Package ‘tidygraph’

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Type Package

Title A Tidy API for Graph Manipulation

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Description A graph, while not "tidy" in itself, can be thought of as two tidy data frames describing node and edge data respectively. 'tidygraph' provides an approach to manipulate these two virtual data frames using the API defined in the 'dplyr' package, as well as provides tidy interfaces to a lot of common graph algorithms.

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**Description**

As a `tbl_graph` can be considered as a collection of two linked tables it is necessary to specify which table is referenced during manipulations. The `activate` verb does just that and needs affects all subsequent manipulations until a new table is activated. `active` is a simple query function to get the currently active context. In addition to the use of `activate` it is also possible to activate nodes or edges as part of the piping using the `%N>%` and `%E>%` pipes respectively. Do note that this approach somewhat obscures what is going on and is thus only recommended for quick, one-line, fixes in interactive use.
Usage

activate(.data, what)

active(x)

lhs %N>% rhs

lhs %E>% rhs

Arguments

.data, x, lhs  A tbl_graph or a grouped_tbl_graph
what  What should get activated? Possible values are nodes or edges.
rhs  A function to pipe into

Value

A tbl_graph

Note

Activate will ungroup a grouped_tbl_graph.

Examples

gr <- create_complete(5) %>%
    activate(nodes) %>%
    mutate(class = sample(c('a', 'b'), 5, TRUE)) %>%
    activate(edges) %>%
    arrange(from)

# The above could be achieved using the special pipes as well
gr <- create_complete(5) %>%
    mutate(class = sample(c('a', 'b'), 5, TRUE)) %>%
    arrange(from)
# But as you can see it obscures what part of the graph is being targeted
Description

The tbl_graph class is a thin wrapper around an igraph object that provides methods for manipulating the graph using the tidy API. As it is just a subclass of igraph every igraph method will work as expected. A grouped_tbl_graph is the equivalent of a grouped_df where either the nodes or the edges has been grouped. The grouped_tbl_graph is not constructed directly but by using the `group_by()` verb. After creation of a tbl_graph the nodes are activated by default. The context can be changed using the `activate()` verb and affects all subsequent operations. Changing context automatically drops any grouping. The current active context can always be extracted with `as_tibble()`, which drops the graph structure and just returns a tbl_df or a grouped_df depending on the state of the tbl_graph. The returned context can be overridden by using the `active` argument in `as_tibble()`.

Usage

```r
## S3 method for class 'data.frame'
as_tbl_graph(x, directed = TRUE, ...)
## S3 method for class 'Node'
as_tbl_graph(x, directed = TRUE, mode = "out", ...)
## S3 method for class 'dendrogram'
as_tbl_graph(x, directed = TRUE, mode = "out", ...)
## S3 method for class 'graphNEL'
as_tbl_graph(x, ...,)
## S3 method for class 'graphAM'
as_tbl_graph(x, ...,)
## S3 method for class 'graphBAM'
as_tbl_graph(x, ...,)
## S3 method for class 'hclust'
as_tbl_graph(x, directed = TRUE, mode = "out", ...)
## S3 method for class 'igraph'
as_tbl_graph(x, ...,)
## S3 method for class 'list'
as_tbl_graph(x, directed = TRUE, node_key = "name", ...)
## S3 method for class 'matrix'
as_tbl_graph(x, directed = TRUE, ...)
## S3 method for class 'network'
as_tbl_graph(x, ...,)
## S3 method for class 'phylo'
```
as_tbl_graph.data.frame

as_tbl_graph(x, directed = NULL, ...)

## S3 method for class 'evonet'
as_tbl_graph(x, directed = TRUE, ...)

tbl_graph(nodes = NULL, edges = NULL, directed = TRUE, node_key = "name")

as_tbl_graph(x, ...)

## Default S3 method:
as_tbl_graph(x, ...)

is.tbl_graph(x)

Arguments

x An object convertible to a tbl_graph

directed Should the constructed graph be directed (defaults to TRUE)

... Arguments passed on to the conversion function

mode In case directed = TRUE should the edge direction be away from node or towards. Possible values are "out" (default) or "in".

node_key The name of the column in nodes that character represented to and from columns should be matched against. If NA the first column is always chosen. This setting has no effect if to and from are given as integers.

nodes A data.frame containing information about the nodes in the graph. If edges$to and/or edges$from are characters then they will be matched to the column named according to node_key in nodes, if it exists. If not, they will be matched to the first column.

directed A data.frame containing information about the edges in the graph. The terminal nodes of each edge must either be encoded in a to and from column, or in the two first columns, as integers. These integers refer to nodes index.

Details

Constructors are provided for most data structures that resembles networks. If a class provides an igraph::as.igraph() method it is automatically supported.

Value

A tbl_graph object

Functions

- `as_tbl_graph(data.frame)`: Method for edge table and set membership table
- `as_tbl_graph(Node)`: Method to deal with Node objects from the data.tree package
- `as_tbl_graph(dendrogram)`: Method for dendrogram objects
• as_tbl_graph(graphNEL): Method for handling graphNEL objects from the graph package (on Bioconductor)
• as_tbl_graph(graphAM): Method for handling graphAM objects from the graph package (on Bioconductor)
• as_tbl_graph(graphBAM): Method for handling graphBAM objects from the graph package (on Bioconductor)
• as_tbl_graph(hclust): Method for hclust objects
• as_tbl_graph(igraph): Method for igraph object. Simply subclasses the object into a tbl_graph
• as_tbl_graph(list): Method for adjacency lists and lists of node and edge tables
• as_tbl_graph(matrix): Method for edgelist, adjacency and incidence matrices
• as_tbl_graph(network): Method to handle network objects from the network package. Requires this packages to work.
• as_tbl_graph(phylo): Method for handling phylo objects from the ape package
• as_tbl_graph(evonet): Method for handling evonet objects from the ape package
• as_tbl_graph(default): Default method. tries to call igraph::as.igraph() on the input.

Examples

rstat_nodes <- data.frame(name = c("Hadley", "David", "Romain", "Julia"))
rstat_edges <- data.frame(from = c(1, 1, 1, 2, 3, 3, 4, 4, 4),
                          to = c(2, 3, 4, 1, 1, 2, 1, 2, 3))
tbl_graph(nodes = rstat_nodes, edges = rstat_edges)

bind_graphs

# Add graphs, nodes, or edges to a tbl_graph

Description

These functions are tbl_graph pendants to dplyr::bind_rows() that allows you to grow your tbl_graph by adding rows to either the nodes data, the edges data, or both. As with bind_rows() columns are matched by name and are automatically filled with NA if the column doesn’t exist in some instances. In the case of bind_graphs() the graphs are automatically converted to tbl_graph objects prior to binding. The edges in each graph will continue to reference the nodes in the graph where they originated, meaning that their terminal node indexes will be shifted to match the new index of the node in the combined graph. This means the bind_graphs() always result in a disconnected graph. See graph_join() for merging graphs on common nodes.

Usage

bind_graphs(.data, ...)
bind_nodes(.data, ...)
bind_edges(.data, ..., node_key = "name")
centrality

Arguments

.data A tbl_graph, or a list of tbl_graph objects (for bind_graphs()).

