Package ‘starsExtra’

April 22, 2020

Title  Miscellaneous Functions for Working with 'stars' Rasters
Version  0.0.3
Description  Miscellaneous functions for working with 'stars' objects, mainly single-band rasters. Currently includes functions for: (1) focal filtering, (2) detrending of Digital Elevation Models, (3) calculating flow length, (4) calculating the Convergence Index, (5) calculating topographic aspect.
Depends  R (>= 3.5.0), sf, stars
Imports  methods, parallel, mgcv, nngeo, units
License  MIT + file LICENSE
Encoding  UTF-8
LazyData  true
RoxygenNote  7.1.0
Suggests  testthat (>= 2.1.0), knitr, rmarkdown
VignetteBuilder  knitr
NeedsCompilation  yes
Author  Michael Dorman [aut, cre]
Maintainer  Michael Dorman <dorman@post.bgu.ac.il>
Repository  CRAN
Date/Publication  2020-04-22 15:40:03 UTC

R topics documented:

aspect .................................................................  2
carmel ...............................................................  3
CI ...................................................................  3
dem .................................................................  5
detrend .............................................................  5
flowlength ..........................................................  6
focal2 ..............................................................  8
golan ...............................................................  9
layer_to_matrix ................................................... 10
Calculate topographic aspect from a DEM

Description

Calculates topographic aspect given a Digital Elevation Model (DEM) raster. Input and output are rasters of class stars, single-band (i.e., only "x" and "y" dimensions), with one attribute.

Usage

```r
aspect(x, na_flag = -9999)
```

Arguments

- **x**: A raster (class stars) with two dimensions: x and y, i.e., a single-band raster, representing a DEM.
- **na_flag**: Value used to mark NA values in C code. This should be set to a value which is guaranteed to be absent from the input raster x (default is -9999).

Value

A stars raster with topographic slope, i.e., the azimuth where the terrain is tilted towards, in decimal degrees (0-360) clockwise from north. Aspect of flat terrain, i.e., where all values in the neighborhood are equal, is set to -1. Returned raster values are of class units (decimal degrees).

Note

Aspect calculation results in NA when at least one of the cell neighbors is NA, including the outermost rows and columns. Given that the focal window size in aspect calculation is 3*3, this means that the outermost one row and one column are given an aspect value of NA.

References

The topographic aspect algorithm is based on the How aspect works article in the ArcGIS documentation:

Examples

# Small example
data(dem)
aspect = aspect(dem)
r = c(dem, round(aspect, 1), along = 3)
r = st_set_dimensions(r, 3, values = c("input", "aspect"))
plot(r, text_values = TRUE, breaks = "equal", col = hcl.colors(11, "Spectral"))

# Larger example
data(carmel)
carmel_asp = aspect(carmel)
r = c(carmel, round(carmel_asp, 1), along = 3)
r = st_set_dimensions(r, 3, values = c("input", "aspect"))
plot(r, breaks = "equal", col = hcl.colors(11, "Spectral"))

---

carmel  
Digital Elevation Model of Mount Carmel

description

A stars object representing a Digital Elevation Model (DEM) Digital Elevation Model of Mount Carmel, at 90m resolution

Usage

carmel

Format

A stars object with 1 attribute:

- **elevation**: Elevation above sea level, in meters

---

CI  
Calculate the Convergence Index (CI) from a slope raster

Description

Calculates the Convergence Index (CI) given a topographic slope raster. Input and output are rasters of class stars, single-band (i.e., only “x” and “y” dimensions), with one attribute.

Usage

CI(x, k, na.rm = FALSE, na_flag = -9999)
Arguments

- **x**: A raster (class stars) with two dimensions: x and y, i.e., a single-band raster, representing aspect in decimal degrees clockwise from north, possibly including -1 to specify flat terrain, such as returned by function `aspect`.
- **k**: Neighborhood size around focal cell. Must be an odd number. For example, k=3 implies a 3*3 neighborhood.
- **na.rm**: Should NA values be ignored when calculating CI? Default is FALSE, i.e., when at least one aspect value in the neighborhood is NA the CI is also set to NA.
- **na_flag**: Value used to mark NA values in C code. This should be set to a value which is guaranteed to be absent from the input raster x (default is -9999).

Value

A stars raster with CI values.

Note

The raster is "padded" with (k-1)/2 more rows and columns of NA values on all sides, so that the neighborhood of the outermost rows and columns is still a complete neighborhood. Those rows and columns are removed from the final result before returning it. Aspect values of -1, specifying flat terrain, are assigned with a CI value of 0 regardless of their neighboring values.

