Package ‘itcSegment’

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Description Three methods for Individual Tree Crowns (ITCs) delineation on remote sensing data: one is based on LiDAR data in x,y,z format and one on imagery data in raster format.
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Description

Prediction of aboveground biomass (AGB) using height and crown diameter and the equations of Jucker et al. (2017).

Usage

\[
\text{agb}(H = \text{NULL}, CA = \text{NULL}, \text{species} = 1)
\]

Arguments

- \( H \) : Tree height in meters.
- \( CA \) : Crown diameter in meters.
- \( \text{species} \) : Integer number indicating the species group:
  - 1 = gymnosperm
  - 2 = angiosperm

Value

The AGB value in kilograms.

Author(s)

Michele Dalponte

References


Examples

```r
## Not run:
data(lasData)

## function takes a while to run

#Extraction of the ITCs
se<-itcLiDAR(lasData$X,lasData$Y,lasData$Z,epsg=32632)
```
dbh

summary(se)

#Computation of the crown diameter from the crown area
se$CD_m<-2*sqrt(se$CA_m2/pi)

#AGB prediction
se$agb<-'NA
se$agb<-'agb(se$Height_m,se$CD_m,species=1)

summary(se)

## End(Not run)

---

dbh

**Diameter at breast height prediction using height and crown diameter**

**Description**

Prediction of diameter at breast height (DBH) using height and crown diameter and the equations of Jucker et al. (2017).

**Usage**

dbh(H = NULL, CA = NULL, biome = 0)

**Arguments**

- **H**
  - Tree height in meters.
- **CA**
  - Crown diameter in meters.
- **biome**
  - Integer number indicating the type of biome:
    - 0 = 'Global'
    - 1 = 'Afrotropic-Tropical forests-Angiosperm'
    - 2 = 'Afrotropic-Woodlands and savannas-Angiosperm'
    - 3 = 'Australasia-Temperate mixed forests-Angiosperm'
    - 4 = 'Australasia-Temperate mixed forests-Gymnosperm'
    - 5 = 'Australasia-Woodlands and savannas-Angiosperm'
    - 6 = 'Indo-Malaya-Tropical forests-Angiosperm'
    - 7 = 'Nearctic-Boreal forests-Angiosperm'
    - 8 = 'Nearctic-Boreal forests-Gymnosperm'
    - 9 = 'Nearctic-Temperate coniferous forests-Angiosperm'
    - 10 = 'Nearctic-Temperate coniferous forests-Gymnosperm'
    - 11 = 'Nearctic-Temperate mixed forests-Angiosperm'
    - 12 = 'Nearctic-Temperate mixed forests-Gymnosperm'
13 = 'Nearctic-Woodlands and savannas-Angiosperm'
14 = 'Nearctic-Woodlands and savannas-Gymnosperm'
15 = 'Neotropic-Tropical forests-Angiosperm'
16 = 'Palearctic-Boreal forests-Angiosperm'
17 = 'Palearctic-Boreal forests-Gymnosperm'
18 = 'Palearctic-Temperate coniferous forests-Angiosperm'
19 = 'Palearctic-Temperate coniferous forests-Gymnosperm'
20 = 'Palearctic-Temperate mixed forests-Angiosperm'
21 = 'Palearctic-Temperate mixed forests-Gymnosperm'
22 = 'Palearctic-Tropical forests-Angiosperm'
23 = 'Palearctic-Woodlands and savannas-Angiosperm'
24 = 'Palearctic-Woodlands and savannas-Gymnosperm'

Value

The DBH value in centimeters.

Author(s)

Michele Dalponte

References


Examples

```r
## Not run:
data(lasData)

## function takes a while to run

#Extraction of the ITCs
se<-itcLiDAR(lasData$x,lasData$y,lasData$z,epsg=32632)

summary(se)

#Computation of the crown diameter from the crown area
se$CD_m<-2*sqrt(se$CA_m2/pi)

#DBH prediction
se$dbh<-NA
se$dbh<-dbh(se$Height_m,se$CD_m,biome=0)
```
**imgData**

Imagery data over a forest area

**Description**

A dataset containing a band (at 812 nm) of an hyperspectral image acquired over a forest area.

**Usage**

```r
data(imgData)
```

**Format**

An object of class `RasterLayer`.

**Details**

- `imgData` An object of class `RasterLayer`.

---

**itcIMG**

Individual Tree Crowns segmentation with imagery data

**Description**

The ITC delineation approach finds local maxima within an imagery, designates these as tree tops, then uses a decision tree method to grow individual crowns around the local maxima.

