Package ‘SOMbrero’

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Title SOM Bound to Realize Euclidean and Relational Outputs

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Description The stochastic (also called on-line) version of the Self-Organising Map (SOM) algorithm is provided. Different versions of the algorithm are implemented, for numeric and relational data and for contingency tables as described, respectively, in Kohonen (2001) <isbn:3-540-67921-9>, Olteanu & Villa-Vialaneix (2005) <doi:10.1016/j.neucom.2013.11.047> and Cottrell et al (2004) <doi:10.1016/j.neunet.2004.07.010>. The package also contains many plotting features (to help the user interpret the results) and a graphical user interface based on 'shiny'.

BugReports http://github.com/tuxette/sombrero/issues

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initGrid Create an empty Self-Organizing Map structure

Description

Create an empty Self-Organizing Map structure which is a list of 2-dimensional points.

Usage

initGrid(dimension=c(5,5), topo=c("square"),
          dist.type=c("euclidean", "maximum", "manhattan", "canberra", "binary",
                        "minkowski", "letremy"))

## S3 method for class 'myGrid'
print(x, ...)
## S3 method for class 'myGrid'
summary(object, ...)

Arguments

dimension Vector of two integer points corresponding to the x dimension and the y dimension. Default values are: (5,5).
deco topo The topology to be used to build the grid. Default value is square.
dist.type The distance type to be used. Default value is euclidean. Type 'letremy' corresponds to the original implementation by Patrick Letremy.
x, object an object of class myGrid
... not used
Value

initGrid function returns an object of class myGrid, including the following components:

- **coord**: A two columns matrix which provides the coordinates of the points of the Self-Organizing Map structure,
- **topo**: Same value as the arguments given to initGrid function,
- **dim**: Same values as the arguments given to initGrid function.
- **dist.type**: Same value as the arguments given to initGrid function.

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References


See Also

See plot.myGrid for plotting a myGrid class object in a graphical window.

Examples

```r
# creating a default grid
# default parameters are: 5x5 dimension, squared topology
# and letremy distance type
initGrid()

# creating a 5x7 squared grid
initGrid(dimension=c(5, 7), topo="square", dist.type="maximum")
```

initSOM

**Initialize parameters for the SOM algorithm**

Description

The initSOM function returns a paramSOM class object which contains the parameters needed to run the SOM algorithm.
Usage

`initSOM(dimension=c(5,5), topo=c("square"),
radius.type=c("gaussian", "letremy"),
dist.type=switch(match.arg(radius.type),
  "letremy"="letremy", "gaussian"="euclidean"),
type=c("numeric", "relational", "korresp"),
affectation=c("standard", "heskes"),
maxit=500, nb.save=0,
verbose=FALSE, proto==NULL,
init.proto=switch(type, "numeric"="random", "relational"="obs",
  "korresp"="random"),
scaling=switch(type, "numeric"="unitvar", "relational"="none",
  "korresp"="chi2"), eps=1)

## S3 method for class 'paramSOM'
print(x, ...)
## S3 method for class 'paramSOM'
summary(object, ...)

Arguments

dimension Vector of two integer points corresponding to the x dimension and
the y dimension of the myGrid class object. Default values are: (5,5).
Other data-driven defaults are set by function trainSOM.

topo The topology to be used to build the grid of the myGrid class object. Default
value is square.

radius.type The neighbourhood type. Default value is "gaussian", which
corresponds to a Gaussian neighbourhood. The annealing of the
neighbourhood during the training step is similar to the one implemented
in yasomi. The alternative value corresponds to an piecewise linear
neighbourhood as implemented by Patrick Letremy in his SAS programs.

dist.type The neighborhood relationship on the grid. When radius.type is letremy,
default value is letremy which is the original implementation by Patrick
Letremy. When radius.type is gaussian, default value is euclidean. The
other possible values (maximum, manhattan, canberra, binary, minkowski)
are passed to method in function dist. dist.type="letremy" is not permitted
with radius.type="gaussian".

type The SOM algorithm type. Possible values are: numeric (default value), korresp
and relational.

mode The SOM algorithm mode. Default value is online.

affectation The SOM affectation type. Default value is standard which corresponds to
a hard affectation. Alternative is heskes which corresponds to Heskes’s soft
affectation.

maxit The maximum number of iterations to be done during the SOM algorithm
process. Default value is 500. Other data-driven defaults are set by function trainSOM.

