

Package ‘dynamichazard’

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Type Package

Title Dynamic Hazard Models using State Space Models

Version 0.3.5

Description Contains functions that lets you fit dynamic hazard models with binary outcomes using state space models. The methods are originally described in Fahrmeir (1992) <doi:10.1080/01621459.1992.10475232> and Fahrmeir (1994) <doi:10.1093/biomet/81.2.317>. The functions also provide an extension hereof where the Extended Kalman filter is replaced by an Unscented Kalman filter. Models are fitted with the regular coxph() like formula.

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R topics documented:

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| | |
|---------|--|
| ddFixed | <i>Auxiliary functions for fixed effects</i> |
|---------|--|

Description

Functions used in formula of [ddhazard](#) for time-invariant effects. ddFixed_intercept is only used for the intercept.

Usage

```
ddFixed(object)

ddFixed_intercept(n)
```

Arguments

| | |
|--------|---|
| object | Expression that would be used in formula. E.g. x or poly(x, degree = 3) |
| n | Number of rows in the data frame the data for estimation |

Examples

```
# All these call with give the same result where
# 'data' is a hypothetical data frame. We can get a
# time-invariant estimate for x1 by:
## Not run:
ddhazard(Surv(stop, event) ~ ddFixed(x1), data)

## End(Not run)
```

```
# All of the calls below will yield the same result
# with a time-invariant intercept:
## Not run:
ddhazard(Surv(stop, event)
  ~ ddFixed(1) + x1, data)
ddhazard(Surv(stop, event)
  ~ -1 + ddFixed(1) + x1, data)
ddhazard(Surv(stop, event)
  ~ ddFixed(rep(1, nrow(data))) + x1, data)
ddhazard(Surv(stop, event)
  ~ -1 + ddFixed(rep(1, nrow(data))) + x1, data)
ddhazard(Surv(stop, event)
  ~ ddFixed_intercept(nrow(data)) + x1, data)
ddhazard(Surv(stop, event)
  ~ -1 + ddFixed_intercept(nrow(data)) + x1, data)

## End(Not run)
```

ddhazard

*Function to fit dynamic discrete hazard models***Description**

Function to fit dynamic discrete hazard models using state space models

Usage

```
ddhazard(formula, data, model = "logit", by, max_T, id, a_0, Q_0, Q = Q_0,
  order = 1, weights, control = list(), verbose = F)
```

Arguments

| | |
|---------|--|
| formula | coxph like formula with Surv (tstart, tstop, event) on the left hand site of ~ |
| data | Data frame or environment containing the outcome and co-variables |
| model | "logit", "exp_clip_time_w_jump", "exp_clip_time" or "exp_bin" for the discrete time function using the logistic link function in the first case or for the continuous time model with different estimation method in the three latter cases (see the ddhazard vignette for details of the methods) |
| by | Interval length of the bins in which parameters are fixed |
| max_T | End of the last interval. The last stop time with an event is selected if the parameter is omitted |
| id | Vector of ids for each row of the in the design matrix |
| a_0 | Vector a_0 for the initial coefficient vector for the first iteration (optional). Default is estimates from static model (see static_glm) |
| Q_0 | Covariance matrix for the prior distribution |

| | |
|---------|---|
| Q | Initial covariance matrix for the state equation |
| order | Order of the random walk |
| weights | Weights to use if e.g. a skewed sample is used |
| control | List of control variables (see details below) |
| verbose | TRUE if you want status messages during execution |

Details

This function can be used to estimate a binary regression where the regression parameters follows a given order random walk. The order is specified by the `order` argument. 1. and 2. order random walks is implemented. The regression parameters are updated at time by, 2by, ..., max_T. See the vignette 'ddhazard' for more details

All filter methods needs a state covariance matrix Q_0 and state vector a_0 . An estimate from a time-invariant model is provided for a_0 if it is not supplied (the same model you would get from [static_glm](#) function). A diagonal matrix with large entries is recommended for Q_0 . What is large depends on the data set and model. Further, a variance matrix for the first iteration Q is needed. It is recommended to select diagonal matrix with low values for the latter. The Q , a_0 and optionally Q_0 is estimated with an EM-algorithm