... In case of bind_nodes() and bind_edges() data.frames to add. In the case of bind_graphs() objects that are convertible to tbl_graph using as_tbl_graph().

node_key The name of the column in nodes that character represented to and from columns should be matched against. If NA the first column is always chosen. This setting has no effect if to and from are given as integers.

Value

A tbl_graph containing the new data

Examples

graph <- create_notable('bull')
new_graph <- create_notable('housex')

# Add nodes
graph %>% bind_nodes(data.frame(new = 1:4))

# Add edges
graph %>% bind_edges(data.frame(from = 1, to = 4:5))

# Add graphs
graph %>% bind_graphs(new_graph)

centrality Calculate node and edge centrality

Description

The centrality of a node measures the importance of node in the network. As the concept of importance is ill-defined and dependent on the network and the questions under consideration, many centrality measures exist. tidygraph provides a consistent set of wrappers for all the centrality measures implemented in igraph for use inside dplyr::mutate() and other relevant verbs. All functions provided by tidygraph have a consistent naming scheme and automatically calls the function on the graph, returning a vector with measures ready to be added to the node data. Further tidygraph provides access to the netrankr engine for centrality calculations and define a number of centrality measures based on that, as well as provide a manual mode for specifying more-or-less any centrality score.

Usage

centrality_alpha(
  weights = NULL,
  alpha = 1,
exo = 1,
tol = 1e-07,
loops = FALSE
)

centrality_authority(
  weights = NULL,
  scale = TRUE,
  options = igraph::arpack_defaults
)

centrality_betweenness(
  weights = NULL,
  directed = TRUE,
  cutoff = -1,
  normalized = FALSE
)

centrality_power(exponent = 1, rescale = FALSE, tol = 1e-07, loops = FALSE)

centrality_closeness(
  weights = NULL,
  mode = "out",
  normalized = FALSE,
  cutoff = NULL
)

centrality_eigen(
  weights = NULL,
  directed = FALSE,
  scale = TRUE,
  options = igraph::arpack_defaults
)

centrality_hub(weights = NULL, scale = TRUE, options = igraph::arpack_defaults)

centrality_pagerank(
  weights = NULL,
  directed = TRUE,
  damping = 0.85,
  personalized = NULL
)

centrality_subgraph(loops = FALSE)

centrality_degree(
  weights = NULL,
  mode = "out",
  }
centrality

loops = TRUE,
        normalized = FALSE
"

centrality_edge_betweenness(weights = NULL, directed = TRUE, cutoff = NULL)

centrality_manual(relation = "dist_sp", aggregation = "sum", ...)

centrality_closeness_harmonic()

centrality_closeness_residual()

centrality_closeness_generalised(alpha)

centrality_integration()

centrality_communicability()

centrality_communicability_odd()

centrality_communicability_even()

centrality_subgraph_odd()

centrality_subgraph_even()

centrality_katz(alpha = NULL)

centrality_betweenness_network(netflowmode = "raw")

centrality_betweenness_current()

centrality_betweenness_communicability()

centrality_betweenness_rsp_simple(rspxparam = 1)

centrality_betweenness_rsp_net(rspxparam = 1)

centrality_information()

centrality_decay(alpha = 1)

centrality_random_walk()

centrality_expected()
Arguments

weights  The weight of the edges to use for the calculation. Will be evaluated in the context of the edge data.
alpha    Relative importance of endogenous vs exogenous factors (centrality_alpha), the exponent to the power transformation of the distance metric (centrality_closeness_generalised), the base of power transformation (centrality_decay), or the attenuation factor (centrality_katz)
exo      The exogenous factors of the nodes. Either a scalar or a number number for each node. Evaluated in the context of the node data.
tol      Tolerance for near-singularities during matrix inversion
loops    Should loops be included in the calculation
scale    Should the output be scaled between 0 and 1
options  Settings passed on to igraph::arpack()
directed Should direction of edges be used for the calculations
cutoff   maximum path length to use during calculations
normalized Should the output be normalized
exponent The decay rate for the Bonacich power centrality
rescale  Should the output be scaled to sum up to 1
mode     How should edges be followed. Ignored for undirected graphs
damping  The damping factor of the page rank algorithm
personalized The probability of jumping to a node when abandoning a random walk. Evaluated in the context of the node data.
relation The indirect relation measure type to be used in netrankr::indirect_relations
aggregation The aggregation type to use on the indirect relations to be used in netrankr::aggregate_positions
...      Arguments to pass on to netrankr::indirect_relations
netflowmode The return type of the network flow distance, either 'raw' or 'frac'
rspxparam inverse temperature parameter

Value

A numeric vector giving the centrality measure of each node.

Functions

- centrality_alpha(): Wrapper for igraph::alpha_centrality()
- centrality_authority(): Wrapper for igraph::authority_score()
- centrality_betweenness(): Wrapper for igraph::betweenness() and igraph::estimate_betweenness()
- centrality_power(): Wrapper for igraph::power_centrality()
- centrality_closeness(): Wrapper for igraph::closeness() and igraph::estimate_closeness()
- centrality_eigen(): Wrapper for igraph::eigen_centrality()
- centrality_hub(): Wrapper for igraph::hub_score()
• centrality_pagerank(): Wrapper for igraph::page_rank()
• centrality_subgraph(): Wrapper for igraph::subgraph_centrality()
• centrality_degree(): Wrapper for igraph::degree() and igraph::strength()
• centrality_edge_betweenness(): Wrapper for igraph::edge_betweenness()
• centrality_manual(): Manually specify your centrality score using the netrankr framework (netrankr)
• centrality_closeness_harmonic(): centrality based on inverse shortest path (netrankr)
• centrality_closeness_residual(): centrality based on 2-to-the-power-of negative shortest path (netrankr)
• centrality_closeness_generalised(): centrality based on alpha-to-the-power-of negative shortest path (netrankr)
• centrality_integration(): centrality based on $1 - (x - 1)/\max(x)$ transformation of shortest path (netrankr)
• centrality_communicability(): centrality an exponential transformation of walk counts (netrankr)
• centrality_communicability_odd(): centrality an exponential transformation of odd walk counts (netrankr)
• centrality_communicability_even(): centrality an exponential transformation of even walk counts (netrankr)
• centrality_subgraph_odd(): subgraph centrality based on odd walk counts (netrankr)
• centrality_subgraph_even(): subgraph centrality based on even walk counts (netrankr)
• centrality_katz(): centrality based on walks penalizing distant nodes (netrankr)
• centrality_betweenness_network(): Betweenness centrality based on network flow (netrankr)
• centrality_betweenness_current(): Betweenness centrality based on current flow (netrankr)
• centrality_betweenness_communicability(): Betweenness centrality based on communicability (netrankr)
• centrality_betweenness_rsp_simple(): Betweenness centrality based on simple randomised shortest path dependencies (netrankr)
• centrality_betweenness_rsp_net(): Betweenness centrality based on net randomised shortest path dependencies (netrankr)
• centrality_information(): centrality based on inverse sum of resistance distance between nodes (netrankr)
• centrality_decay(): based on a power transformation of the shortest path (netrankr)
• centrality_random_walk(): centrality based on the inverse sum of expected random walk length between nodes (netrankr)
• centrality_expected(): Expected centrality ranking based on exact rank probability (netrankr)
Examples

```r
create_notable('bull') %>%
  activate(nodes) %>%
  mutate(importance = centrality_alpha())

# Most centrality measures are for nodes but not all
create_notable('bull') %>%
  activate(edges) %>%
  mutate(importance = centrality_edge_betweenness())
```

component_games

Graph games based on connected components

Description

This set of graph creation algorithms simulate the topology by, in some way, connecting subgraphs. The nature of their algorithm is described in detail at the linked igraph documentation.