nb.save The number of intermediate back-ups to be done during the algorithm process.
Default value is 0.
verbose  The boolean value which activates the verbose mode during the SOM algorithm process. Default value is FALSE.

proto0  The initial prototypes. Default value is NULL.

init.proto  The method to be used to initialize the prototypes, which may be random (randomization), obs (each prototype is assigned a random observation) or pca. In pca the prototypes are initialized to the observations closest to a grid along the two first principal components of the data (numeric case) or along a two-dimensional multidimensional scaling (relational case, equivalent to a relational PCA). Default value is random for the numeric and korresp types, and obs for the relational type. pca is not available for korresp SOM.

scaling  The type of data pre-processing. For numeric SOM, possibilities are unitvar (data are centered and scaled; this is the default value for a numeric SOM), none (no pre-processing), and center (data are centered but not scaled). For korresp SOM, the only available value is ch2. For relational SOM, possibilities are none (no pre-processing, default value for relational SOM) and cosine. This last one first turns the dissimilarity into a similarity using the suggestion in (Lee and Verleysen, 2007). Then, a cosine normalization as described in (Ben-Hur and Weston, 2010) is applied to the kernel, that is finally turned back into its induced distance. For further details on this processing, have a look at the corresponding documentation in the directory “doc” of the package’s installation directory.

eps0  The scaling value for the stochastic gradient descent step in the prototypes’ update. The scaling value for the stochastic gradient descent step is equal to $0.3c_0 \frac{1+0.2t}{\text{dim}}$, where $t$ is the current step number and dim is the grid dimension (width multiplied by height).

x, object  an object of class paramSOM.

...  not used

Value

The initSOM function returns an object of class paramSOM which is a list of the parameters passed to the initSOM function, plus the default parameters for the ones not specified by the user.

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References


Lesmis


See Also

See initGrid for creating a SOM prior structure (grid).

Examples

# create a default 'paramSOM' class object
default.paramSOM <- initSOM()
summary(default.paramSOM)

lesmis

Dataset "Les Miserables"

Description

This dataset contains the coappearance network (igraph object) of characters in the novel Les Misérables (written by the French writer Victor Hugo).

Usage

data(lesmis)

Format

lesmis is an igraph object. Its vertices are the characters of the novel and an edge indicates that the two characters appear together in the same chapter of the novel, at least once. Vertex attributes for this graph are 'id', a vertex number between 1 and 77, and 'label', the character’s name. The edge attribute ‘value’ gives the number of co-appearances between the two characters afferent to the edge (the igraph can thus be made a weighted graph using this attribute). Finally, a graph attribute ‘layout’ is used to provide a layout (generated with the igraph function layout_with_fr) for visualizing the graph.

dissim.lesmis is a dissimilarity matrix computed with the function shortest_paths and containing the length of the shortest paths between pairs of nodes.

Details

Les Miserables is a French historical novel, written by Victor Hugo and published in 1862. The co-appearance network has been extracted by D.E. Knuth (1993).

References

Hugo V. (1862) Les Miserables.

plot.myGrid

Examples

```r
data(lesmis)
## Not run:
summary(lesmis)
plot(lesmis, vertex.size = 0)
## End(Not run)
```

## Description

Draw a grid corresponding to a `myGrid` class object in a graphical window.

## Usage

```r
## S3 method for class 'myGrid'
plot(x, neuron.col = "white", print.title = FALSE,
     the.titles = paste("Cluster", 1:prod(x$dim)), ...)
```

## Arguments

- `x`: The `myGrid` class object to be drawn.
- `neuron.col`: Color(s) used to depict the neurons. Default value is `white`. If the argument is composed of one single color, neurons will all be filled with the same color. If the argument is composed of many colors, the number of colors must match the total number of neurons.
- `print.title`: Whether the cluster titles must be printed in center of the grid or not. Default to `FALSE` (titles not displayed).
- `the.titles`: If `print.title = TRUE`, values of the title to display. Default to "Cluster " followed by the cluster number.
- `...`: Further arguments to the `plot` function.

## Details

Color filling process uses the coordinates of the object `x`, having class `myGrid` and included in `x$coord`.

## Author(s)

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## See Also

- `initGrid` to define a `myGrid` class object.
Examples

# creating grid
a.grid <- initGrid(dimension=c(5,5), topo="square", dist.type="maximum")

# plotting grid
# without any color specification
plot(a.grid)
# generating colors from rainbow() function
my.colors <- rainbow(5*5)
plot(a.grid, neuron.col=my.colors)

---

plot.somRes

Draw a somRes class object

Description

Produce graphics to help interpreting a somRes object.

