Package ‘aslib’

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Title  Interface to the Algorithm Selection Benchmark Library

Description  Provides an interface to the algorithm selection benchmark library
at <http://www.aslib.net> and the 'LLAMA' package
(<https://cran.r-project.org/package=llama>) for building
algorithm selection models; see Bischl et al. (2016)

Author  Bernd Bischl <bernd_bischl@gmx.net>, Lars Kotthoff <larsko@uwyo.edu>,
Pascal Kerschke <kerschke@uni-muenster.de> [ctb],
Damir Pulatov <damirpolat@protonmail.com> [ctb]

Maintainer  Lars Kotthoff <larsko@uwyo.edu>

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ASScenarioDesc

Description

Object members

Details

scenario_id [character(1) ] Name of scenario.

performance_measures [character ] Names of measures.

maximize [named character ] Maximize measure?

performance_type [named character ] Either “runtime” or “solution_quality”.

algorithm_cutoff_time [numeric(1) ] Cutoff time for an algorithm run.

algorithm_cutoff_memory [numeric(1) ] Cutoff memory for an algorithm run.

features_cutoff_time [numeric(1) ] Cutoff time for an instance feature run.
checkDuplicatedInstances

Description
Potentially duplicated instances are detected by grouping all instances with equal feature vectors.

Usage
checkDuplicatedInstances(asscenario)

Arguments
asscenario [ASScenario] Algorithm selection scenario.

Value
list of character . List of instance id vectors where corresponding feature vectors are the same. Only groups of at least 2 elements are returned.

convertAlgoPerfToWideFormat
Converting algo.runs object of a scenario to wide format.

Description
The first 2 columns are “instance_id” and “repetition”. The remaining ones are the measured performance values. The feature columns are in the same order as “features_deterministic”, “features_stochastic” in the description object. codeNA means the performance value is not available, possibly because the algorithm run was aborted. The data.frame is sorted by “instance_id”, then “repetition”.

Usage
convertAlgoPerfToWideFormat(desc, algo.runs, measure)
convertToLlama

Arguments

desc \[\text{ASScenarioDesc}\]
Description object of scenario.

algo.runs \[\text{data.frame}\]
Algo runs data.frame from scenario.

measure \[\text{character(1)}\]
Selected performance measure. Default is first measure in scenario.

Value
data.frame.

Description
For features, mean values are computed across repetitions. For algorithms, repetitions are not supported at the moment and will result in an error.

Usage
convertToLlama(asscenario, measure, feature.steps)

Arguments
asscenario \[\text{ASScenario}\]
Algorithm selection scenario.

measure \[\text{character(1)}\]
Measure to use for modeling. Default is first measure in scenario.

feature.steps \[\text{character}\]
Which feature steps are allowed? Default are the default feature steps or all steps in case no defaults were defined.

Details
Note that feature step dependencies are currently not supported explicitly by LLAMA. The conversion checks that all dependencies are satisfied, but subsequent feature selection on the LLAMA data frame may not work as expected.

Value
Result of calling \text{input}. 

**convertToLlamaCVFolds**  
Convert an ASScenario scenario object to a llama data object with cross-validation folds.

**Description**

For features, mean values are computed across repetitions. For algorithms, repetitions are not supported at the moment and will result in an error.

**Usage**

```r
convertToLlamaCVFolds(
  asscenario,
  measure,
  feature.steps,
  algorithm.feature.steps,
  cv.splits
)
```

**Arguments**

- `asscenario` [ASScenario]
  Algorithm selection scenario.
- `measure` [character(1)]
  Measure to use for modelling. Default is first measure in scenario.
- `feature.steps` [character]
  Which instance feature steps are allowed? Default are the default instance feature steps or all steps in case no defaults were defined.
- `algorithm.feature.steps` [character]
  Which algorithm feature steps are allowed? Default are the default algorithm feature steps or all steps in case no defaults were defined.
- `cv.splits` [data.frame]
  Data frame defining the split of the data into cross-validation folds, as returned by `createCVSplits`. Default are the splits `asscenario$cv.splits`

**Value**

Result of calling `input` with data partitioned into folds.
createCVSplits  

Create cross-validation splits for a scenario.