Usage

```r
play_blocks(n, size_blocks, p_between, directed = TRUE, loops = FALSE)
play_blocks_hierarchy(n, size_blocks, rho, p_within, p_between)
play_islands(n_islands, size_islands, p_within, m_between)
play_smallworld(n_dim, dim_size, order, p_rewire, loops = FALSE, multiple = FALSE)
```

Arguments

- `n`: The number of nodes in the graph.
- `size_blocks`: The number of vertices in each block.
- `p_between`: The probability of edges within and between groups/blocks.
- `p_within`: The probability of edges within and between groups/blocks.
- `directed`: Should the resulting graph be directed.
- `loops`: Are loop edges allowed.
- `rho`: The fraction of vertices per cluster.
- `n_islands`: The number of densely connected islands.
size_islands  The number of nodes in each island
m_between  The number of edges between groups/islands
n_dim, dim_size  The dimension and size of the starting lattice
order  The neighborhood size to create connections from
p_rewire  The rewiring probability of edges
multiple  Are multiple edges allowed

Value
A tbl_graph object

Functions

• play_blocks(): Create graphs by sampling from stochastic block model. See `igraph::sample_sbm()`
• play_blocks_hierarchy(): Create graphs by sampling from the hierarchical stochastic block model. See `igraph::sample_hierarchical_sbm()`
• play_islands(): Create graphs with fixed size and edge probability of subgraphs as well as fixed edge count between subgraphs. See `igraph::sample_islands()`
• play_smallworld(): Create graphs based on the Watts-Strogatz small-world model. See `igraph::sample_smallworld()`

See Also
Other graph games: `evolution_games`, `sampling_games`, `type_games`

Examples

plot(play_islands(4, 10, 0.7, 3))
create_graphs

Value

Either a tbl_graph (.G()) or a tibble (.N())

Functions

- `.G()`: Get the tbl_graph you’re currently working on
- `.N()`: Get the nodes data from the graph you’re currently working on
- `.E()`: Get the edges data from the graph you’re currently working on

Examples

```r
# Get data from the nodes while computing for the edges
create_notable('bull') %>%
  activate(nodes) %>%
  mutate(centrality = centrality_power()) %>%
  activate(edges) %>%
  mutate(mean_centrality = .N()[centrality[from] + .N()[centrality[to]]/2)
```

create_graphs

Create different types of well-defined graphs

Description

These functions create a long list of different types of well-defined graphs, that is, their structure is not based on any randomisation. All of these functions are shallow wrappers around a range of igraph::make_* functions but returns tbl_graph rather than igraph objects.

Usage

- `create_ring(n, directed = FALSE, mutual = FALSE)`
- `create_path(n, directed = FALSE, mutual = FALSE)`
- `create_chordal_ring(n, w)`
- `create_de_bruijn(alphabet_size, label_size)`
- `create_empty(n, directed = FALSE)`
- `create_bipartite(n1, n2, directed = FALSE, mode = "out")`
- `create_citation(n)`
- `create_complete(n)`
- `create_notable(name)`
create_kautz(alphabet_size, label_size)

create_lattice(dim, directed = FALSE, mutual = FALSE, circular = FALSE)

create_star(n, directed = FALSE, mutual = FALSE, mode = "out")

create_tree(n, children, directed = TRUE, mode = "out")

Arguments

n, n1, n2 The number of nodes in the graph

directed Should the graph be directed

mutual Should mutual edges be created in case of the graph being directed

w A matrix specifying the additional edges in the chordan. See \texttt{igraph::make_chordal_ring()}

alphabet_size The number of unique letters in the alphabet used for the graph

label_size The number of characters in each node

mode In case of a directed, non-mutual, graph should the edges flow 'out' or 'in'

name The name of a notable graph. See a complete list in \texttt{igraph::make_graph()}

dim The dimensions of the lattice

circular Should each dimension in the lattice wrap around

children The number of children each node has in the tree (if possible)

Value

A tbl_graph

Functions

\begin{itemize}
  \item \texttt{create_ring()}: Create a simple ring graph
  \item \texttt{create_path()}: Create a simple path
  \item \texttt{create_chordal_ring()}: Create a chordal ring
  \item \texttt{create_de_bruijn()}: Create a de Bruijn graph with the specified alphabet and label size
  \item \texttt{create_empty()}: Create a graph with no edges
  \item \texttt{create_bipartite()}: Create a full bipartite graph
  \item \texttt{create_citation()}: Create a full citation graph
  \item \texttt{create_complete()}: Create a complete graph (a graph where all nodes are connected)
  \item \texttt{create_notable()}: Create a graph based on its name. See \texttt{igraph::make_graph()}
  \item \texttt{create_kautz()}: Create a Kautz graph with the specified alphabet and label size
  \item \texttt{create_lattice()}: Create a multidimensional grid of nodes
  \item \texttt{create_star()}: Create a star graph (A single node in the center connected to all other nodes)
  \item \texttt{create_tree()}: Create a tree graph
\end{itemize}
Examples

```r
# Create a complete graph with 10 nodes
create_complete(10)
```

### edge_types

**Querying edge types**

**Description**

These functions lets the user query whether the edges in a graph is of a specific type. All functions return a logical vector giving whether each edge in the graph corresponds to the specific type.

**Usage**

- `edge_is_multiple()`
- `edge_is_loop()`
- `edge_is_mutual()`
- `edge_is_from(from)`
- `edge_is_to(to)`
- `edge_is_between(from, to, ignore_dir = !graph_is_directed())`
- `edge_is_incident(i)`

**Arguments**

- `from`, `to`, `i` A vector giving node indices
- `ignore_dir` Is both directions of the edge allowed

**Value**

A logical vector of the same length as the number of edges in the graph

**Functions**

- `edge_is_multiple()`: Query whether each edge has any parallel siblings
- `edge_is_loop()`: Query whether each edge is a loop
- `edge_is_mutual()`: Query whether each edge has a sibling going in the reverse direction
- `edge_is_from()`: Query whether an edge goes from a set of nodes
- `edge_is_to()`: Query whether an edge goes to a set of nodes
- `edge_is_between()`: Query whether an edge goes between two sets of nodes
- `edge_is_incident()`: Query whether an edge goes from or to a set of nodes
evolution_games

Examples

```r
create_star(10, directed = TRUE, mutual = TRUE) %>%
activate(edges) %>%
sample_frac(0.7) %>%
mutate(single_edge = !edge_is_mutual())
```

---

**evolution_games**  
*Graph games based on evolution*

---

**Description**

This games create graphs through different types of evolutionary mechanisms (not necessarily in a biological sense). The nature of their algorithm is described in detail at the linked igraph documentation.