Usage

## S3 method for class 'somRes'
plot(x, what=c("obs", "prototypes", "energy", "add"),
     type=switch(what, "obs"="hitmap", "prototypes"="color", "add"="pie",
                  "energy"=NULL),
     variable = if (what=="add") NULL else if (type=="boxplot")
                 1:min(5, ncol(x$data)) else 1,
     my.palette=NULL,
     is.scaled = if (x$parameters$type=="numeric") TRUE else FALSE,
     print.title=FALSE, the.titles=if (what!="energy")
                       switch(type, "graph"=1:prod(x$parameters(the.grid$dim)),
                           paste("Cluster", 1:prod(x$parameters(the.grid$dim)))),
     proportional=TRUE, s.radius=1, pie.graph=FALSE, pie.variable=NULL,
     view = if (x$parameters$type=="korresp") "r" else NULL, ...)

Arguments

x
A somRes class object.

what
What you want to plot. Either the observations (obs, default case), the evolution of energy (energy), the prototypes (prototypes) or an additional variable (add).

type
Further argument indicating which type of chart you want to have. Choices depend on the value of what (what="energy" has no type argument). Default values are "hitmap" for obs, "color" for prototypes and "pie" for add. See section "Details" below for further details.

variable
Either the variable to be used for what="add" or the index of the variable of the data set to consider. For type="boxplot", the default value is the sequence from 1 to the minimum between 5 and the number of columns of the data set. In all other cases, default value is 1. See somRes.plotting for further details.
my.palette  A vector of colors. If omitted, predefined palettes are used, depending on
the plot case. This argument is used for the following combinations: all "color"
types and "prototypes"/"poly.dist".

is.scaled  A boolean indicating whether values should be scaled prior to plotting or not.
Default value is TRUE when type="numeric" and FALSE in the other cases.

print.title  Boolean used to indicate whether each neuron should have a title or not. De-
default value is FALSE. It is feasible on the following cases: all "color" types, all
"lines" types, all "barplot" types, all "radar" types, all "boxplot" types, all
"names" types, "add"/"pie", "prototypes"/"umatrix", "prototypes"/"poly.dist"
and "add"/"words".

the.titles  The titles to be printed for each neuron if print.title=TRUE. Default to a num-
ber which identifies the neuron.

proportional  Boolean used when what="add" and type="pie". It indicates if the pies should
be proportional to the number of observations in the class. Default value is TRUE.

s.radius  The size of the pies to be plotted (maximum size when proportional=TRUE).
The default value is 0.9.

pie.graph  Boolean used when what="add" and type="graph". It indicates if the vertices
should be pies or not.

pie.variable  The variable needed to plot the pies when what="add", type="graph" and ar-

view  Used only when the algorithm’s type is "korresp". It indicates whether rows
("r") or columns ("c") must be drawn.

...  Further arguments to be passed to the underlined plot function (which can be
plot, barplot, pie... depending on type; see somRes.plotting for further
details).

Details

See somRes.plotting for further details.

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See Also

trainSOM to run the SOM algorithm, that returns a somRes class object.
predict.somRes

**predict.somRes**  
*Predict the classification of a new observation*

### Description

Predict the neuron where a new observation is classified

### Usage

```r
## S3 method for class 'somRes'
predict(object, x.new=NULL, ..., radius=0, tolerance=10^(-10))
```

### Arguments

- **object**: `somRes` object
- **x.new**: a new observation (optional). Default is `NULL` which corresponds to performing prediction on the training dataset
- **...**: not used
- **radius**: current radius used to perform soft affectation (when affectation="heskes", see `initSOM` for further details about Heskes's soft affectation). Default value is `0`, which corresponds to a hard affectation.
- **tolerance**: numeric tolerance (to avoid numeric instability during 'cosine' pre-processing). Default value is `10^(-10)`

### Details

The number of columns of the new observations (or its length if only one observation is provided) must match the number of columns of the data set given to the SOM algorithm (see `trainSOM`).

### Value

*predict.somRes* returns the number of the neuron to which the new observation is assigned (i.e., neuron with the closest prototype).

When the algorithm's type is "korresp", `x.new` must be the original contingency table passed to the algorithm.

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### See Also

* `trainSOM`
Examples

```r
set.seed(2343)
my.som <- trainSOM(x.data=iris[-100,1:4], dimension=c(5,5))
predict(my.som, iris[100,1:4])
```

---

presidentielles2002 2002 French presidential election data set

Description

This data set provides the number of votes at the first round of the 2002 French presidential election for each of the 16 candidates for 106 administrative districts called "Departements".