The model is specified through the `model` argument. See the `model` in the argument above for details. The logistic model is where outcomes are binned into the intervals. Be aware that there can be loss of information due to binning. It is key for the logit model that the `id` argument is provided if individuals in the data set have time varying co-variables. The the exponential models use an exponential model for the arrival times where there is no loss information due to binning

It is recommended to see the Shiny app demo for this function by calling [ddhazard_app\(\)](#)

Value

A list with class `fahrmeier_94`. The list contains:

`formula` The passed formula

`call` The matched call

`state_vecs` 2D matrix with the estimated state vectors (regression parameters) in each bin

`state_vars` 3D array with smoothed variance estimates for each state vector

`lag_one_cov` 3D array with lagged correlation matrix for each for each change in the state vector.

Only present when the model is logit and the method is EKF

`n_risk` The number of observations in each interval

`times` The interval borders

`risk_set` The object from [get_risk_obj](#) if saved

`data` The data argument if saved

`id` ids used to match rows in data to individuals

`order` Order of the random walk

`F_` Matrix with that map transition from one state vector to the next

`method` Method used in the E-step

est_Q_0 TRUE if Q_0 was estimated in the EM-algorithm
 hazard_func Hazard function
 hazard_first_deriv First derivative of the hazard function with respect to the linear predictor

Control

The control argument allows you to pass a list to select additional parameters. See the vignette 'ddhazard' for more information on hyper parameters. Unspecified elements of the list will yield default values

method Set to the method to use in the E-step. Either "EKF" for the Extended Kalman Filter, "UKF" for the Unscented Kalman Filter, "SMA" for the sequential posterior mode approximation method or "GMA" for the global mode approximation method. "EKF" is the default

LR Learning rate for the Extended Kalman filter

NR_eps Tolerance for the Extended Kalman filter. Default is NULL which means that no extra iteration is made in the correction step

alpha Hyper parameter α in the Unscented Kalman Filter

beta Hyper parameter β in the Unscented Kalman Filter

kappa Hyper parameter κ in the Unscented Kalman Filter

n_max Maximum number of iteration in the EM-algorithm

eps Tolerance parameter for the EM-algorithm

est_Q_0 TRUE if you want the EM-algorithm to estimate Q_0. Default is FALSE

save_risk_set TRUE if you want to save the list from `get_risk_obj` used to estimate the model. It may be needed for later call to residuals, plot and logLike. Can be set to FALSE to save memory

save_data TRUE if you want to save the list data argument. It may be needed for later call to residuals, plot and logLike. Can be set to FALSE to save memory

denom_term Term added to denominators in either the EKF or UKF

fixed_parems_start Starting value for fixed terms

fixed_terms_method The method used to estimate the fixed effects. Either 'M_step' or 'E_step' for estimation in the M-step or E-step respectively

Q_0_term_for_fixed_E_step The diagonal value of the initial covariance matrix, Q_0, for the fixed effects if fixed effects are estimated in the E-step

eps_fixed_parems Tolerance used in the M-step of the Fisher's Scoring Algorithm for the fixed effects

permu TRUE if the risk sets should be permuted before computation. This is TRUE by default for posterior mode approximation method and FALSE for all other methods

posterior_version The implementation version of the posterior approximation method. Either "woodbury" or "cholesky"

GMA_max_rep Maximum number of iterations in the correction step if method = 'GMA'

GMA_NR_eps Tolerance for the convergence criteria for the relative change in the norm of the coefficients in the correction step if method = 'GMA'

References

Fahrmeir, Ludwig. *Dynamic modelling and penalized likelihood estimation for discrete time survival data*. Biometrika 81.2 (1994): 317-330.

Durbin, James, and Siem Jan Koopman. *Time series analysis by state space methods*. No. 38. Oxford University Press, 2012.