**Usage**

```r
play_citation_age(
  n,
  growth = 1,
  bins = n/7100,
  p_pref = (1:(bins + 1))^3,
  directed = TRUE
)
```

```r
play_forestfire(
  n,
  p_forward,
  p_backward = p_forward,
  growth = 1,
  directed = TRUE
)
```

```r
play_growing(n, growth = 1, directed = TRUE, citation = FALSE)
```

```r
play_barabasi_albert(
  n,
  power,
  growth = 1,
  growth_dist = NULL,
  use_out = FALSE,
  appeal_zero = 1,
  directed = TRUE,
  method = "psumtree"
)
```

```r
play_barabasi_albert_aging(
```
n,  
power, 
power_age, 
growth = 1, 
growth_dist = NULL,  
bins = 300, 
use_out = FALSE, 
appeal_zero = 1, 
appeal_zero_age = 0, 
directed = TRUE, 
coefficient = 1, 
coefficient_age = 1, 
window = NULL
)

Arguments

n                The number of nodes in the graph.
growth           The number of edges added at each iteration 
bins             The number of aging bins 
p_pref            The probability that an edge will be made to an age bin.
directed         Should the resulting graph be directed 
p_forward, p_backward 
                 Forward and backward burning probability 
citation         Should a citation graph be created 
power            The power of the preferential attachment 
growth_dist      The distribution of the number of added edges at each iteration 
use_out          Should outbound edges be used for calculating citation probability 
appeal_zero      The appeal value for unconnected nodes 
method           The algorithm to use for graph creation. Either 'psumtree', 'psumtree-multiple', or 'bag' 
power_age        The aging exponent 
appeal_zero_age  The appeal value of nodes without age 
coefficient      The coefficient of the degree dependent part of attrictiveness 
coefficient_age  The coefficient of the age dependent part of attrictiveness 
window           The aging window to take into account when calculating the preferential attraction

Value

A tbl_graph object
Functions

- `play_citation_age()`: Create citation graphs based on a specific age link probability. See `igraph::sample_last_cit()`
- `play_forestfire()`: Create graphs by simulating the spread of fire in a forest. See `igraph::sample_forestfire()`
- `play_growing()`: Create graphs by adding a fixed number of edges at each iteration. See `igraph::sample_growing()`
- `play_barabasi_albert()`: Create graphs based on the Barabasi-Alberts preferential attachment model. See `igraph::sample_pa()`
- `play_barabasi_albert_aging()`: Create graphs based on the Barabasi-Alberts preferential attachment model, incorporating node age preference. See `igraph::sample_pa_age()`.

See Also

`play_traits()` and `play_citation_type()` for an evolutionary algorithm based on different node types

Other graph games: `component_games`, `sampling_games`, `type_games`

Examples

```r
plot(play_forestfire(50, 0.5))
```

---

**graph_join**

*Join graphs on common nodes*

**Description**

This graph-specific join method makes a full join on the nodes data and updates the edges in the joining graph so they matches the new indexes of the nodes in the resulting graph. Node and edge data is combined using `dplyr::bind_rows()` semantic, meaning that data is matched by column name and filled with `NA` if it is missing in either of the graphs.

**Usage**

```r
graph_join(x, y, by = NULL, copy = FALSE, suffix = c(".x", ".y"), ...)
```

**Arguments**

- `x` A `tbl_graph`
- `y` An object convertible to a `tbl_graph` using `as_tbl_graph()`
- `by` A join specification created with `join_by()`, or a character vector of variables to join by.
  
  If `NULL`, the default, `*_join()` will perform a natural join, using all variables in common across `x` and `y`. A message lists the variables so that you can check they're correct; suppress the message by supplying `by` explicitly.
To join on different variables between x and y, use a `join_by()` specification. For example, `join_by(a == b)` will match x$a to y$b.

To join by multiple variables, use a `join_by()` specification with multiple expressions. For example, `join_by(a == b, c == d)` will match x$a to y$b and x$c to y$d. If the column names are the same between x and y, you can shorten this by listing only the variable names, like `join_by(a, c).

`join_by()` can also be used to perform inequality, rolling, and overlap joins. See the documentation at `?join_by` for details on these types of joins.

For simple equality joins, you can alternatively specify a character vector of variable names to join by. For example, `by = c("a", "b")` joins x$a to y$a and x$b to y$b. If variable names differ between x and y, use a named character vector like `by = c("x_a" = "y_a", "x_b" = "y_b").

To perform a cross-join, generating all combinations of x and y, see `cross_join()`.

copy

If x and y are not from the same data source, and copy is TRUE, then y will be copied into the same src as x. This allows you to join tables across srcs, but it is a potentially expensive operation so you must opt into it.

suffix

If there are non-joined duplicate variables in x and y, these suffixes will be added to the output to disambiguate them. Should be a character vector of length 2.

... Other parameters passed onto methods.

### Value

A tbl_graph containing the merged graph

### Examples

```r
gr1 <- create_notable('bull') %>%
activate(nodes) %>%
mutate(name = letters[1:5])
gr2 <- create_ring(10) %>%
activate(nodes) %>%
mutate(name = letters[4:13])
gr1 %>% graph_join(gr2)
```

### Description

This set of functions provide wrappers to a number of igraphs graph statistic algorithms. As for the other wrappers provided, they are intended for use inside the tidygraph framework and it is thus not necessary to supply the graph being computed on as the context is known. All of these functions are guaranteed to return scalars making it easy to compute with them.
Usage

graph_adhesion()

graph_assortativity(attr, in_attr = NULL, directed = TRUE)

graph_automorphisms(sh = "fm")

graph_clique_num()

graph_clique_count(min = NULL, max = NULL, subset = NULL)

graph_component_count(type = "weak")

graph_motif_count(size = 3, cut.prob = rep(0, size))

graph_diameter(weights = NULL, directed = TRUE, unconnected = TRUE)

graph_girth()

graph_radius(mode = "out")

graph_mutual_count()

graph_asym_count()

graph_unconn_count()

graph_size()

graph_order()

graph_reciprocity(ignore_loops = TRUE, ratio = FALSE)

graph_min_cut(capacity = NULL)

graph_mean_dist(directed = TRUE, unconnected = TRUE)

graph_modularity(group, weights = NULL)

Arguments

attr The node attribute to measure on

in_attr An alternative node attribute to use for incoming node. If NULL the attribute given by type will be used

directed Should a directed graph be treated as directed

sh The splitting heuristics for the BLISS algorithm. Possible values are: ‘f’: first non-singleton cell, ‘fl’: first largest non-singleton cell, ‘fs’: first smallest non-singleton cell, ‘fm’: first maximally non-trivially connected non-singleton cell,
graph_measures

‘flm’: first largest maximally non-trivially connected non-singleton cell, ‘fsm’: first smallest maximally non-trivially connected non-singleton cell.

