dots, K$  of PLC  $i$ .  
 base logarithm base for complexity (entropy). Default: base = 2 (thus 'bits').  
 type estimation type for the probabilities: "MLE"

**See Also**

[states2probs](#)

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states2probs	<i>Convert states to vector of probabilities of any given state</i>
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**Description**

Converts states (either as a size  $N$  array of labels or an  $N \times K$  weight matrix) into  $N$  probabilities per state.

If states is a matrix - representing the state space in the dimensions of the original data - then the probabilities will be formatted automatically to an array of the same shape and dimension.

**Usage**

```
states2probs(weight.matrix = NULL, states = NULL, type = "MLE")
```

**Arguments**

states array of size  $N$  with entry  $i$  being the label  $k = 1, \dots, K$  of PLC  $i$   
 weight.matrix  $N \times K$  weight matrix  
 type estimation type for the probabilities: c("MLE")

**See Also**

[weight\\_matrix2states](#)

**Examples**

```
state.sim <- sample.int(5, 100, replace = TRUE)
prob.state <- states2probs(states = state.sim)
layout(matrix(1:2, ncol = 2))
plot(state.sim, xlab = "", ylab = "state")
plot(prob.state, xlab = "", ylab = "probability")
plot(state.sim, prob.state, xlab = "state", ylab = "probability", type = "h")
```

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