Usage

data(presidentielles2002)

Format

presidentielles2002 is a data frame of 106 rows (the French administrative districts called "Departements") and 16 columns (the candidates).

Source

The data are provided by the French minister "Ministere de l'Interieur". The original data can be downloaded at [http://www.interieur.gouv.fr/Elections/Les-resultats/Presidentielles](http://www.interieur.gouv.fr/Elections/Les-resultats/Presidentielles) (2002 elections and "Resultats par departements")

References

The 2002 French presidential election consisted of two rounds. The second round attracted a greater than usual amount of international attention because of far-right candidate Le Pen's unexpected victory over Socialist candidate Lionel Jospin. The event is known because, on the one hand, the number of candidates was unusually high (16) and, on the other hand, because the polls had failed to predict that Jean-Marie would be on the second round.


Examples

```r
data(presidentielles2002)
apply(presidentielles2002,2,sum)
```
projectIGraph

Compute the projection of a graph on a grid

Description

Compute the projection of a graph, provided as an igraph object, on the grid of the somRes object.

Usage

```r
## S3 method for class 'somRes'
projectIGraph(object, init.graph, ...)
```

Arguments

- `object`: a somRes object.
- `init.graph`: an igraph whose number of vertices is equal to the clustering length of the somRes object.
- `...`: Not used.

Value

The result is an igraph which vertexes are the clusters (the clustering is thus understood as a vertex clustering) and the edges are the counts of edges in the original graph between two vertices corresponding to the two clusters in the projected graph or, if `init.graph` is a weighted graph, the sum of the weights between the pairs of vertices corresponding to the two clusters.

The resulting igraph object's attributes are:

- the graph attribute `layout` which provides the layout of the projected graph according to the grid of the SOM;
- the vertex attributes `name` and `size` which, respectively are the vertex number on the grid and the number of vertexes included in the corresponding cluster;
- the edge attribute `weight` which gives the number of edges (or the sum of the weights) between the vertexes of the two corresponding clusters.

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References

protoDist

See Also

`projectIGraph.somSC` which uses the results of a super-clustering to obtain another projected graph. `plot.somRes` with the option `type="graph"` or `plot.somSC` with the option `type="projgraph"`.

Examples

data(lesmis)
set.seed(7383)
mis.som <- trainSOM(x.data=dissim.lesmis, type="relational", nb.save=10)
proj.lesmis <- projectIGraph(mis.som, lesmis)
## Not run: plot(proj.lesmis)

protoDist

Compute distances between prototypes

Description

Compute distances, either between all prototypes (mode="complete") or only between prototypes’ neighbours (mode="neighbors").

Usage

## S3 method for class 'somRes'
protoDist(object, mode=c("complete","neighbors"), ...)

Arguments

object a somRes object.
mode Specifies which distances should be computed.
... Not used.

Details

When mode="complete", distances between all prototypes are computed. When mode="neighbors", distances are computed only between the prototypes and their neighbors. If the data were preprocessed during the SOM training procedure, the distances are computed on the normalized values of the prototypes.

Value

When mode="complete", the function returns a square matrix which dimensions are equal to the product of the grid dimensions.

When mode="neighbors", the function returns a list which length is equal to the product of the grid dimensions; the length of each item is equal to the number of neighbors. Neurons are considered to have 8 neighbors at most (i.e., two neurons are neighbors if they have a distance of type 'maximum' which is equal to 1).
Quality

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See Also

trainSOM

Examples

```r
set.seed(2343)
my.som <- trainSOM(x=data[,1:4], dimension=c(5,5))
protoDist(my.som)
```

**quality**

*Compute SOM algorithm quality criteria*

**Description**

The quality function computes several quality criteria for the result of a SOM algorithm.

**Usage**

```r
## S3 method for class 'somRes'
quality(sommap, quality.type=c("all", "quantization", "topographic"), ...)
```

**Arguments**

- `sommap`: A somRes object (see trainSOM for details).
- `quality.type`: The quality type to compute. Two types are implemented: quantization and topographic. The output of the function is one those or both of them using the option "all". Default value is the latter.
- `...`: Not used.

**Value**

The quality function returns either a numeric value (if only one type is computed) or a list a numeric values (if all types are computed).

The quantization error calculates the mean squared euclidean distance between the sample vectors and their respective cluster prototypes. It is a decreasing function of the size of the map.