`min, max` The upper and lower bounds of the cliques to be considered.

`subset` The indexes of the nodes to start the search from (logical or integer). If provided only the cliques containing these nodes will be counted.

`type` The type of component to count, either 'weak' or 'strong'. Ignored for undirected graphs.

`size` The size of the motif.

`cut.prob` Numeric vector giving the probabilities that the search graph is cut at a certain level. Its length should be the same as the size of the motif (the `size` argument). By default no cuts are made.

`weights` Optional positive weight vector for calculating weighted distances. If the graph has a `weight` edge attribute, then this is used by default.

`unconnected` Logical, what to do if the graph is unconnected. If FALSE, the function will return a number that is one larger the largest possible diameter, which is always the number of vertices. If TRUE, the diameters of the connected components will be calculated and the largest one will be returned.

`mode` How should eccentricity be calculated. If "out" only outbound edges are followed. If "in" only inbound are followed. If "all" all edges are followed. Ignored for undirected graphs.

`ignore_loops` Logical. Should loops be ignored while calculating the reciprocity ratio

`ratio` Should the old "ratio" approach from igraph < v0.6 be used

`capacity` The capacity of the edges

`group` The node grouping to calculate the modularity on

Value

A scalar, the type depending on the function

Functions

• graph_adhesion(): Gives the minimum edge connectivity. Wraps `igraph::edge_connectivity()`

• graph_assortativity(): Measures the propensity of similar nodes to be connected. Wraps `igraph::assortativity()`

• graph_automorphisms(): Calculate the number of automorphisms of the graph. Wraps `igraph::automorphisms()`

• graph_clique_num(): Get the size of the largest clique. Wraps `igraph::clique_num()`

• graph_clique_count(): Get the number of maximal cliques in the graph. Wraps `igraph::count_max_cliques()`

• graph_component_count(): Count the number of unconnected components in the graph. Wraps `igraph::count_components()`

• graph_motif_count(): Count the number of motifs in a graph. Wraps `igraph::count_motifs()`

• graph_diameter(): Measures the length of the longest geodesic. Wraps `igraph::diameter()`

• graph_girth(): Measures the length of the shortest circle in the graph. Wraps `igraph::girth()`
graph_types

- `graph_radius()`: Measures the smallest eccentricity in the graph. Wraps `igraph::radius()`
- `graph_mutual_count()`: Counts the number of mutually connected nodes. Wraps `igraph::dyad_census()`
- `graph_asym_count()`: Counts the number of asymmetrically connected nodes. Wraps `igraph::dyad_census()`
- `graph_unconn_count()`: Counts the number of unconnected node pairs. Wraps `igraph::dyad_census()`
- `graph_size()`: Counts the number of edges in the graph. Wraps `igraph::gsize()`
- `graph_order()`: Counts the number of nodes in the graph. Wraps `igraph::gorder()`
- `graph_reciprocity()`: Measures the proportion of mutual connections in the graph. Wraps `igraph::reciprocity()`
- `graph_min_cut()`: Calculates the minimum number of edges to remove in order to split the graph into two clusters. Wraps `igraph::min_cut()`
- `graph_mean_dist()`: Calculates the mean distance between all node pairs in the graph. Wraps `igraph::mean_distance()`
- `graph_modularity()`: Calculates the modularity of the graph contingent on a provided node grouping

Examples

```r
# Use e.g. to modify computations on nodes and edges
create_notable('meredith') %>%
  activate(nodes) %>%
  mutate(rel_neighbors = centrality_degree()/graph_order())
```

Querying graph types

Description

This set of functions lets the user query different aspects of the graph itself. They are all concerned with whether the graph implements certain properties and will all return a logical scalar.

Usage

- `graph_is_simple()`
- `graph_is_directed()`
- `graph_is_bipartite()`
- `graph_is_connected()`
- `graph_is_tree()`
- `graph_is_forest()`
- `graph_is_dag()`
graph_is_chordal()

graph_is_complete()

graph_is_isomorphic_to(graph, method = "auto", ...)

graph_is_subgraph_isomorphic_to(graph, method = "auto", ...)

Arguments

graph The graph to compare structure to
method The algorithm to use for comparison
... Arguments passed on to the comparison methods. See igraph::is_isomorphic_to() and igraph::is_subgraph_isomorphic_to()

Value

A logical scalar

Functions

- `graph_is_simple()`: Is the graph simple (no parallel edges)
- `graph_is_directed()`: Is the graph directed
- `graph_is_bipartite()`: Is the graph bipartite
- `graph_is_connected()`: Is the graph connected
- `graph_is_tree()`: Is the graph a tree
- `graph_is_forest()`: Is the graph an ensemble of multiple trees
- `graph_is_dag()`: Is the graph a directed acyclic graph
- `graph_is_chordal()`: Is the graph chordal
- `graph_is_complete()`: Is the graph fully connected
- `graph_is_isomorphic_to()`: Is the graph isomorphic to another graph. See igraph::is_isomorphic_to()
- `graph_is_subgraph_isomorphic_to()`: Is the graph an isomorphic subgraph to another graph. See igraph::is_subgraph_isomorphic_to()

Examples

gr <- create_tree(50, 4)

with_graph(gr, graph_is_tree())
group_graph

Group nodes and edges based on community structure

Description

These functions are wrappers around the various clustering functions provided by igraph. As with the other wrappers they automatically use the graph that is being computed on, and otherwise passes on its arguments to the relevant clustering function. The return value is always a numeric vector of group memberships so that nodes or edges with the same number are part of the same group. Grouping is predominantly made on nodes and currently the only grouping of edges supported is biconnected components.

Usage

```r
  group_components(type = "weak")
  group_edge_betweenness(weights = NULL, directed = TRUE, n_groups = NULL)
  group_fast_greedy(weights = NULL, n_groups = NULL)
  group_infomap(weights = NULL, node_weights = NULL, trials = 10)
  group_label_prop(weights = NULL, label = NULL, fixed = NULL)
  group_leading_eigen(
    weights = NULL,
    steps = -1,
    label = NULL,
    options = igraph::arpack_defaults,
    n_groups = NULL
  )
  group_louvain(weights = NULL)
  group_optimal(weights = NULL)
  group_spinglass(weights = NULL, ...)
  group_walktrap(weights = NULL, steps = 4, n_groups = NULL)
  group_biconnected_component()
```

Arguments

- `type` The type of component to find. Either 'weak' or 'strong'
- `weights` The weight of the edges to use for the calculation. Will be evaluated in the context of the edge data.
directed: Should direction of edges be used for the calculations

n_groups: Integer scalar, the desired number of communities. If too low or two high, then an error message is given.

node_weights: The weight of the nodes to use for the calculation. Will be evaluated in the context of the node data.

trials: Number of times partition of the network should be attempted

label: The initial groups of the nodes. Will be evaluated in the context of the node data.

fixed: A logical vector determining which nodes should keep their initial groups. Will be evaluated in the context of the node data.

steps: The number of steps in the random walks

options: Settings passed on to igraph::arpack()

...: arguments passed on to igraph::cluster_spinglass()

Value

A numeric vector with the membership for each node in the graph. The enumeration happens in order based on group size progressing from the largest to the smallest group.