References

The Convergence Index algorithm is described in:


Examples

```r
# Small example
data(dem)
dem_asp = aspect(dem)
dem_ci = CI(dem_asp, k = 3)
r = c(dem, round(dem_ci, 1), along = 3)
r = st_set_dimensions(r, 3, values = c("input", "CI (k=3)"))
plot(r, text_values = TRUE, breaks = "equal", col = terrain.colors(10))

# Larger example
data(golan)
golan_asp = aspect(golan)
golan_ci = CI(golan_asp, k = 25)
plot(golan_ci)
```
**dem**

Small Digital Elevation Model

**Description**

A stars object representing a small 13*11 Digital Elevation Model (DEM), at 90m resolution

**Usage**

dem

**Format**

A stars object with 1 attribute:

**elevation**  Elevation above sea level, in meters

**detrend**

Detrend a Digital Elevation Model

**Description**

Detrends a Digital Elevation Model (DEM) raster, by subtracting a trend surface. The trend is computed using mgcv::gam or mgcv::bam (when parallel>1) with formula z ~ s(x,y).

**Usage**

detrend(x, parallel = 1)

**Arguments**

- `x`  A two-dimensional stars object representing the DEM
- `parallel`  Number of parallel processes. With parallel=1 uses ordinary, non-parallel processing.

**Value**

A two-dimensional stars object, with two attributes:

- **resid** - the detrended result, i.e., "residual"
- **trend** - the estimated "trend" which was subtracted from the actual elevation to obtain resid
Examples

# Small example
data(dem)
dem1 = detrend(dem)
dem1 = st_redimension(dem1)
dem1 = st_set_dimensions(dem1, 3, values = c("resid", "trend"))
plot(round(dem1), text_values = TRUE, col = terrain.colors(11))

# Larger example 1
data(carmel)
carmel1 = detrend(carmel, parallel = 2)
carmel1 = st_redimension(carmel1)
carmel1 = st_set_dimensions(carmel1, 3, values = c("resid", "trend"))
plot(carmel1, col = terrain.colors(11))

# Larger example 2
data(golan)
golan1 = detrend(golan, parallel = 2)
golan1 = st_redimension(golan1)
golan1 = st_set_dimensions(golan1, 3, values = c("resid", "trend"))
plot(golan1, col = terrain.colors(11))

---

flowlength

**Calculate flow length**

Description

Calculates flow length for each pixel in a Digital Elevation Model (DEM) raster. Inputs and output are rasters of class *stars*, single-band (i.e., only "x" and "y" dimensions), with one attribute.

Usage

flowlength(elev, veg)

Arguments

elev A numeric *stars* raster representing a Digital Elevation Model (DEM).

veg A matching logical *stars* raster representing vegetation presence. TRUE values represent vegetated cells where flow is absorbed (i.e. sinks), FALSE values represent cells where flow is unobstructed.

Value

A numeric *stars* raster where each cell value is flow length, in resolution units.
References

The algorithm is described in:


Examples

# Example from Fig. 2 in Mayor et al. 2008

elev = rbind(
  c(8, 8, 8, 8, 9, 8, 9),
  c(7, 7, 7, 7, 9, 7, 7),
  c(6, 6, 6, 6, 6, 5, 7),
  c(4, 5, 5, 3, 5, 4, 7),
  c(4, 5, 4, 5, 4, 6, 5),
  c(3, 3, 3, 3, 2, 3, 3),
  c(2, 2, 2, 3, 4, 1, 3)
)
veg = rbind(
  c(TRUE, TRUE, TRUE, TRUE, FALSE, FALSE, TRUE),
  c(TRUE, TRUE, TRUE, TRUE, FALSE, FALSE),
  c(FALSE, FALSE, FALSE, FALSE, FALSE, FALSE),
  c(FALSE, TRUE, FALSE, FALSE, FALSE, FALSE),
  c(TRUE, TRUE, FALSE, FALSE, FALSE, FALSE),
  c(TRUE, TRUE, TRUE, FALSE, FALSE, FALSE),
  c(FALSE, TRUE, TRUE, FALSE, FALSE, TRUE)
)
elev = matrix_to_stars(elev)
veg = matrix_to_stars(veg)

# Calculate flow length
fl = flowlength(elev, veg)

# Plot
plot(round(elev, 1), text_values = TRUE, breaks = "equal", col = terrain.colors(6))
plot(veg*1, text_values = TRUE, breaks = "equal", col = rev(terrain.colors(2)))
plot(round(fl, 1), text_values = TRUE, breaks = "equal", col = terrain.colors(6))

# Larger example
data(carmel)
elev = carmel
elev[is.na(elev)] = 0
veg = elev > 100
fl = flowlength(elev, veg)
plot(fl)
focal2  Apply a focal filter on a raster

Description

Applies a focal filter with weighted neighborhood \( w \) on a raster. The weights \( w \) can be added to, subtracted from, multiplied by or divided with the raster values (as specified with weight_fun). The focal cell is then taken as the mean, sum, minimum or maximum of the weighted values (as specified with fun). Input and output are rasters of class stars, single-band (i.e., only "x" and "y" dimensions), with one attribute.