See Also

[plot](#), [residuals](#), [predict](#), [static_glm](#), [ddhazard_app](#), [ddhazard_boot](#)

ddhazard_app

ddhazard demo

Description

ddhazard_app runs a shiny app with demonstration of models

Usage

```
ddhazard_app(quietly = F, ...)
```

Arguments

| | |
|---------|---|
| quietly | TRUE if no messages should be printed when the app is run |
| ... | Starting values for the shiny app |

Details

Runs a shiny app where you try different model specifications on simulated data

Examples

```
## Not run:
dynamichazard::ddhazard_app()
dynamichazard::ddhazard_app(seed = 1, more_options = TRUE)

## End(Not run)
```

| | |
|---------------|---|
| ddhazard_boot | <i>Bootstrap for ddhazard</i> |
|---------------|---|

Description

See the vignette 'Bootstrap illustration'. The `do_stratify_with_event` may be useful when either cases or non-cases are very rare to ensure that the model estimation succeeds.

Usage

```
ddhazard_boot(ddhazard_fit, strata, unique_id, R = 100,  
  do_stratify_with_event = F, do_sample_weights = F,  
  LRs = ddhazard_fit$control$LR * 2^(0:(-4)), print_errors = F)
```

Arguments

| | |
|-------------------------------------|--|
| <code>ddhazard_fit</code> | Returned object from a ddhazard call |
| <code>strata</code> | Strata to sample within. These need to be on an individual by individual basis and not rows in the design matrix |
| <code>unique_id</code> | Unique ids where entries match entries of <code>strata</code> |
| <code>R</code> | Number of bootstrap estimates |
| <code>do_stratify_with_event</code> | TRUE if sampling should be by strata of whether the individual has an event. An interaction factor will be made if <code>strata</code> is provided |
| <code>do_sample_weights</code> | TRUE if weights should be sample instead of individuals |
| <code>LRs</code> | Learning rates in decreasing order which will be used to estimate the model. |
| <code>print_errors</code> | TRUE if errors should be printed when estimations fails |

Value

An object like returned from the [boot](#) function

See Also

[ddhazard](#), [plot](#)

get_risk_obj

Get the risk set at each bin over an equal distance grid

Description

Get the risk set at each bin over an equal distance grid

Usage

```
get_risk_obj(Y, by, max_T, id, is_for_discrete_model = T, n_threads = 1,
             min_chunk = 5000)
```

Arguments

| | |
|-----------------------|---|
| Y | Vector of outcome variable |
| by | Length of each bin |
| max_T | Last observed time |
| id | Vector with ids where entries match with outcomes Y |
| is_for_discrete_model | TRUE/FALSE for whether the model outcome is discrete. For example, a logit model is discrete whereas what is coined an exponential model in this package is a dynamic model |
| n_threads | Set to a value greater than one to use mclapply to find the risk object |
| min_chunk | Minimum chunk size of ids to use when parallel version is used. |

Value

A list with the following elements:

- risk_sets** List of lists with one for each bin. Each of the sub lists have indices that corresponds to the entries of Y that are at risk in the bin
- min_start** Start time of the first bin
- I_len** Length of each bin
- d** Number of bins
- is_event_in** Indices for which bin an observation Y is an event. -1 if the individual does not die in any of the bins
- is_for_discrete_model** Value of is_for_discrete_model argument

get_survival_case_weights_and_data

Static GLM fit for survival models

Description

Function used to get design matrix and weights for a static fit for survivals models where observations are binned into intervals

Usage

```
get_survival_case_weights_and_data(formula, data, by, max_T, id, init_weights,
  risk_obj, use_weights = T, is_for_discrete_model = T, c_outcome = "Y",
  c_weights = "weights", c_end_t = "t")
```

Arguments

| | |
|-------------------------------|---|
| formula | coxph like formula with Surv (tstart, tstop, event) on the left hand site of ~ |
| data | Data frame or environment containing the outcome and co-variates |
| by | Length of each intervals that cases are binned into |
| max_T | The end time of the last bin |
| id | The id for each row in data. This is important when variables are time varying |
| init_weights | Weights for the rows data. Useful with skewed sampling and will be used when computing the final weights |
| risk_obj | A pre-computed result from a get_risk_obj . Will be used to skip some computations |
| use_weights | TRUE if weights should be used. See details |
| is_for_discrete_model | TRUE if the model is for a discrete hazard model like the logistic model. Affects how deaths are included when individuals have time varying coefficients |
| c_outcome, c_weights, c_end_t | Alternative names to use for the added columns described in the return section. Useful if you already have a column named Y, t or weights |