Description

Create a data.frame that defines cross-validation splits for a scenario, and potentially store it in an ARFF file. The mlr package is used to generate the splits, see makeResampleDesc and makeResampleInstance.

Usage

createCVSplits(asscenario, reps = 1L, folds = 10L, file = NULL)

Arguments

asscenario  
[ASScenario]  
Algorithm selection scenario.

reps  
[integer]  
CV repetitions. Default is 1.

folds  
[integer]  
CV folds. Default is 10.

file  
[character]  
If not missing, where to save the returned splits as an ARFF file via write.arff. Default is no saving.

Value

data.frame. Splits as defined in the algorithm benchmark repository specification text. Has columns: “instance_id”, “fold”, “rep”. Defines which instances go into the test set for each replication / fold during CV. The training set are the remaining instances, in exactly the order as given by the data.frame for the current repetition.

findDominatedAlgos  

Creates a table that shows the dominance of one algorithm over another one.

Description

If NAs occur, they are imputed (before aggregation) by base + 0.3 * range. base is the cutoff value for runtimes scenarios with cutoff or the worst performance for all others. Stochastic replications are aggregated by the mean value.

Usage

findDominatedAlgos(asscenario, measure, reduce = FALSE, type = "logical")
**Arguments**

asscenario  
[ASScenario]  
Algorithm selection scenario.

measure  
[character(1)]  
Measure for algorithm performance. Default is first measure in scenario.

reduce  
[logical(1)]  
Should the resulting matrix be reduced to algorithms that are either dominated by or dominate another algorithm? Default is FALSE.

type  
[character(1)]  
Data type of the result object.  
“logical”: Logical matrix, TRUE means row algorithm dominates column algorithm.  
“character”: Same information but more human-readable. States how the row relates to the column.

**Value**

matrix . See above.

---

**fixFeckingPresolve**  
*Bakes presolving stuff into a LLAMA data frame.*

**Description**

Determines whether any of the feature groups in the LLAMA data frame presolve any of the instances. If so, the performances of all algorithms in the portfolio are set to the runtime of the first used feature group that presolves the respective instance. Furthermore, the success of all algorithms on those instances is set to true.

**Usage**

```
fixFeckingPresolve(asscenario, ldf)
```

**Arguments**

asscenario  
[ASScenario]  
Algorithm selection scenario.

ldf  
[LLAMA data frame]  
LLAMA data frame to modify.

**Details**

These modifications are done on the main LLAMA data and on any test splits. They are *not* done on the training data. This function should only ever be used to evaluate the performance of an actual selector that uses features (i.e. not VBS or single best). Using it in polite company is to be avoided.
Value

The LLAMA data frame with presolving baked into the algorithm performances.

---

getAlgorithmNames

Returns algorithm names of scenario.

---

Description

Returns algorithm names of scenario.

Usage

getAlgorithmNames(asscenario)

Arguments

asscenario [ASScenario]
Algorithm selection scenario.

Value

character.

---

cgetCosealASScenario

Retrieves a scenario from the Coseal Github repository and parses into an S3 object.

---

Description

Uses subversion export to retrieve a specific scenario from the official Coseal Github repository. The scenario is checked out into a temporary directory and parsed with parseASScenario.

Usage

cgetCosealASScenario(name)

Arguments

name [character(1)]
Name of benchmark data set.

Value

ASScenario. Description object.
getCostsAndPresolvedStatus

Examples

```r
## Not run:
sc = getPosealASScenario("CSP-2010")

## End(Not run)
```

getCostsAndPresolvedStatus

Return whether an instance was presolved and which step did it.

Description

Return whether an instance was presolved and which step did it.

Usage

```r
getcostsandPresolvedStatus(asscenario, feature.steps, type)
```

Arguments

- **asscenario** [ASScenario]
  Algorithm selection scenario.
- **feature.steps** [character]
  Which feature steps are allowed? Default is all steps.
- **type** [character(1)]
  Feature type (instance or algorithmic).