Functions

- group_components(): Group by connected components using igraph::components()
- group_edge_betweenness(): Group densely connected nodes using igraph::cluster_edge_betweenness()
- group_fast_greedy(): Group nodes by optimising modularity using igraph::cluster_fast_greedy()
- group_infomap(): Group nodes by minimizing description length using igraph::cluster_infomap()
- group_label_prop(): Group nodes by propagating labels using igraph::cluster_label_prop()
- group_leading_eigen(): Group nodes based on the leading eigenvector of the modularity matrix using igraph::cluster_leading_eigen()
- group_louvain(): Group nodes by multilevel optimisation of modularity using igraph::cluster_louvain()
- group_optimal(): Group nodes by optimising the modularity score using igraph::cluster_optimal()
- group_spinglass(): Group nodes using simulated annealing with igraph::cluster_spinglass()
- group_walktrap(): Group nodes via short random walks using igraph::cluster_walktrap()
- group_biconnected_component(): Group edges by their membership of the maximal biconnected components using igraph::biconnected_components()

Examples

create_notable('tutte') %>%
  activate(nodes) %>%
  mutate(group = group_infomap())
Measures based on the neighborhood of each node

Description

These functions wrap a set of functions that all measure quantities of the local neighborhood of each node. They all return a vector or list matching the node position.

Usage

- `local_size(order = 1, mode = "all", mindist = 0)`
- `local_members(order = 1, mode = "all", mindist = 0)`
- `local_triangles()`
- `local_ave_degree(weights = NULL)`
- `local_transitivity(weights = NULL)`

Arguments

- `order` Integer giving the order of the neighborhood.
- `mode` Character constant, it specifies how to use the direction of the edges if a directed graph is analyzed. For 'out' only the outgoing edges are followed, so all vertices reachable from the source vertex in at most `order` steps are counted. For 'in' all vertices from which the source vertex is reachable in at most `order` steps are counted. 'all' ignores the direction of the edges. This argument is ignored for undirected graphs.
- `mindist` The minimum distance to include the vertex in the result.
- `weights` An edge weight vector. For `local_ave_degree`: If this argument is given, the average vertex strength is calculated instead of vertex degree. For `local_transitivity`: if given weighted transitivity using the approach by A. Barrat will be calculated.

Value

A numeric vector or a list (for `local_members`) with elements corresponding to the nodes in the graph.

Functions

- `local_size()`: The size of the neighborhood in a given distance from the node. (Note that the node itself is included unless `mindist > 0`). Wraps `igraph::ego_size()`.
- `local_members()`: The members of the neighborhood of each node in a given distance. Wraps `igraph::ego()`.
- `local_triangles()`: The number of triangles each node participate in. Wraps `igraph::count_triangles()`.
• `local_ave_degree()`: Calculates the average degree based on the neighborhood of each node. Wraps `igraph::knn()`.
• `local_transitivity()`: Calculate the transitivity of each node, that is, the propensity for the nodes neighbors to be connected. Wraps `igraph::transitivity()`

Examples

```r
# Get all neighbors of each graph
create_notable('chvatal') %>%
  activate(nodes) %>%
  mutate(neighborhood = local_members(mindist = 1))

# These are equivalent
create_notable('chvatal') %>%
  activate(nodes) %>%
  mutate(n_neighbors = local_size(mindist = 1),
         degree = centrality_degree()) %>%
  as_tibble()
```

map_bfs

Apply a function to nodes in the order of a breath first search

Description

These functions allow you to map over the nodes in a graph, by first performing a breath first search on the graph and then mapping over each node in the order they are visited. The mapping function will have access to the result and search statistics for all the nodes between itself and the root in the search. To map over the nodes in the reverse direction use `map_bfs_back()`.

Usage

```r
map_bfs(root, mode = "out", unreachable = FALSE, .f, ...)
map_bfs_lgl(root, mode = "out", unreachable = FALSE, .f, ...)
map_bfs_chr(root, mode = "out", unreachable = FALSE, .f, ...)
map_bfs_int(root, mode = "out", unreachable = FALSE, .f, ...)
map_bfs_dbl(root, mode = "out", unreachable = FALSE, .f, ...)
```

Arguments

- `root` The node to start the search from
- `mode` How should edges be followed? 'out' only follows outbound edges, 'in' only follows inbound edges, and 'all' follows all edges. This parameter is ignored for undirected graphs.
map_bfs

unreachable  Should the search jump to an unvisited node if the search is completed without visiting all nodes.

.f  A function to map over all nodes. See Details

...  Additional parameters to pass to .f

Details

The function provided to .f will be called with the following arguments in addition to those supplied through . . .:

- graph: The full tbl_graph object
- node: The index of the node currently mapped over
- rank: The rank of the node in the search
- parent: The index of the node that led to the current node
- before: The index of the node that was visited before the current node
- after: The index of the node that was visited after the current node.
- dist: The distance of the current node from the root
- path: A table containing node, rank, parent, before, after, dist, and result columns giving the values for each node leading to the current node. The result column will contain the result of the mapping of each node in a list.

Instead of spelling out all of these in the function it is possible to simply name the ones needed and use . . . to catch the rest.

Value

map_bfs() returns a list of the same length as the number of nodes in the graph, in the order matching the node order in the graph (that is, not in the order they are called). map_bfs_*() tries to coerce its result into a vector of the classes logical (map_bfs_lgl), character (map_bfs_chr), integer (map_bfs_int), or double (map_bfs_dbl). These functions will throw an error if they are unsuccesful, so they are type safe.

See Also

Other node map functions: map_bfs_back(), map_dfs_back(), map_dfs()

Examples

# Accumulate values along a search
create_tree(40, children = 3, directed = TRUE) %>%
  mutate(value = round(runif(40)*100)) %>%
  mutate(value_acc = map_bfs_dbl(node_is_root(), .f = function(node, path, ...) {
    sum(.N()$value[c(node, path$node)])
  }))
map_bfs_back

Apply a function to nodes in the reverse order of a breadth first search

Description

These functions allow you to map over the nodes in a graph, by first performing a breadth first search on the graph and then mapping over each node in the reverse order they are visited. The mapping function will have access to the result and search statistics for all the nodes following itself in the search. To map over the nodes in the original direction use `map_bfs()`.

Usage

map_bfs_back(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_back_lgl(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_back_chr(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_back_int(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_back_dbl(root, mode = "out", unreachable = FALSE, .f, ...)

Arguments

root
  The node to start the search from

mode
  How should edges be followed? 'out' only follows outbound edges, 'in' only follows inbound edges, and 'all' follows all edges. This parameter is ignored for undirected graphs.

unreachable
  Should the search jump to an unvisited node if the search is completed without visiting all nodes.