Details

This function is used to get the data frame for e.g. a glm fit that is comparable to a [ddhazard](#) fit in the sense that it is a static version. For example, say that we bin our time periods into (0,1], (1,2] and (2,3]. Next, consider an individual who dies at time 2.5. He should be a control in the the first two bins and should be a case in the last bin. Thus the rows in the final data frame for this individual is c(Y = 1, ..., weights = 1) and c(Y = 0, ..., weights = 2) where Y is the outcome, ... is the co-variates and weights is the weights for the regression. Consider another individual who does not die and we observe him for all three periods. Thus, he will yield one row with c(Y = 0, ..., weights = 3)

This function use similar logic as the `ddhazard` for individuals with time varying co-variates (see the vignette "ddhazard" for details)

If `use_weights = FALSE` then the two individuals will yield three rows each. The first individual will have `c(Y = 0, t = 1, ..., weights = 1)`, `c(Y = 0, t = 2, ..., weights = 1)`, `c(Y = 1, t = 3, ..., weights = 1)` while the latter will have three rows `c(Y = 0, t = 1, ..., weights = 1)`, `c(Y = 0, t = 2, ..., weights = 1)`, `c(Y = 0, t = 3, ..., weights = 1)`. This kind of data frame is useful if you want to make a fit with e.g. `gam` function in the `mgcv` package as described en Tutz et. al (2016) (see reference)

Value

Returns a data frame with the design matrix from the formula where the following is added (column names will differ if you specified them): column `Y` for the binary outcome, column `weights` for weights of each row and additional rows if applicable. A column `t` is added for the stop time of the bin if `use_weights = FALSE`

References

Tutz, Gerhard, and Matthias Schmid. *Nonparametric Modeling and Smooth Effects*. Modeling Discrete Time-to-Event Data. Springer International Publishing, 2016. 105-127.

See Also

`ddhazard`, `static_glm`

hatvalues.fahrmeier_94

Hat values for `ddhazard`

Description

Computes hat-"like" values from usual L2 penalized binary regression

Usage

```
## S3 method for class 'fahrmeier_94'
hatvalues(model, ...)
```

Arguments

| | |
|--------------------|----------------------------------|
| <code>model</code> | A fit from <code>ddhazard</code> |
| <code>...</code> | Not used |

Details

Computes hat-"like" values in each interval for each individual at risk in the interval. See the `ddhazard` vignette for details

Value

A list of matrices. Each matrix has three columns: the hat values, the row number of the original data point and the id the row belongs to

See Also

[ddhazard](#)

`model.frame.ddformula` *model.frame* and *model.matrix* for *ddformula*

Description

Functions added to handle fixed (time-invariant) intercept coefficient for [ddhazard](#). `model.frame.ddformula` always has `drop.unused.levels = FALSE` regardless of the input.

Usage

```
## S3 method for class 'ddformula'
model.frame(formula, data = NULL, subset = NULL,
  na.action = na.fail, xlev = NULL, ...)

## S3 method for class 'ddformula'
model.matrix(object, data = environment(object),
  contrasts.arg = NULL, xlev = NULL, ...)
```

Arguments

| | |
|----------------------------|--|
| <code>formula</code> | Same as model.frame.default |
| <code>data</code> | Same as model.matrix.default |
| <code>subset</code> | Same as model.frame.default |
| <code>na.action</code> | Same as model.frame.default |
| <code>xlev</code> | Same as model.frame.default |
| <code>...</code> | Unused |
| <code>object</code> | Same as model.matrix.default |
| <code>contrasts.arg</code> | Same as model.matrix.default |

plot.fahrmeier_94 *Plots for [ddhazard](#)*

Description

Plot to illustrate the estimate state space variables from a [ddhazard](#) fit

Usage

```
## S3 method for class 'fahrmeier_94'
plot(x, xlab = "Time", ylab = "Hazard",
     type = "cov", plot_type = "l", cov_index, ylim, col = "black",
     add = F, do_alter_mfcol = T, level = 0.95, ddhazard_boot, ...)
```