The topographic error is the simplest of the topology preservation measure: it calculates the ratio of sample vectors for which the second best matching unit is not in the direct neighborhood of the best matching unit.
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**References**


**See Also**

`trainSOM`, `plot.somRes`

**Examples**

```r
my.som <- trainSOM(x.data=iris[,1:4])
quality(my.som, quality.type="all")
quality(my.som, quality.type="topographic")
```

**Description**

This package implements the stochastic (also called on-line) Self-Organising Map (SOM) algorithm for numeric and relational data.

It is based on a grid (see `initGrid`) which is part of the parameters given to the algorithm (see `initSOM` and `trainSOM`). Many graphs can help you with the results (see `plot.somRes`).

**Details**

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The version of the SOM algorithm implemented in this package is the stochastic version.

Several variants able to handle non-vectorial data are also implemented in their stochastic versions: type="korresp" for contingency tables, as described in Cottrell et al., 2004 (with the observation weights defined in Cottrell and Letremy, 2005) and type="relational" for dissimilarity data, as described in Olteanu and Villa-Vialaneix, 2015a with the fast implementation of Mariette et al., 2017. A special focus has been put on representing graphs, as described in Olteanu and Villa-Vialaneix, 2015b.
sombreroGUI

Graphical Web User Interface for SOMbrero

Description

Starts the SOMbrero GUI

Usage

sombreroGUI()
**Arguments**

No arguments.

**Value**

This function starts the graphical user interface with the default system browser. This interface is more likely to work properly with Firefox [http://www.mozilla.org/fr/firefox/new/](http://www.mozilla.org/fr/firefox/new/). In case Firefox is not your default browser, copy/paste [http://localhost:8100](http://localhost:8100) into the address bar.

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**References**


RStudio and Inc. (2013). shiny: Web Application Framework for R. R package version 0.7.0. [https://cran.r-project.org/package=shiny](https://cran.r-project.org/package=shiny)

---

**somRes.plotting**

*Plotting somRes results*

**Description**

Useful details on how to produce graphics to help interpreting a somRes object. Important: all these graphics are available when the algorithm’s type is "numeric"; those which are available for a korresp SOM are marked by a * and those which are available for a relational SOM are marked with a #.

**Graphics on the observations:** what="obs"

The possible values for type are: "hitmap"(*, #), "color", "lines", "barplot", "names"(*, #), "boxplot" and "radar".

For the cases what="obs" and what="add", if a neuron is empty, nothing will be plotted at its location.

- "hitmap" (*, #) plots proportional areas according to the number of observations per neuron. It is the default plot when what="obs".
- "color" can have two more arguments, var, the index of the variable to be considered (default, 1), and my.palette for the colors to be used. Neurons are filled using the given colors according to the average value level of the observations for the chosen variable.
• "lines" plots, for each neuron, the average value level of the observations, with lines. One point represents a variable. All variables of the dataset used to train the algorithm are plotted.

• "barplot" is similar to "lines" but using barplots. Then, a bar represents a variable.

• "radar" is similar to "lines" but using radars. Then, a slice represents a variable. If needed, a legend can be added; its location has to be passed by the key.loc argument (see stars).

• "names" (*, #) prints on the grid the element names (i.e., the names of the rows) in the neuron to which it belongs.

• "boxplot" plots boxplots for several observations in every neuron. This case can handle 5 variables at most. The default behavior is to plot the boxplots for the first 5 variables of the data set; if there is less than 5 variables in the data set, they will all be plotted.

When the algorithm's type is korresp or relational, only the types "hitmap" and "names" are available.

**Graphic on the energy:** what="energy" (*, #)

This graphic is only available if some intermediate backups have been registered (i.e., x$parameters$nb.save>1). Graphic plots the evolution of the level of the energy according to the registered steps.

**Graphics on the prototypes:** what="prototypes"

The possible values for type are: "3d"(*), "lines"(*, #), "barplot"(*, #), "radar"(*, #), "color"(*), "smooth.dist"(*, #), "poly.dist"(*, #), "umatrix"(*, #), "mds"(*, #) and "grid.dist"(*, #).

