Package ‘dma’

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dma-package ......................................................... 1
dma ................................................................. 2
logistic.dma .......................................................... 4

Index 8

<table>
<thead>
<tr>
<th>dma-package</th>
<th>Dynamic model averaging</th>
</tr>
</thead>
</table>

Description

This package implements dynamic Bayesian model averaging as described for continuous outcomes in Raftery et al. (2010, Technometrics) and for binary outcomes in McCormick et al. (2011, Biometrics).
Details

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Author(s)

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References


Description

Implement dynamic model averaging for continuous outcomes as described in Raftery, A.E., Kurny, M., and Ettler, P. (2010). Online Prediction Under Model Uncertainty Via Dynamic Model Averaging: Application to a Cold Rolling Mill. Technometrics 52:52-66. Along with the values described below, plot() creates a plot of the posterior model probabilities over time and model-averaged fitted values and print() returns model matrix and posterior model probabilities. There are TT time points, K models, and d total covariates.

Usage

dma(x, y, models.which, lambda=0.99, gamma=0.99, eps=.001/nrow(models.which), delay=0, initialperiod=200)
Arguments

\textbf{Arguments}

\begin{itemize}
\item \texttt{x} \quad TT\text{x}d \text{ matrix of system inputs}
\item \texttt{y} \quad TT\text{-vector of system outputs}
\item \texttt{models\.which} \quad K\text{x}d \text{ matrix, with 1 row per model and 1 col per variable indicating whether that variable is in the model (the state theta is of dim (model\.dim+1); the extra 1 for the intercept)}
\item \texttt{lambda} \quad parameter forgetting factor
\item \texttt{gamma} \quad flatterning parameter for model updating
\item \texttt{eps} \quad regularization parameter for regularizing posterior model model probabilities away from zero
\item \texttt{delay} \quad When \texttt{y} \_\texttt{t} is controlled, only \texttt{y} \_\texttt{t-delay-1} and before are available. This is determined by the machine. Note that delay as defined here corresponds to (k-1) in the Ettler et al (2007, MixSim) paper. Thus k=25 in the paper corresponds to delay=24.
\item \texttt{initialperiod} \quad length of initial period. Performance is summarized with and without the first initialperiod samples.
\end{itemize}

Value

\begin{itemize}
\item \texttt{yhat\.bymodel} \quad TT\text{x}K \text{ matrix whose tk element gives yhat for yt for model k}
\item \texttt{yhat\.ma} \quad TT \text{ vector whose t element gives the model-averaged yhat for yt}
\item \texttt{pmp} \quad TT\text{x}K \text{ matrix whose tk element is the post prob of model k at t}
\item \texttt{thetahat} \quad K\text{x}TT\text{x}(nvar+1) \text{ array whose ktj element is the estimate of theta\_j-1 for model k at t}
\item \texttt{Vtheta} \quad K\text{x}TT\text{x}(nvar+1) \text{ array whose ktj element is the variance of theta\_j-1 for model k at t}
\item \texttt{thetahat\.ma} \quad TT\text{x}(nvar+1) \text{ matrix whose tj element is the model-averaged estimate of theta\_j-1 at t}
\item \texttt{Vtheta\.ma} \quad TT\text{x}(nvar+1) \text{ matrix whose tj element is the model-averaged variance of thetahat\_j-1 at t}
\item \texttt{mse\.bymodel} \quad MSE for each model
\item \texttt{mse\.ma} \quad MSE of model-averaged prediction
\item \texttt{mse\_initialperiod\.bymodel} \quad MSE for each model excluding the first initialperiod samples
\item \texttt{mse\_initialperiod\.ma} \quad MSE of model averaging excluding the first initialperiod samples
\item \texttt{model\.forget} \quad forgetting factor for the model switching matrix
\end{itemize}

Author(s)

Adrian Raftery, Tyler H. McCormick
logistic.dma

Dynamic model averaging for binary outcomes

Description

Implements dynamic model averaging for continuous outcomes as described in McCormick et al.
(2011, Biometrics). It can be either performed for all data at once (using logistic.dma), or
dynamically for one observation at a time (combining the remaining functions, see Example). Along
with the values described below, plot() creates a plot of the posterior model probabilities over time
and model-averaged fitted values (with smooth curve overlay) and print() returns model matrix and
posterior model probabilities. There are K candidate models, T time points, and d total covariates
(including the intercept).

Usage

logistic.dma(x, y, models.which, lambda = 0.99, alpha = 0.99, autotune = TRUE,
    initmodelprobs = NULL, initialsamp = NULL)

logdma.init(x, y, models.which)

logdma.predict(fit, newx)

logdma.update(fit, newx, newy, lambda = 0.99, autotune = TRUE)
logdma.average(fit, alpha = 0.99, initmodelprobs = NULL)

Arguments

- **x**: T by (d-1) matrix of observed covariates. Note that a column of 1’s is added automatically for the intercept. In `logdma.init`, this matrix contains only the training set.
- **y**: T vector of binary responses. In `logdma.init`, these correspond to the training set only.
- **models.which**: K by (d-1) matrix defining models. A 1 indicates a covariate is included in a particular model, a 0 if it is excluded. Model averaging is done over all models specified in `models.which`.
- **lambda**: scalar forgetting factor with each model
- **alpha**: scalar forgetting factor for model averaging
- **autotune**: T/F indicates whether or not the automatic tuning procedure described in McCormick et al. should be applied. Default is true.
- **initmodelprobs**: K vector of starting probabilities for model averaging. If null (default), then use 1/K for each model.
- **initialsamp**: scalar indicating how many observations to use for generating initial values. If null (default), then use the first 10 percent of observations.
- **newx, newy**: Subset of `x` and `y` corresponding to new observations.
- **fit**: List with estimation results that are outputs of functions `logdma.init`, `logdma.update` and `logdma.average`.