Arguments

| | |
|-----------------------|--|
| x | Result of ddhazard call |
| xlab, ylab, ylim, col | Arguments to override defaults set in the function |
| type | Type of plot. Currently, only "cov" is available for plot of the state space parameters |
| plot_type | The type argument passed to plot |
| cov_index | The index (indices) of the state space parameter(s) to plot |
| add | FALSE if you want to make a new plot |
| do_alter_mfcol | TRUE if the function should alter par(mfcol) in case that cov_index has more than one element |
| level | Level (fraction) for confidence bounds |
| ddhazard_boot | Object from a ddhazard_boot call which confidence bounds will be based on and where bootstrap samples will be printed with a transparent color |
| ... | Arguments passed to plot or lines depending on the value of add |

Details

Creates a plot of state variables or adds state variables to a plot with indices cov_index. Pointwise 1.96 std. confidence intervals are provided with the smoothed co-variance matrices from the fit

```
plot.fahrmeier_94_SpaceErrors
```

State space error plot

Description

Plot function for state space errors from [ddhazard](#) fit

Usage

```
## S3 method for class 'fahrmeier_94_SpaceErrors'
plot(x, mod, cov_index = NA,
     t_index = NA, p_cex = par()$cex * 0.2, pch = 16,
     ylab = "Std. state space error", x_tick_loc = NA, x_tick_mark = NA,
     xlab = "Time", ...)
```

Arguments

| | |
|-------------------------|--|
| x | Result of residuals for state space errors |
| mod | The ddhazard result used in the residuals call |
| cov_index | The indices of state vector errors to plot. Default is to use all which is likely what you want if the state space errors are standardized |
| t_index | The bin indices to plot. Default is to use all bins |
| p_cex | cex argument for the points |
| pch, ylab, xlab | Arguments to override defaults set in the function |
| x_tick_loc, x_tick_mark | at and labels arguments passed to axis |
| ... | Arguments passed to plot |

```
predict.fahrmeier_94
```

Predict function for the result of [ddhazard](#)

Description

Predict function for the result of [ddhazard](#)

Usage

```
## S3 method for class 'fahrmeier_94'
predict(object, new_data, type = c("response", "term"),
       tstart = "start", tstop = "stop", use_parallel = F, sds = F,
       max_threads = getOption("ddhazard_max_threads"), ...)
```

Arguments

| | |
|---------------------------|--|
| <code>object</code> | Result of a ddhazard call |
| <code>new_data</code> | New data to base predictions on |
| <code>type</code> | Either "response" for predicted probability of death or "term" for predicted terms in the linear predictor |
| <code>tstart</code> | Name of the start time column in <code>new_data</code> . It must corresponds to <code>tstart</code> used in the Surv(tstart, tstop, event) in the formula passed to ddhazard |
| <code>tstop</code> | same as <code>tstart</code> for the stop argument |
| <code>use_parallel</code> | TRUE if computation for <code>type = "response"</code> should be computed in parallel with the <code>parallel</code> package |
| <code>sds</code> | TRUE if point wise standard deviation should be computed. Convenient if you use functions like ns and you only want one term per term in the right hand site of the formula used in ddhazard |
| <code>max_threads</code> | Maximum number of threads to use. -1 if it should be determined by a call to detectCores |
| <code>...</code> | Not used |

Term

The result of `type = "term"` is a list with the following elements

`terms` Is a 3D array. The first dimension is the number of bins, the second dimension is rows in `new_data` and the last dimension is the state space terms

`sds` Similar to `terms` for the point wise confidence intervals using the smoothed co-variance matrices

`fixed_terms` Vector of the fixed effect terms for each observation

Response

The result of `type = "response"` is a list with the elements below. The function check if there are columns in `new_data` which's names match `tstart` and `tstop`. If not, then each row in new data will get a predicted probability of dying in every bin.