• "lines" (*, #) has the same behavior as the "lines" case described in the observations section, but according to the prototypes level;

• "barplot" (*, #) has the same behavior as the "barplot" case described in the observations section, but according to the prototypes level;

• "radar" (*, #) has the same behavior as the "radar" case described in the observations section, but according to the prototypes level;

• "color" (*) has the same behavior as the "color" case described in the observations section, but according to the prototypes level;

• "3d" case is similar to the "color" case, but in 3 dimensions, with x and y the coordinates of the grid and z the value of the prototypes for the considered variable;

• "smooth.dist" (*, #) depicts the average distance between a prototypes and its neighbors on a map where x and y are the coordinates of the prototypes on the grid;

• "poly.dist" (*, #) also represents the distances between prototypes but with polygons plotted for each neuron. The closest from the border the polygon point is, the closest the pairs of prototypes are. The color used for filling the polygon shows the number of observations in each neuron. A white polygon means that there is no observation. With the default colors, a red polygon means a high number of observations;

• "umatrix" (*, #) is another way of plotting distances between prototypes. The grid is plotted and filled with my.palette colors according to the mean distance between the current neuron and the neighboring neurons. With the default colors, red indicates proximity.

• "mds" (*, #) plots the number of the neuron on a map according to a Multi Dimensional Scaling (MDS) projection on a two dimensional space.
• "grid.dist" (*, #) plots on a 2 dimension map all distances. The number of points on this picture is equal to: \(\frac{\text{number of neurons} \times (\text{number of neurons} - 1)}{2}\). On the x axis corresponds to the prototype distances whereas the y axis depicts the grid distances.

**Graphics on an additional variable:** what="add" (#)

The case what="add" considers an additional variable, which has to be given to the argument variable. Its length must match the number of observations in the original data. Then the possible values for type are: "pie"(#), "color"(#), "lines"(#), "boxplot"(#), "barplot"(#), "radar"(#), "names"(#), "words"(#) and "graph"(#).

• "color" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be a numerical vector;

• "lines" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be a numerical matrix or a data frame;

• "boxplot" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be either a numeric vector or a numeric matrix/data frame;

• "barplot" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be either a numeric vector or a numeric matrix/data frame;

• "radar" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be a numerical matrix or data frame;

• "pie" requires the argument variable to be a factor vector and plots one pie for each neuron according to this factor;

• "names" (#) has the same behavior as the "names" case described in the observations section. Then, the names to be printed are the elements of the variable given to the variable argument;

• "words" (#) needs the argument variable be a contingency table: names of the columns will be used as words and the values express the frequency of a given word in the observation. Then, for each neuron of the grid, the words will be printed with sizes proportional to their frequency in the neuron;

• Last option is "graph" (#). The argument variable must be an igraph object (see library(igraph). According to the existing edges in the graph and to the clustering obtained with the SOM algorithm, a clustered graph will be produced where a vertex between two vertices represents a neuron and the width of an edge is proportional to the number of edges in the given graph between the vertices affected to the corresponding neurons. The option can handle two more arguments: pie.graph and pie.variable. These are used to display the vertex as pie charts. For this case, pie.graph must be set to TRUE and a factor vector is supplied by pie.variable.

When the algorithm’s type is korresp, no graphic is available for what="add".

All these graphics are available for a relational SOM.

**Further arguments via ...**

Further arguments, their reference functions and the plot.somRes cases are summarized in the following list:
• **plot** is called by the cases:
  – what="energy"
  – type="lines"
  – what="prototypes"/type="mds"

• **plot.myGrid** is called by the cases:
  – what="obs"/type="hitmap"
  – type="color"
  – what="prototypes"/type="poly.dist"
  – what="prototypes"/type="umatrix"

• **plot.igraph** is called by the case what="add"/type="graph"

• **pie** is called by the case what="add"/type="pie"

• **barplot** is called by the cases type="barplot"

• **boxplot** is called by the cases type="boxplot"

• **stars** is called by the cases type="radar"

• **persp** is called by the case what="prototypes"/type="3d"

• **wordcloud** is called by the cases:
  – type="names"
  – what="add"/type="words"

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**Examples**

```r
# run the SOM algorithm on the numerical data of 'iris' data set
iris.som <- trainSOM(x.data=iris[,1:4], nb.save=2)

# plots
# on energy
plot(iris.som, what="energy")  # energy
# on prototypes
plot(iris.som, what="prototypes", type="3d", variable="Sepal.Length")
# on an additional variable: the flower species
plot(iris.som, what="add", type="pie", variable=iris$Species)
```
superClass  

Create super-clusters from SOM clustering

Description

Aggregate the resulting clustering of the SOM algorithm into super-clusters.