Details

The function `logistic.dma` is composed of three parts, which can be also used separately: First, the model is trained with a subset of the data (function `logdma.init`), where the size of the training set is determined by `initialsamp`. Note that arguments `x` and `y` in `logdma.init` should contain the training subset only. Then, the estimation is updated with new observations (function `logdma.update`). Lastly, a dynamic model averaging is performed on the final estimates (function `logdma.average`). The updating, averaging and in addition predicting (`logdma.predict`) can be performed dynamically for one observation at a time, see Example below.

Value

Functions `logistic.dma` and `logdma.average` return an object of class `logistic.dma`. Functions `logdma.init` and `logdma.update` return a list with estimation results which is a subset of the `logistic.dma` object. It has the following components:

- **x**: T by (d-1) matrix of covariates
- **y**: T by 1 vector of binary responses
- **models.which**: K by (d-1) matrix of candidate models
- **lambda**: scalar, tuning factor within models
alpha scalar, tuning factor for model averaging
autotune T/F, indicator of whether or not to use autotuning algorithm
alpha.used T vector of alpha values used
theta K by T by d array of dynamic logistic regression estimates for each model
vartheta K by T by d array of dynamic logistic regression variances for each model
pmp K by T array of posterior model probabilities
yhatdma T vector of model-averaged predictions
yhatmodel K by T vector of fitted values for each model

Function logdma.predict returns a matrix with predictions corresponding to the newx covariates.

Author(s)

Tyler H. McCormick, David Madigan, Adrian Raftery
Sevvandi Kandanaarachchi and Hana Sevcikova implemented the “streaming” functionality, i.e. the original function was decomposed into standalone parts that can be used separately for one observation at a time.

References


Examples

# simulate some data to test
# first, static coefficients
coeff <- c(.08, -.4, -.1)
coeffmat <- cbind(rep(coef[1], 200), rep(coef[2], 200), rep(coef[3], 200))

# then, dynamic ones
coeffmat <- cbind(coefmat, seq(1, .45, length.out = nrow(coefmat)),
                 seq(-.75, -.15, length.out = nrow(coefmat)),
                 c(rep(-1.5, nrow(coefmat)/2), rep(-.5, nrow(coefmat)/2)))
npar <- ncol(coeffmat)-1

# simulate data
set.seed(1234)
dat <- matrix(rnorm(200*npar, 0, 1), 200, (npar))
ydat <- exp(rowSums(cbind(rep(1, nrow(dat)), dat)[1:100,]*coeffmat[1:100,]))/(1+exp(rowSums(cbind(rep(1, nrow(dat)), dat)[1:100,]*coeffmat[1:100,])))
y <- c(ydat, exp(rowSums(cbind(rep(1, nrow(dat)), dat)[-c(1:100), c(1, 5, 6)]*coeffmat[-c(1:100), c(1, 5, 6)]))/(1+exp(rowSums(cbind(rep(1, nrow(dat)), dat)[-c(1:100), c(1, 5, 6)]*coeffmat[-c(1:100), c(1, 5, 6)])))
u <- runif(length(y))
y <- as.numeric(u < y)

# Consider three candidate models
mmat <- matrix(c(1, 1, 1, 1, 0, 0, 0, 1, 1, 0, 1, 0, 1, 1, 0, 1, 0, 1, 0, 1, 0, 1), 3, 5, byrow = TRUE)
# Fit model and plot
# autotuning is turned off for this demonstration example
lda.test <- logistic.dma(dat, y, mmat, lambda = .99, alpha = .99, 
                      autotune = FALSE, initialsamp = 20)
plot(lda.test)

# Using DMA in a "streaming" mode
modl <- logdma.init(dat[1:20,], y[1:20], mmat)
yhat <- matrix(0, ncol=3, nrow=200)
for(i in 21:200){
  # if prediction is desired, use logdma.predict
  yhat[i,] <- logdma.predict(modl, dat[i,])
  # update
  modl <- logdma.update(modl, dat[i,], y[i],
                         lambda = .99, autotune = FALSE)
}
# the averaging step could be also done within the loop above
lda.stream <- logdma.average(modl, alpha = .99)
plot(lda.stream)
Index

* dma
  dma-package, 1

coef.dma(dma), 2

dlogr.init(logistic.dma), 4
dlogr.predict(logistic.dma), 4
dlogr.step(logistic.dma), 4
dma, 2
dma-package, 1

laplace.fn(logistic.dma), 4
logdma.average(logistic.dma), 4
logdma.init(logistic.dma), 4
logdma.predict(logistic.dma), 4
logdma.update(logistic.dma), 4
logistic.dma, 4

makf4(dma), 2
model.update3(dma), 2

plot.dma(dma), 2
plot.logistic.dma(logistic.dma), 4
print.dma(dma), 2
print.logistic.dma(logistic.dma), 4

rm.Kalman(dma), 2

tunemat.fn(logistic.dma), 4