Usage

focal2(
  x,
  w,
  fun = "mean",
  weight_fun = "*",
  na.rm = FALSE,
  mask = FALSE,
  na_flag = -9999
)

Arguments

x  A raster (class stars) with one attribute and two dimensions: x and y, i.e., a single-band raster.

w  Weights matrix defining the neighborhood size around the focal cell, as well as the weights. For example, matrix(1, 3, 3) implies a neighborhood of size 3*3 with equal weights of 1 for all cells. The matrix must be square, with an odd number of rows and columns.

fun  A function to aggregate the resulting values for each neighborhood. Possible values are: "mean", "sum", "min", "max". The default is "mean", i.e., the resulting values per neighborhood are averaged before being assigned to the new focal cell value.

weight_fun  An operator which is applied on each pair of values comprising the cell value and the respective weight value, as in raster_value-weight. Possible values are: "+", "-", "*", "/". The default is "*", i.e., each cell value is multiplied by the respective weight.

na.rm  Should NA values in the neighborhood be removed from the calculation? Default is FALSE.

mask  If TRUE, pixels with NA in the input are set to NA in the output as well, i.e., the output is "masked" using the input (default is FALSE).

na_flag  Value used to mark NA values in C code. This should be set to a value which is guaranteed to be absent from the input raster x (default is -9999).
Value

The filtered stars raster.

Note

The raster is "padded" with \((nrow(w)-1)/2\) more rows and columns of NA values on all sides, so that the neighborhood of the outermost rows and columns is still a complete neighborhood. Those rows and columns are removed from the final result before returning it. This means, for instance, that the outermost rows and columns in the result will be NA when using na.rm=FALSE.

References

The function interface was inspired by function raster::focal. The C code for this function is a modified and expanded version of the C function named applyKernel included with R package spatialfil.

Examples

```r
# Small example
data(dem)
dem_mean3 = focal2(dem, matrix(1, 3, 3), "mean")
r = c(dem, round(dem_mean3, 1), along = 3)
r = st_set_dimensions(r, 3, values = c("input", "mean (k=3)"))
plot(r, text_values = TRUE, breaks = "equal", col = terrain.colors(10))

# Larger example
data(carmel)
carmel_mean15 = focal2(carmel, matrix(1, 15, 15), "mean")
r = c(carmel, carmel_mean15, along = 3)
r = st_set_dimensions(r, 3, values = c("input", "mean (k=15)"))
plot(r, breaks = "equal", col = terrain.colors(10))
```

---

golan

**Digital Elevation Model of Mount Carmel**

Description

A stars object representing a Digital Elevation Model (DEM) Digital Elevation Model of part of the Golan Heights and Lake Kinneret, at 90m resolution

Usage

golan
Format

A stars object with 1 attribute:

**elevation**  Elevation above sea level, in meters

---

**layer_to_matrix**  *Get stars layer values as matrix*

---

Description

Extracts the values of a single layer in a stars object to a matrix.

Usage

```r
layer_to_matrix(r)
```

Arguments

- **r**  A stars raster with one attribute and two dimensions, x and y, i.e., a single-band raster.

Value

A matrix with the layer values, having the same orientation as the raster (i.e., rows represent the y-axis and columns represent the x-axis).

Examples

```r
data(dem)
m = layer_to_matrix(dem)
m
```

---

**layer_to_vector**  *Get stars layer values as vector*

---

Description

Extracts the values of a single layer in a stars object to a vector. Cell values are ordered from top-left corner to the right.

Usage

```r
layer_to_vector(r)
```
**matrix_extend**

**Arguments**

- `r` A raster (class `stars`) with two dimensions: x and y, i.e., a single-band raster

**Value**

A vector with cell values, ordered by rows, starting from the top left corner (north-west) and to the right.

**Examples**

```r
data(dem)
v = layer_to_vector(dem)
v
```

---

**Description**

Adds `n` rows and columns with NA values on all sides of a matrix.