Usage

```r
## S3 method for class 'somRes'
superClass(sommap, method="ward.D", members=NULL, k=NULL, h=NULL, ...)
## S3 method for class 'somSC'
print(x, ...)
## S3 method for class 'somSC'
summary(object, ...)
## S3 method for class 'somSC'
projectIGraph(object, init.graph, ...)
## S3 method for class 'somSC'
plot(x, type=c("dendrogram", "grid", "hitmap", "lines", "barplot", "boxplot", "mds", "color", "poly.dist", "pie", "graph", "dendro3d", "radar", "projgraph"), plot.var=TRUE, plot.legend=FALSE, add.type=FALSE, print.title = FALSE, the.titles = paste("Cluster", 1:prod(x$som$parameters$the.grid$dim)), ...)
```

Arguments

- `sommap` A somRes object
- `method, members` Arguments passed to the `hclust` function.
- `k, h` Arguments passed to the `cutree` function (respectively, the number of super-clusters or the height where to cut the dendrogram).
- `x, object` A somSC object
- `init.graph` An igraph object which is projected according to the super-clusters. The number of vertices of init.graph must be equal to the number of rows in the original dataset processed by the SOM (case "korresp" is not handled by this function). In the projected graph, the vertices are positionned at the center of gravity of the super-clusters (more details in the section Details below).
- `type` The type of plot to draw. Default value is "dendrogram", to plot the dendrogram of the clustering. Case "grid" plots the grid in color according to the super clustering. Case "projgraph" uses an igraph object passed to the
argument variable and plots the projected graph as defined by the function
projectigraph.somSC. All other cases are those available in the function plot.somRes
and superimpose the super-clusters over these plots.

plot.var A boolean indicating whether a graph showing the evolution of the explained
variance should be plotted. This argument is only used when type=\"dendrogram\", its default value is TRUE.

plot.legend A boolean indicating whether a legend should be added to the plot. This argu-
ment is only used when type is either \"grid\" or \"hitmap\" or \"mds\". Its default value is FALSE.

add.type A boolean, which default value is FALSE, indicating whether you are giving an
additional variable to the argument variable or not. If you do, the function
plot.somRes will be called with the argument what set to \"add\".

print.title Whether the cluster titles must be printed in center of the grid or not for type=\"grid\".
Default to FALSE (titles not displayed).

the.titles If print.title = TRUE, values of the title to display for type=\"grid\". Default
to \"Cluster \" followed by the cluster number.

... Used for plot.somSC: further arguments passed either to the function plot (case
type=\"dendro\") or to plot.myGrid (case type=\"grid\") or to plot.somRes
(all other cases).

Details

The superClass function can be used in 2 ways:

• to choose the number of super clusters via an hclust object: then, both arguments k and h are
not filled.

• to cut the clustering into super clusters: then, either argument k or argument h must be filled.
   See cutree for details on these arguments.

The squared distance between prototypes is passed to the algorithm.

summary on a superClass object produces a complete summary of the results that displays
the number of clusters and super-clusters, the clustering itself and performs ANOVA analyses. For
type=\"numeric\" the ANOVA is performed for each input variable and test the difference of this
variable accross the super-clusters of the map. For type=\"relational\" a dissimilarity ANOVA is
performed (see (Anderson, 2001), except that in the present version, a crude estimate of the p-value
is used which is based on the Fisher distribution and not on a permutation test.

On plots, the different super classes are identified in the following ways:

• either with different color, when type is set among: \"grid\" (*, #), \"hitmap\" (*, #), \"lines\n   
\" (*, #), \"barplot\" (*, #), \"boxplot\", \"mds\" (*, #), \"dendro3d\" (*, #), \"graph\" (*, #)

• or with title, when type is set among: \"color\" (*), \"poly.dist\" (*, #), \"pie\" (#), \"radar\n   (#)

In the list above, the charts available for a korresp SOM are marked with a * whereas those avail-
able for a relational SOM are marked with a #.

projectigraph.somSC produces a projected graph from the igraph object passed to the argument
variable as described in (Olteanu and Villa-Vialaneix, 2015). The attributes of this graph are the
same than the ones obtained from the SOM map itself in the function `projectIGraph.somRes`. `plot.somSC` used with `type="projgraph"` calculates this graph and represents it by positionning the super-vertexes at the center of gravity of the super-clusters. This feature can be combined with `pie.graph=TRUE` to super-impose the information from an external factor related to the individuals in the original dataset (or, equivalently, to the vertexes of the graph).