**Usage**

```r
itcIMG(imagery = NULL, epsg = NULL, searchWinSize = 3, TRESHSeed = 0.45, TRESHCrown = 0.55, DIST = 10, th = 0, ischm = FALSE)
```
Arguments

imagery  An object of class raster on which to perform the segmentation. The image should be projected.
epsg     The EPSG code of the reference system of the image.
searchWinSize Size (in pixels) of the moving window used to detect the local maxima. It should be an odd number larger than 3.
TRESHSeed Growing threshold 1. It should be between 0 and 1.
TRESHCrown Growing threshold 2. It should be between 0 and 1.
DIST     Maximum value of the crown diameter of a detected tree (in meters).
th       Digital number value below which a pixel cannot be a local maxima.
ischm    TRUE if the imagery is a Canopy Height Model (CHM). Default: FALSE.

Value

An object of the class SpatialPolygonsDataFrame containing the delineated ITCs. The information for each ITC contained in the data frame are the X and Y coordinates position of the tree, the tree height in meters (Height_m; only if ischm=TRUE) and its crown area in square meters (CA_m2).

Author(s)

Michele Dalponte

References


Examples

```r
## Not run:
data(imgData)

se<-itcIMG(imgData,epsg=32632)
summary(se)
plot(se,axes=T)

## to save the data use rgdal function called writeOGR. For more help see rgdal package.

## End(Not run)
```
**Description**

The ITC delineation approach finds local maxima within a rasterized canopy height model (CHM), designates these as tree tops, then uses a decision tree method to grow individual crowns around the local maxima. The approach goes through the following steps: (1) a low-pass filter is applied to the rasterized CHM to smooth the surface and reduce the number of local maxima; (2) local maxima are located using a moving window with size that adapts inside a user defined range (minimum and maximum size) according the pixel height; a pixel of the CHM is labelled as local maxima if its z value is greater than all other z values in the window, and with z greater than some minimum height above-ground; (3) each local maximum is labelled as an ‘initial region’ around which a tree crown can grow; the heights of the four neighboring pixels are extracted from the CHM and these pixels are added to the region if their vertical distance from the local maximum is less than some user-defined percentage of the local-maximum height, and less than some user-defined maximum difference; this procedure is repeated for all the neighbors of cells now included in the region, and so on iteratively until no further pixels are added to the region; (4) from each region that had been identified the first-return ALS points are extracted (having first removed low elevation points), (5) a 2D convex hull is applied to these points, and the resulting polygons becomes the final ITCs.

**Usage**

```python
itcliDAR(X = NULL, Y = NULL, Z = NULL, epsg = NULL, resolution = 0.5,
MinSearchFilSize = 3, MaxSearchFilSize = 7, TRESHSeed = 0.55,
TRESHCrown = 0.6, minDIST = 5, maxDIST = 40, HeightThreshold = 2,
cw = 1)
```

**Arguments**

- **X**
  A column vector of x coordinates.
- **Y**
  A column vector of y coordinates (it must have the same length as X).
- **Z**
  A column vector of z coordinates (it must have the same length as X). Z must be normalized respect to the ground.
- **epsg**
  The EPSG code of the reference system of the X,Y coordinates.
- **resolution**
  The resolution of the raster on which the first segmentation is carried out.
- **MinSearchFilSize**
  Minimum size (in pixels) of the moving window used to detect the local maxima. It should be an odd number larger than 3.
- **MaxSearchFilSize**
  Maximum size (in pixels) of the moving window used to detect the local maxima. It should be bigger or equal to MinSearchFilSize, and it should be an odd number larger than 3.
- **TRESHSeed**
  Growing threshold 1. It should be between 0 and 1.
- **TRESHCrown**
  Growing threshold 2. It should be between 0 and 1.
\(\text{minDIST}\) Minimum value of the crown diameter of a detected tree (in meters).

\(\text{maxDIST}\) Maximum value of the crown diameter of a detected tree (in meters). It should be bigger or equal to minDIST.

\(\text{HeightThreshold}\) Minimum height of the trees.

\(\text{cw}\) Weighting exponent used to increase the contrast in the CHM used to detect the local maxima (default \(\text{cw}=1\)).

### Value

An object of the class \(\text{SpatialPolygonsDataFrame}\) containing the delineated ITCs. The information for each ITC contained in the data frame are the X and Y coordinates position of the tree, the tree height in meters (\(\text{Height}_m\)) and its crown area in square meters (\(\text{CA}_{m^2}\)).