.f
  A function to map over all nodes. See Details

...
  Additional parameters to pass to .f

Details

The function provided to .f will be called with the following arguments in addition to those supplied through ...:

- graph: The full tbl_graph object
- node: The index of the node currently mapped over
- rank: The rank of the node in the search
- parent: The index of the node that led to the current node
- before: The index of the node that was visited before the current node
- after: The index of the node that was visited after the current node.
map_dfs

- **dist**: The distance of the current node from the root
- **path**: A table containing node, rank, parent, before, after, dist, and result columns giving the values for each node reached from the current node. The result column will contain the result of the mapping of each node in a list.

Instead of spelling out all of these in the function it is possible to simply name the ones needed and use ... to catch the rest.

**Value**

`map_bfs_back()` returns a list of the same length as the number of nodes in the graph, in the order matching the node order in the graph (that is, not in the order they are called). `map_bfs_back_`() tries to coerce its result into a vector of the classes logical (`map_bfs_back_lgl`), character (`map_bfs_back_chr`), integer (`map_bfs_back_int`), or double (`map_bfs_back_dbl`). These functions will throw an error if they are unsuccessful, so they are type safe.

**See Also**

Other node map functions: `map_bfs()`, `map_dfs_back()`, `map_dfs()`

**Examples**

```r
# Collect values from children
create_tree(40, children = 3, directed = TRUE) %>%
mutate(value = round(runif(40)*100)) %>%
mutate(child_acc = map_bfs_back_dbl(node_is_root(), .f = function(node, path, ...) {
  if (nrow(path) == 0) .N()$value[node]
  else {
    sum(unlist(path$result[path$parent == node]))
  }
})
```

---

**map_dfs**

Apply a function to nodes in the order of a depth first search

**Description**

These functions allow you to map over the nodes in a graph, by first performing a depth first search on the graph and then mapping over each node in the order they are visited. The mapping function will have access to the result and search statistics for all the nodes between itself and the root in the search. To map over the nodes in the reverse direction use `map_dfs_back()`.

**Usage**

```r
map_dfs(root, mode = "out", unreachable = FALSE, .f, ...)
map_dfs_lgl(root, mode = "out", unreachable = FALSE, .f, ...)
```
map_dfs_chr(root, mode = "out", unreachable = FALSE, .f, ...)
map_dfs_int(root, mode = "out", unreachable = FALSE, .f, ...)
map_dfs_dbl(root, mode = "out", unreachable = FALSE, .f, ...)

Arguments

root The node to start the search from
mode How should edges be followed? 'out' only follows outbound edges, 'in' only follows inbound edges, and 'all' follows all edges. This parameter is ignored for undirected graphs.
unreachable Should the search jump to an unvisited node if the search is completed without visiting all nodes.
.f A function to map over all nodes. See Details
... Additional parameters to pass to .f

Details

The function provided to .f will be called with the following arguments in addition to those supplied through ...:

- graph: The full tbl_graph object
- node: The index of the node currently mapped over
- rank: The rank of the node in the search
- rank_out: The rank of the completion of the nodes subtree
- parent: The index of the node that led to the current node
- dist: The distance of the current node from the root
- path: A table containing node, rank, rank_out, parent, dist, and result columns giving the values for each node. The result column will contain the result of the mapping of each node in a list.

Instead of spelling out all of these in the function it is possible to simply name the ones needed and use ... to catch the rest.

Value

map_dfs() returns a list of the same length as the number of nodes in the graph, in the order matching the node order in the graph (that is, not in the order they are called). map_dfs_*() tries to coerce its result into a vector of the classes logical (map_dfs_lgl), character (map_dfs_chr), integer (map_dfs_int), or double (map_dfs_dbl). These functions will throw an error if they are unsuccesful, so they are type safe.

See Also

Other node map functions: map_bfs_back(), map_bfs(), map_dfs_back()
Examples

```r
# Add a random integer to the last value along a search
create_tree(40, children = 3, directed = TRUE) %>%
  mutate(child_acc = map_dfs_int(node_is_root(), .f = function(node, path, ...) {
    last_val <- if (nrow(path) == 0) 0L else tail(unlist(path$result), 1)
    last_val + sample(1:10, 1)
  }))
```

---

map_dfs_back

**Apply a function to nodes in the reverse order of a depth first search**

Description

These functions allow you to map over the nodes in a graph, by first performing a depth first search on the graph and then mapping over each node in the reverse order they are visited. The mapping function will have access to the result and search statistics for all the nodes following itself in the search. To map over the nodes in the original direction use `map_dfs()`.

Usage

```r
map_dfs_back(root, mode = "out", unreachable = FALSE, .f, ...)
map_dfs_back_lgl(root, mode = "out", unreachable = FALSE, .f, ...)
map_dfs_back_chr(root, mode = "out", unreachable = FALSE, .f, ...)
map_dfs_back_int(root, mode = "out", unreachable = FALSE, .f, ...)
map_dfs_back_dbl(root, mode = "out", unreachable = FALSE, .f, ...)
```

Arguments

- `root` The node to start the search from
- `mode` How should edges be followed? 'out' only follows outbound edges, 'in' only follows inbound edges, and 'all' follows all edges. This parameter is ignored for undirected graphs.
- `unreachable` Should the search jump to an unvisited node if the search is completed without visiting all nodes.
- `.f` A function to map over all nodes. See Details
- `...` Additional parameters to pass to `.f`

Details

The function provided to `.f` will be called with the following arguments in addition to those supplied through `...`:

- `graph`: The full tbl_graph object
map_local

- **node**: The index of the node currently mapped over
- **rank**: The rank of the node in the search
- **rank_out**: The rank of the completion of the nodes subtree
- **parent**: The index of the node that led to the current node
- **dist**: The distance of the current node from the root
- **path**: A table containing node, rank, rank_out, parent, dist, and result columns giving the values for each node. The result column will contain the result of the mapping of each node in a list.

Instead of spelling out all of these in the function it is possible to simply name the ones needed and use `...` to catch the rest.

**Value**

`map_dfs_back()` returns a list of the same length as the number of nodes in the graph, in the order matching the node order in the graph (that is, not in the order they are called). `map_dfs_back_*()` tries to coerce its result into a vector of the classes logical (`map_dfs_back_lgl`), character (`map_dfs_back_chr`), integer (`map_dfs_back_int`), or double (`map_dfs_back_dbl`). These functions will throw an error if they are unsuccessful, so they are type safe.

**See Also**

Other node map functions: `map_bfs_back()`, `map_bfs()`, `map_dfs()`

**Examples**

```r
# Collect values from the 2 closest layers of children in a dfs search
create_tree(40, children = 3, directed = TRUE) %>%
  mutate(value = round(runif(40)*100)) %>%
  mutate(child_acc = map_dfs_back(node_is_root(), .f = function(node, path, dist, ...) {
    if (nrow(path) == 0) .N()$value[node]
    else {
      unlist(path$result[path$dist - dist <= 2])
    }
  })))
```

---

**map_local**

*Map a function over a graph representing the neighborhood of each node*

**Description**

This function extracts the neighborhood of each node as a graph and maps over each of these neighborhood graphs. Conceptually it is similar to `igraph::local_scan()`, but it borrows the type safe versions available in `map_bfs()` and `map_dfs()`.
Usage

map_local(order = 1, mode = "all", mindist = 0, .f, ...)
map_local_lgl(order = 1, mode = "all", mindist = 0, .f, ...)
map_local_chr(order = 1, mode = "all", mindist = 0, .f, ...)
map_local_int(order = 1, mode = "all", mindist = 0, .f, ...)
map_local_dbl(order = 1, mode = "all", mindist = 0, .f, ...)