`fits` Fitted probability of dying

`istart` Vector with the index of the first bin the elements in `fits` is in

`istop` Vector with the index of the last bin the elements in `fits` is in

```
print.ddhazard_boot
```

Summary statistics for a ddhazard_boot object

Description

Arguments have the same effects as for an object from a [boot](#) call. See [print](#)

Usage

```
## S3 method for class 'ddhazard_boot'
print(x, digits = getOption("digits"),
      index = 1L:ncol(boot.out$t), ...)
```

Arguments

| | |
|--------|---|
| x | Returned object from a ddhazard_boot call |
| digits | The number of digits to be printed in the summary statistics |
| index | Indices indicating for which elements of the bootstrap output summary statistics are required |
| ... | Not used |

See Also

[ddhazard_boot](#)

```
print.fahrmeier_94
```

Print function for ddhazard result

Description

The sd printed for time-varying effects are point-wise standard deviations from either the filter with smoothing

Usage

```
## S3 method for class 'fahrmeier_94'
print(x, var_indices = 1:ncol(x$state_vecs),
      time_indices = 1:nrow(x$state_vecs), digits = getOption("digits"), ...)
```

Arguments

| | |
|--------------|--|
| x | Object returned from ddhazard |
| var_indices | Variable indices to print for time-varying effects |
| time_indices | Time intervals to print for time-varying effects |
| digits | Number of digits to print |
| ... | Not used |

residuals.fahrmeier_94

Residuals for [ddhazard](#)

Description

Residuals function for the result of a [ddhazard](#) fit

Usage

```
## S3 method for class 'fahrmeier_94'
residuals(object, type = c("std_space_error",
  "space_error", "pearson", "raw"), data = NULL, ...)
```

Arguments

| | |
|--------|--|
| object | Result of ddhazard call |
| type | Type of residuals. Four possible values: "std_space_error", "space_error", "pearson" and "raw". See the sections below for details |
| data | Data frame with data for Pearson or raw residuals |
| ... | Not used |

Pearson and raw residuals

Is the result of a call with a type argument of either "pearson" or "raw" for Pearson residuals or raw residuals. Returns a list with class "fahrmeier_94_res" with the following elements

residuals List of residuals for each bin. Each element of the list contains a 2D array where the rows corresponds to the passed data and columns are the residuals (residuals), estimated probability of death (p_est), outcome (Y) and row number in the initial dataset (row_num). The data rows will only have a residuals in a given risk list if they are at risk in that risk set

type The type of residual

State space errors

Is the result of a call with a type argument of either "std_space_error" or "space_error". The former is for standardized residuals while the latter is non-standardized. Returns a list with class "fahrmeier_94_SpaceErrors" with the following elements

residuals 2D array with either standardized or non-standardized state space errors. The row are bins and the columns are the parameters in the regression

standardize TRUE if standardized state space errors

Covariances 3D array with the smoothed co-variance matrix for each set of the state space errors

| | |
|------------|--|
| static_glm | <i>Function to make a static glm fit</i> |
|------------|--|

Description

Function to make a static glm fit

Usage

```
static_glm(formula, data, by, max_T, ..., id, family = "logit", model = F,
           weights, risk_obj = NULL, speedglm = F, only_coef = FALSE, mf)
```

Arguments

| | |
|-----------|---|
| formula | coxph like formula with Surv (tstart, tstop, event) on the left hand site of ~ |
| data | Data frame or environment containing the outcome and co-variates |
| by | Length of each intervals that cases are binned into |
| max_T | The end time of the last bin |
| ... | arguments passed to glm or speedglm . If only_coef = TRUE then the arguments are passed to glm.control if glm is used |
| id | The id for each row in data. This is important when variables are time varying |
| family | "logit" or "exponential" for the static equivalent model of ddhazard |
| model | TRUE if you want to save the design matrix used in glm |
| weights | weights if a skewed sample or similar is used |
| risk_obj | A pre-computed result from a get_risk_obj . Will be used to skip some computations |
| speedglm | TRUE if speedglm should be used. |
| only_coef | TRUE if only coefficients should be returned. This will only call the speedglm.wfit or glm.fit which will be faster. |
| mf | model frame for regression. Needed when only_coef = TRUE |

Details

Method to fit a static model corresponding to a [ddhazard](#) fit. The method uses weights to ease the memory requirements. See [get_survival_case_weights_and_data](#) for details on weights

Value

The returned list from the [glm](#) call or just coefficients depending on the value of only_coef

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