Value

The `superClass` function returns an object of class `somSC` which is a list of the following elements:

- **cluster**: The super clustering of the prototypes (only if either `k` or `h` are given by user).
- **tree**: An `hclust` object.
- **som**: The `somRes` object given as argument (see `trainSOM` for details).

The `projectIGraph.somSC` function returns an object of class `igraph` with the following attributes:

- the graph attribute `layout` which provides the layout of the projected graph according to the center of gravity of the super-clusters positionned on the SOM grid;
- the vertex attributes `name` and `size` which, respectively are the vertex number on the grid and the number of vertexes included in the corresponding cluster;
- the edge attribute `weight` which gives the number of edges (or the sum of the weights) between the vertexes of the two corresponding clusters.

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References


See Also

`hclust`, `cutree`, `trainSOM`, `plot.somRes`

Examples

```r
set.seed(11051729)
my.som <- trainSOM(x.data=iris[,1:4])
# choose the number of super-clusters
sc <- superClass(my.som)
plot(sc)
# cut the clustering
sc <- superClass(my.som, k=4)
summary(sc)
plot(sc)
plot(sc, type="hitmap", plot.legend=TRUE)
```
trainSOM  

**Run the SOM algorithm**

**Description**

The `trainSOM` function returns a `somRes` class object which contains the outputs of the algorithm.

**Usage**

```r
trainSOM(x.data, ...)  
## S3 method for class 'somRes'
print(x, ...)  
## S3 method for class 'somRes'
summary(object, ...)
```

**Arguments**

- `x.data`: a data frame or matrix containing the observations to be mapped on the grid by the SOM algorithm.
- `...`: Further arguments to be passed to the function `initSOM` for specifying the parameters of the algorithm. The default values of the arguments `maxit` and `dimension` are calculated according to the SOM type if the user does not set them:
  - `maxit`: is equal to (number of rows + number of columns) * 5 if the SOM type is `korresp`. It is equal to number of rows * 5 in all other SOM types.
  - `dimension`: for a `korresp` SOM, is approximately equal to the square root of the number of observations to be classified divided by 10 but it is never smaller than 5 or larger than 10.
- `x`, `object`: an object of class `somRes`

**Details**

The version of the SOM algorithm implemented in this package is the stochastic version.

Several variants able to handle non-vectorial data are also implemented in their stochastic versions:
- `type = "korresp"` for contingency tables, as described in Cottrell et al., 2004 (with weights as in Cottrel and Letremy, 2005).
- `type = "relational"` for dissimilarity matrices, as described in Olteanu et al., 2015, with the fast implementation introduced in Mariette et al., 2017.

`summary` produces a complete summary of the results that displays the parameters of the SOM, quality criteria and ANOVA. For `type = "numeric"` the ANOVA is performed for each input variable and test the difference of this variable accross the clusters of the map. For `type = "relational"` a dissimilarity ANOVA is performed (see Anderson, 2001), except that in the present version, a crude estimate of the p-value is used which is based on the Fisher distribution and not on a permutation test.
Value

The `trainSOM` function returns an object of class `somRes` which contains the following components:

- `clustering` the final classification of the data.
- `prototypes` the final coordinates of the prototypes.
- `energy` the final energy of the map.
- `backup` a list containing some intermediate backups of the prototypes coordinates, clustering, energy and the indexes of the recorded backups, if `nb.save` is set to a value larger than 1.
- `data` the original dataset used to train the algorithm.
- `parameters` a list of the map’s parameters, which is an object of class `paramSOM` as produced by the function `initSOM`.

The function `summary.somRes` also provides an ANOVA (ANalysis Of VAriance) of each input numeric variables in function of the map’s clusters. This is helpful to see which variables participate to the clustering.

Note

Warning! Recording intermediate backups with the argument `nb.save` can strongly increase the computational time since calculating the entire clustering and the energy is time consuming. Use this option with care and only when it is strictly necessary.

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References


Mariette J., Rossi F., Olteanu M., Mariette J. (2017) Accelerating stochastic kernel SOM. In: M. Verleysen, *XXVth European Symposium on Artificial Neural Networks, Computational Intelligence and Machine Learning (ESANN 2017)*, i6doc, Bruges, Belgium, 269-274.
See Also

See `initSOM` for a description of the parameters to pass to the `trainSOM` function to change its behavior and `plot.somRes` to plot the outputs of the algorithm.

Examples

```r
# Run trainSOM algorithm on the iris data with 500 iterations
iris.som <- trainSOM(x.data=iris[,1:4])
iris.som
summary(iris.som)
```
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