**Usage**

`matrix_extend(m, n = 1, fill = NA)`

**Arguments**

- `m` A matrix
- `n` By how many rows/columns to extend the matrix on each side?
- `fill` Fill value (default is NA)

**Value**

An extended matrix

**Examples**

```r
m = matrix(1:6, nrow = 2, ncol = 3)
m
matrix_extend(m, 1)
matrix_extend(m, 2)
matrix_extend(m, 3)
```
**matrix_get_neighbors**  
*Get neighboring cell values for given matrix cell*

**Description**

Get the values of a $k \times k$ neighborhood, as vector and by row, given a matrix, $k$, and focal cell position (row and column).

**Usage**

\[
\text{matrix_get_neighbors}(m, \text{pos}, k = 3)
\]

**Arguments**

- **m**: A matrix.
- **pos**: The focal cell position, a numeric vector of length two of the form `c(row, column)`.
- **k**: Neighborhood size around the focal cell. For example, $k=3$ implies a neighborhood of size $3 \times 3$. Must be an odd positive integer.

**Value**

A vector with cell values, ordered by rows, starting from the top left corner of the neighborhood and to the right. When neighborhood extends beyond matrix bounds, only the "existing" values are returned.

**Examples**

```r
m = matrix(1:12, nrow = 3, ncol = 4)
m
```

```
matrix_get_neighbors(m, pos = c(2, 2), k = 3)
matrix_get_neighbors(m, pos = c(2, 2), k = 5)
matrix_get_neighbors(m, pos = c(2, 2), k = 7)  # Same result
```

---

**matrix_to_stars**  
*Convert matrix to stars*

**Description**

Converts matrix to a single-band stars raster, conserving the matrix orientation where rows become the y-axis and columns become the y-axis. The bottom-left corner of the axis is set to (0, 0) coordinate, so that x and y coordinates are positive across the raster extent.

**Usage**

\[
\text{matrix_to_stars}(m, \text{res} = 1)
\]
**matrix_trim**

**Arguments**

- **m**  
  A matrix

- **res**  
  The cell size, default is 1

**Value**

A stars raster

**Examples**

```r
data(volcano)
r = matrix_to_stars(volcano, res = 10)
plot(r)
```

---

**matrix_trim** — *Trim matrix*

**Description**

Removes *n* rows and columns with NA values on all sides of a matrix.

**Usage**

```r
matrix_trim(m, n = 1)
```

**Arguments**

- **m**  
  A matrix

- **n**  
  By how many rows/columns to trim the matrix on each side?

**Value**

A trimmed matrix, or NULL if trimming results in an "empty" matrix.

**Examples**

```r
m = matrix(1:80, nrow = 8, ncol = 10)
m
matrix_trim(m, 1)
matrix_trim(m, 2)
matrix_trim(m, 3)
matrix_trim(m, 4)
```
### w_azimuth

*Create matrix with azimuths to center*

**Description**

Creates a matrix with directions (i.e., azimuth) to central cell, of specified size \( k \). The matrix can be used as weight matrix when calculating the convergence index (see Examples).

**Usage**

\[ w_{azimuth}(k) \]

**Arguments**

\[ k \]

Neighborhood size around focal cell. Must be an odd number. For example, \( k=3 \) implies a 3*3 neighborhood.

**Value**

A matrix where each cell value is the azimuth from that cell towards the matrix center.

**Examples**

\[ m = w_{azimuth}(3) \]
\[ m \]
\[ m = w_{azimuth}(5) \]
\[ m \]

### w_circle

*Create matrix with circular weight pattern*

**Description**

Creates a matrix with where a circular pattern is filled with values of 1 and the remaining cells are filled with values of 0 (see Examples).

**Usage**

\[ w_{circle}(k) \]

**Arguments**

\[ k \]

Neighborhood size around focal cell. Must be an odd number. For example, \( k=3 \) implies a 3*3 neighborhood.
Value

A matrix with a circular pattern.

Examples

```r
m = w_circle(3)
image(m, asp = 1, axes = FALSE)
m = w_circle(5)
image(m, asp = 1, axes = FALSE)
m = w_circle(15)
image(m, asp = 1, axes = FALSE)
m = w_circle(35)
image(m, asp = 1, axes = FALSE)
m = w_circle(91)
image(m, asp = 1, axes = FALSE)
m = w_circle(151)
image(m, asp = 1, axes = FALSE)
```
Index

*Topic **datasets**
  - carmel, 3
  - dem, 5
  - golan, 9

aspect, 2, 4

- carmel, 3
- CI, 3

- dem, 5
- detrend, 5

flowlength, 6

- focal2, 8

- golan, 9

- layer_to_matrix, 10
- layer_to_vector, 10

matrix_extend, 11

- matrix_get_neighbors, 12
- matrix_to_stars, 12
- matrix_trim, 13

w_azimuth, 14

- w_circle, 14