### Author(s)

Michele Dalponte

### References


### Examples

```r
## Not run:
data(lasData)

## function takes a while to run
se<-itcLiDAR(lasData$X, lasData$Y, lasData$Z, epsg=32632)
summary(se)
plot(se, axes=T)

## If we want to separate the height of the trees by grayscales:
plot(se, col=gray((max(se$Height_m)-se$Height_m)/(max(se$Height_m)-min(se$Height_m))), axes=T)

## to save the data use rgdal function called writeOGR. For more help see rgdal package.

## End(Not run)
```
Description

The ITC delineation approach finds local maxima within a rasterized canopy height model (CHM), designates these as tree tops, then uses a decision tree method to grow individual crowns around the local maxima. The approach goes through the following steps: (1) a low-pass filter is applied to the rasterized CHM to smooth the surface and reduce the number of local maxima; (2) local maxima are located using a moving window with size that adapts inside a user defined range (minimum and maximum size) according the pixel height; a pixel of the CHM is labelled as local maxima if its z value is greater than all other z values in the window, and with z greater than some minimum height above-ground; (3) each local maximum is labelled as an ‘initial region’ around which a tree crown can grow; the heights of the four neighboring pixels are extracted from the CHM and these pixels are added to the region if their vertical distance from the local maximum is less than some user-defined percentage of the local-maximum height, and less than some user-defined maximum difference; this procedure is repeated for all the neighbors of cells now included in the region, and so on iteratively until no further pixels are added to the region; (4) from each region that had been identified the first-return ALS points are extracted (having first removed low elevation points), (5) a 2D convex hull is applied to these points, and the resulting polygons becomes the final ITCs.

Usage

```r
itcLiDARallo(X = NULL, Y = NULL, Z = NULL, epsg = NULL,
            resolution = 0.5, TRESHSeed = 0.55, TRESHCrown = 0.6,
            HeightThreshold = 2, lut = NULL, cw = 1)
```

Arguments

- **X**: A column vector of x coordinates.
- **Y**: A column vector of y coordinates (it must have the same length as X).
- **Z**: A column vector of z coordinates (it must have the same length as X). Z must be normalized respect to the ground.
- **epsg**: The EPSG code of the reference system of the X,Y coordinates.
- **resolution**: The resolution of the raster on which the first segmentation is carried out.
- **TRESHSeed**: Growing threshold 1. It should be between 0 and 1.
- **TRESHCrown**: Growing threshold 2. It should be between 0 and 1.
- **HeightThreshold**: Minimum height of the trees.
- **lut**: Look up table. It should be made of two columns. The first column indicate the height in meters and the second the crown diameter in meters.
- **cw**: Weighting exponent used to increase the contrast in the CHM used to detect the local maxima (default cw=1).
Value

An object of the class SpatialPolygonsDataFrame containing the delineated ITCs. The information for each ITC contained in the data frame are the X and Y coordinates position of the tree, the tree height in meters (Height_m) and its crown area in square meters (CA_m2).

Author(s)

Michele Dalponte

References


Examples

```r
# Not run:
data(lasData)

# Creation of the look-up-table
lut <- matrix(6, 2, data = NA)
lut <- data.frame(lut)
names(lut) <- c("H", "CD")
lut$H <- c(2, 10, 15, 20, 25, 30)
lut$CD <- c(0, 1, 2, 3, 4, 5)

# Function takes a while to run
se <- itcLidar(all(lasData$X, lasData$Y, lasData$Z, epsg = 32632, lut = lut)
summary(se)
plot(se, axes = T)

# If we want to separate the height of the trees by grayscales:
plot(se, col = gray((max(se$Height_m) - se$Height_m) / (max(se$Height_m) - min(se$Height_m))), axes = T)

# To save the data use rgdal function called writeOGR. For more help see rgdal package.

# End(Not run)
```

**lasData**  
*LiDAR data point cloud acquired over a forest area*
Description

A dataset containing the X Y Z coordinates of LiDAR points acquired over a forest area. The EPSG code of the coordinates is 32632.

Usage

data(lasData)

Format

A data frame with 16907 rows and 3 variables

Details

• X. X coordinate in UTM WGS84 32 N (EPSG code 32632).
• Y. Y coordinate in UTM WGS84 32 N (EPSG code 32632).
• Z. Z coordinate. The Z coordinate is normalized respect to the ground.
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