Value

list. Below, n is the number of instances. All following object are ordered by “instance_id”.

```r
is.presolved [logical(n)]
  Was instance presolved? Named by instance ids.
solve.steps [character(n)]
  Which step solved it? NA if no step did it. Named by instance ids.
costs [numeric(n)]
  Feature costs for using the steps. Named by instance ids. NULL if no costs are present.
```
getFeatureNames

getFeatureNames

Returns feature names of scenario.

Description

Returns feature names of scenario.

Usage

getFeatureNames(asscenario)

Arguments

asscenario [ASScenario]
   Algorithm selection scenario.

Value

character.

getDefaultFeatureStepNames

getDefaultFeatureStepNames

Returns the default feature step names of scenario.

Description

Returns the default feature step names of scenario.

Usage

getDefaultFeatureStepNames(asscenario)

Arguments

asscenario [ASScenario]
   Algorithm selection scenario.

Value

character.
**getFeatureStepNames**

Returns feature step names of scenario.

**Description**

Returns feature step names of scenario.

**Usage**

```
getFeatureStepNames(asscenario, type)
```

**Arguments**

- **asscenario** [ASScenario]
  Algorithm selection scenario.
- **type** [character(1)] Feature type (instance or algorithmic).

**Value**

character.

---

**getInstanceNames**

Returns instance names of scenario.

**Description**

Returns instance names of scenario.

**Usage**

```
getInstanceNames(asscenario)
```

**Arguments**

- **asscenario** [ASScenario]
  Algorithm selection scenario.

**Value**

character.
**getDescription**

Returns number of CV folds.

**Usage**

getNumberOfCVFolds(asscenario)

**Arguments**

  asscenario [ASScenario]
  Algorithm selection scenario.

**Value**

integer(1).

---

**getDescription**

Returns number of CV repetitions.

**Usage**

getNumberOfCVReps(asscenario)

**Arguments**

  asscenario [ASScenario]
  Algorithm selection scenario.

**Value**

integer(1).
getProvidedFeatures  
Return features that are useable for a given set of feature steps.

Description
Return features that are useable for a given set of feature steps.

Usage
getProvidedFeatures(asscenario, steps, type)

Arguments
asscenario  [ASScenario]
Algorithm selection scenario.
steps  [character]
Feature steps. Default are all feature steps.
type  [character(1)] Feature type (instance or algorithmic).

Value
character.

getSummedFeatureCosts  Returns feature costs of scenario, summed over all instances.

Description
Returns feature costs of scenario, summed over all instances.

Usage
getSummedFeatureCosts(asscenario, feature.steps)

Arguments
asscenario  [ASScenario]
Algorithm selection scenario.
feature.steps  [character]
Sum costs only for these selected steps. Default are all feature steps.

Value
character.
imputeAlgoPerf

**Imputes algorithm performance for runs which have NA performance values.**

**Description**

The following formula is used for imputation: 

\[
\text{base} \, + \, \text{range.scalar} \times \text{range.span} \, + \, N(0, \, sd = \, \text{jitter} \times \text{range.span})
\]

With \( \text{range.span} = \max - \min \).

Returns an object like `algo.runs` of `asscenario`, but drops the `runstatus` and all other measures.

**Usage**

```r
imputeAlgoPerf(
  asscenario,  
  measure,  
  base = NULL,  
  range.scalar = 0.3,  
  jitter = 0,  
  impute.zero.vals = FALSE
)
```

**Arguments**

- `asscenario` [ASScenario]
  - Algorithm selection scenario.
- `measure` [character(1)]
  - Measure to impute. Default is first measure in scenario.
- `base` [numeric(1)]
  - See formula. Default is NULL, which means maximum of performance values if measure should be minimized, or minimum for maximization case.
- `range.scalar` [numeric(1)]
  - See formula. Default is 0.3.
- `jitter` [numeric(1)]
  - See formula. Default is 0.
- `impute.zero.vals` [logical(1)]
  - Should values which are exactly 0 be imputed to 1e-6? This allows to take the logarithm later on, handy for subsequent visualizations. Note that this really only makes sense for non-negative measures! Default is FALSE.

**Value**

- `data.frame`.
parseASScenario

Parses the data files of an algorithm selection scenario into an S3 object.

Description

Object members

Let n be the number of (replicated) instances, m the number of unique instances, p the number of features, s the number of feature steps and k the number of algorithms.

desc [ASScenarioDesc ] Description object, containing further info.

feature.runstatus [data.frame(n, s + 2 ) ] Runstatus of instance feature computation steps. The first 2 columns are “instance_id” and “repetition”, the remaining are the status factors. The step columns are in the same order as the feature steps in the description object. The factor levels are always: ok, presolved, crash, timeout, memout, other. No entry can be NA. The data.frame is sorted by “instance_id”, then “repetition”.

algorithm.feature.runstatus [data.frame(k, s + 1 ) ] Runstatus of algorithm feature computation steps. The first column is “algorithm”, the remaining are the status factors. The step columns are in the same order as the feature steps in the description object. The factor levels are always: ok, crash, timeout, memout, other. No entry can be NA. The data.frame is sorted by “algorithm”.

feature.costs [data.frame(n, s + 2 ) ] Costs of instance feature computation steps. The first 2 columns are “instance_id” and “repetition”, the remaining are numeric costs of the instance feature steps. The step columns are in the same order as the feature steps in the description object. codeNA means the cost is not available, possibly because the feature computation was aborted. The data.frame is sorted by “instance_id”, then “repetition”. If no cost file is available at all, NULL is stored.

algorithm.feature.costs [data.frame(n, s + 1 ) ] Costs of algorithm feature computation steps. The first column is “algorithm”, the remaining are numeric costs of the algorithmic feature steps. The step columns are in the same order as the feature steps in the description object. codeNA means the cost is not available, possibly because the feature computation was aborted. The data.frame is sorted by “algorithm”. If no cost file is available at all, NULL is stored.

feature.values [data.frame(n, p + 2 ) ] Measured feature values of instances. The first 2 columns are “instance_id” and “repetition”. The remaining ones are the measured instance features. The feature columns are in the same order as “instance_features_deterministic”, “features_stochastic” in the description object. codeNA means the feature is not available, possibly because the feature computation was aborted. The data.frame is sorted by “instance_id”, then “repetition”.

algorithm.feature.values [data.frame(k, p + 1 ) ] Measured feature values of algorithms The first column is “algorithm”. The remaining ones are the measured algorithmic features. The feature columns are in the same order as “algorithm_features_deterministic”, “algorithm_features_stochastic” in the description object. codeNA means the feature is not available, possibly because the feature computation was aborted. The data.frame is sorted by “algorithm”.

algo.runs [data.frame ] Runstatus and performance information of the algorithms. Simply the parsed ARFF file. See convertAlgoPerfToWideFormat for a more convenient format.
### plotAlgoCorMatrix

Plots the correlation matrix of the algorithms.

**Description**

If NAs occur, they are imputed (before aggregation) by \( \text{base} + 0.3 \times \text{range} \). \text{base} is the cutoff value for runtimes scenarios with cutoff or the worst performance for all others.

Stochastic replications are aggregated by the mean value.

### Usage

`plotAlgoCorMatrix`.

### Arguments

- `algo.runstatus` [data.frame(n, k + 2)] Runstatus of algorithm runs. The first 2 columns are “instance_id” and “repetition”, the remaining are the status factors. The step columns are in the same order as the feature steps in the description object. The factor levels are always: ok, presolved, crash, timeout, memout, other. No entry can be NA. The data.frame is sorted by “instance_id”, then “repetition”.

- `cv.splits` [data.frame(m, 3)] Definition of cross-validation splits for each replication of a repeated CV with folds. Has columns “instance_id”, “repetition” and “fold”. The instances with fold = i for a replication r constitute the i-th test set for the r-th CV. The training set is the “instance_id” column with repetition = r, in the same order, when the test set is removed. The data.frame is sorted by “repetition”, then “fold”, then “instance_id”. If no CV file is available at all, NULL is stored, and a warning is issued, although this should not happen.

### Examples

```r
## Not run:
sc = parseASScenario("/path/to/scenario")
## End(Not run)
```

### See Also

- `writeASScenario`

---

### parseASScenario

**Usage**

`parseASScenario(path)`

**Arguments**

- `path` [character(1)]
  
Path to directory of benchmark data set.

**Value**

`ASScenario`. Description object.

**See Also**

- `writeASScenario`

**Examples**

```r
## Not run:
sc = parseASScenario("/path/to/scenario")
## End(Not run)
```
Usage

plotAlgoCorMatrix(
  asscenario,
  measure,
  order.method = "hclust",
  hclust.method = "ward.D2",
  cor.method = "spearman"
)

Arguments

asscenario [ASScenario]
Algorithm selection scenario.

measure [character(1)]
Measure to plot. Default is first measure in scenario.

order.method [character(1)]
Method for ordering the algorithms within the plot. Possible values are “hclust” (for hierarchical clustering order), “FPC” (first principal component order), “AOE” (angular order of eigenvectors), “original” (original order) and “alphabet” (alphabetical order). See corrMatOrder. Default is “hclust”.

hclust.method [character(1)]
Method for hierarchical clustering. Only useful, when order.method is set to “hclust”, otherwise ignored. Possible values are: “ward.D2”, “single”, “complete”, “average”, “mcquitty”, “median” and “centroid”. See corrMatOrder. Default is “ward.D2”.

cor.method [character(1)]
Method to be used for calculating the correlation between the algorithms. Possible values are “pearson”, “kendall” and “spearman”. See cor. Default is “spearman”.

Value

See corrplot.

---

plotAlgoPerf EDA plots for performance values of algorithms across all instances.

Description

If NAs occur, they are imputed (before aggregation) by base + 0.3 range + jitter. base is is the cutoff value for runtimes scenarios with cutoff or the worst performance for all others.

For the CDFs we only show the visible area where successful runs occurred.

Stochastic replications are aggregated by the mean value.
plotAlgoPerf

Usage

plotAlgoPerfBoxplots(
  asscenario, 
  measure, 
  impute.zero.vals = FALSE, 
  log = FALSE, 
  impute.failed.runs = TRUE, 
  rm.censored.runs = TRUE
)

plotAlgoPerfCDFs(
  asscenario, 
  measure, 
  impute.zero.vals = FALSE, 
  log = FALSE, 
  rm.censored.runs = TRUE
)

plotAlgoPerfDensities(
  asscenario, 
  measure, 
  impute.failed.runs = TRUE, 
  impute.zero.vals = FALSE, 
  log = FALSE, 
  rm.censored.runs = TRUE
)

plotAlgoPerfScatterMatrix(
  asscenario, 
  measure, 
  impute.zero.vals = FALSE, 
  log = FALSE, 
  rm.censored.runs = TRUE
)

Arguments

asscenario  [ASSScenario]
Algorithm selection scenario.

measure      [character(1)]
Measure to plot. Default is first measure in scenario.

impute.zero.vals  [logical(1)]
Should values which are exactly 0 be imputed to 1e-6? This allows to take the 
logarithm later on, handy for subsequent visualizations. Note that this really 
only makes sense for non-negative measures! Default is FALSE.

log  [logical(1)]
runLlamaModels

Should the performance values be log10-transformed in the plot? Default is FALSE.

impute.failed.runs

[logical(1)]

Should runtimes for failed runs be imputed? Default is TRUE.

rm.censored.runs

[logical(1)]

Should runtimes for censored runs (i.e., runs that have hit the walltime) be removed (and eventually be imputed along with the remaining NAs)? Default is TRUE.

Value

ggplot2 plot object.

runLlamaModels

Creates a registry which can be used for running several Llama models on a cluster.

Description

It is likely that you need to install some additional R packages for this from CRAN or extra Weka learner. The latter can be done via e.g. WPM("install-package", "XMeans").

Feature costs are added for real prognostic models but not for baseline models.

Usage

runLlamaModels(
  asscenarios,
  feature.steps.list = NULL,
  baselines = NULL,
  learners = list(),
  par.sets = list(),
  rs.iters = 100L,
  n.inner.folds = 2L
)

Arguments

asscenarios     [(list of) ASScenario]

Algorithm selection scenarios.

feature.steps.list

[list of character]

Named list of feature steps we want to use. Must be named with scenario ids. Default is to take the default feature steps from the scenario.
summarizeAlgoPerf

Arguments

baselines [character]
Vector of characters, defining the baseline models. Default is c("vbs", "singleBest","singleBestByPar", "singleBestBySuccesses").

learners [list of Learner]
mml learners to use for modeling. Default is none.

par.sets [list of ParamSet]
Param sets for learners to tune via random search. Pass an empty param set, if you want no tuning. Must be in of same length as learners and in the same order. Default is none.

rs.iters [integer(1)]
Number of iterations for random search hyperparameter tuning. Default is 100.

n.inner.folds [integer(1)]
Number of cross-validation folds for inner CV in hyperparameter tuning. Default is 2L.

Value

batchtools registry.

summarizeAlgoPerf Creates summary data.frame for algorithm performance values across all instances.

Description

Creates summary data.frame for algorithm performance values across all instances.

Usage

summarizeAlgoPerf(asscenario, measure)

Arguments

asscenario [ASScenario]
Algorithm selection scenario.

measure [character(1)]
Selected measure. Default is first measure in scenario.

Value

data.frame .
summarizeAlgoRunstatus

Creates summary data.frame for algorithm runstatus across all instances.

Description

Creates summary data.frame for algorithm runstatus across all instances.

Usage

summarizeAlgoRunstatus(asscenario)

Arguments

asscenario [ASScenario]
Algorithm selection scenario.

Value

data.frame .

summarizeFeatureSteps

Creates a data.frame that summarizes the feature steps.

Description

Creates a data.frame that summarizes the feature steps.

Usage

summarizeFeatureSteps(asscenario)

Arguments

asscenario [ASScenario]
Algorithm selection scenario.

Value

data.frame .
summarizeFeatureValues

*Create* summary data.frame for feature values across all instances.

**Description**

Creates summary data.frame for feature values across all instances.

**Usage**

```r
summarizeFeatureValues(asscenario, type)
```

**Arguments**

- `asscenario` - [ASScenario](#)
  
  Algorithm selection scenario.

- `type` - [character(1)]
  
  Feature type (instance or algorithmic).

**Value**

data.frame.

---

summarizeLlamaExps

*Create* summary data.table for runLlamaModel experiments.

**Description**

Creates summary data.table for runLlamaModel experiments.

**Usage**

```r
summarizeLlamaExps(
    reg,
    ids = findSubmitted(),
    fun = function(job, res) {
      return(list(succ = res$succ, par10 = res$par10, mcp = res$mcp))
    },
    missing.val = list(succ = 0, par10 = Inf, mcp = Inf)
  )
```
writeASScenario

Arguments

reg [Registry]  
batchtools registry.

ids [data.table]  
Selected job ids. Default is all submitted jobs.

fun [function()]  
Function to aggregate results with. Default is a function that returns succ, par10 and mcp values. For a detailed description, see [reduceResultsList].

missing.val [list(1)]  
List with defaults for missing values that are needed for aggregation. For a detailed description, see [reduceResultsList].

Value

data.table.

writeASScenario  Writes an algorithm selection scenario to a directory.

Description

Splits an algorithm selection scenario into description, feature values / runstatus / costs, algorithm performance and cv splits and saves those data sets as single ARFF files in the given directory.

Usage

writeASScenario(asscenario, path = asscenario$desc$scenario_id)

Arguments

asscenario [ASScenario]  
Algorithm selection scenario.

path [character(1)]  
Path to write scenario to. Default is the name of the scenario.

See Also

parseASScenario
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