Arguments

order Integer giving the order of the neighborhood.
mode Character constant, it specifies how to use the direction of the edges if a directed
graph is analyzed. For 'out' only the outgoing edges are followed, so all vertices
reachable from the source vertex in at most order steps are counted. For "in":
all vertices from which the source vertex is reachable in at most order steps are
counted. "all" ignores the direction of the edges. This argument is ignored for
undirected graphs.
mindist The minimum distance to include the vertex in the result.
.f A function to map over all nodes. See Details
... Additional parameters to pass to .f

Details

The function provided to .f will be called with the following arguments in addition to those supplied
through ...:

• neighborhood: The neighborhood graph of the node
• graph: The full tbl_graph object
• node: The index of the node currently mapped over

The neighborhood graph will contain an extra node attribute called .central_node, which will be
TRUE for the node that the neighborhood is expanded from and FALSE for everything else.

Value

map_local() returns a list of the same length as the number of nodes in the graph, in the order
matching the node order in the graph. map_local_*() tries to coerce its result into a vector of the
classes logical (map_local_lgl), character (map_local_chr), integer (map_local_int), or
double (map_local_dbl). These functions will throw an error if they are unsuccessful, so they are
type safe.
Examples

# Smooth out values over a neighborhood
create_notable('meredith') %>%
  mutate(value = rpois(graph_order(), 5)) %>%
  mutate(value_smooth = map_local_dbl(order = 2, .f = function(neighborhood, ...) {
    mean(as_tibble(neighborhood, active = 'nodes')$value)
  })))

morph

Create a temporary alternative representation of the graph to compute on

Description

The morph/unmorph verbs are used to create temporary representations of the graph, such as e.g. its search tree or a subgraph. A morphed graph will accept any of the standard dplyr verbs, and changed to the data is automatically propagated to the original graph when unmorphing. Tidygraph comes with a range of morphers, but is it also possible to supply your own. See Details for the requirement for custom morphers. The crystallise verb is used to extract the temporary graph representation into a tibble containing one separate graph per row and a name and graph column holding the name of each graph and the graph itself respectively. convert() is a shorthand for performing both morph and crystallise along with extracting a single tbl_graph (defaults to the first). For morphs were you know they only create a single graph, and you want to keep it, this is an easy way.

Usage

morph(.data, .f, ...)

unmorph(.data)

crystallise(.data)

crystallize(.data)

convert(.data, .f, ..., .select = 1, .clean = FALSE)

Arguments

.data A tbl_graph or a morphed_tbl_graph

.f A morphing function. See morphers for a list of provided one.

... Arguments passed on to the morpher

.select The graph to return during convert(). Either an index or the name as created during crystallise().

.clean Should references to the node and edge indexes in the original graph be removed when using convert
Details

It is only possible to change and add to node and edge data from a morphed state. Any filtering/removal of nodes and edges will not result in removal from the main graph. However, nodes and edges not present in the morphed state will be unaffected in the main graph when unmorphing (if new columns were added during the morphed state they will be filled with NA).

Morphing an already morphed graph will unmorph prior to applying the new morph.

During a morphed state, the mapping back to the original graph is stored in .tidygraph_node_index and .tidygraph_edge_index columns. These are accessible but protected, meaning that any changes to them with e.g. mutate will be ignored. Furthermore, if the morph results in the merging of nodes and/or edges the original data is stored in a .data column. This is protected as well.

When supplying your own morphers the morphing function should accept a tbl_graph as its first input. The provided graph will already have nodes and edges mapped with a .tidygraph_node_index and .tidygraph_edge_index column. The return value must be a tbl_graph or a list of tbl_graphs and these must contain either a .tidygraph_node_index column or a .tidygraph_edge_index column (or both). Note that it is possible for the morph to have the edges mapped back to the original nodes and vice versa (e.g. as with to_linegraph). In that case the edge data in the morphed graph(s) will contain a .tidygraph_node_index column and/or the node data a .tidygraph_edge_index column. If the morphing results in the collapse of multiple columns or edges the index columns should be converted to list columns mapping the new node/edge back to all the nodes/edges it represents. Furthermore the original node/edge data should be collapsed to a list of tibbles, with the row order matching the order in the index column element.

Value

A morphed tbl_graph

Examples

```r
create_notable('meredith') %>%
mutate(group = group_infomap()) %>%
morph(to_contracted, group) %>%
mutate(group_centrality = centrality_pagerank()) %>%
unmorph()
```

---

### morphers

<table>
<thead>
<tr>
<th>Functions to generate alternate representations of graphs</th>
</tr>
</thead>
</table>

Description

These functions are meant to be passed into `morph()` to create a temporary alternate representation of the input graph. They are thus not meant to be called directly. See below for detail of each morpher.
Usage

to_linegraph(graph)
to_subgraph(graph, ..., subset_by = NULL)
to_subcomponent(graph, node)
to_split(graph, ..., split_by = NULL)
to_components(graph, type = "weak")
to_complement(graph, loops = FALSE)
to_local_neighborhood(graph, node, order = 1, mode = "all")
to_dominator_tree(graph, root, mode = "out")
to_minimum_spanning_tree(graph, weights = NULL)
to_shortest_path(graph, from, to, mode = "out", weights = NULL)
to_bfs_tree(graph, root, mode = "out", unreachable = FALSE)
to_dfs_tree(graph, root, mode = "out", unreachable = FALSE)
to_simple(graph, remove_multiples = TRUE, remove_loops = TRUE)
to_contracted(graph, ..., simplify = TRUE)
to_unfolded_tree(graph, root, mode = "out")
to_directed(graph)
to_undirected(graph)
to_hierarchical_clusters(graph, method = "walktrap", weights = NULL, ...)

Arguments

graph A tbl_graph

... Arguments to pass on to filter(), group_by(), or the cluster algorithm (see igraph::cluster_walktrap(), igraph::cluster_leading_eigen(), and igraph::cluster_edge_betweenness())

subset_by, split_by Whether to create subgraphs based on nodes or edges

node The center of the neighborhood for to_local_neighborhood() and the node to that should be included in the component for to_subcomponent()

type The type of component to split into. Either 'weak' or 'strong'
loops  Should loops be included. Defaults to FALSE
order  The radius of the neighborhood
mode  How should edges be followed? 'out' only follows outbound edges, 'in' only follows inbound edges, and 'all' follows all edges. This parameter is ignored for undirected graphs.
root  The root of the tree
weights  Optional edge weights for the calculations
from, to  The start and end node of the path
unreachable  Should the search jump to a node in a new component when stuck.
remove_multiples  Should edges that run between the same nodes be reduced to one
remove_loops  Should edges that start and end at the same node be removed
simplify  Should edges in the contracted graph be simplified? Defaults to TRUE
method  The clustering method to use. Either 'walktrap', 'leading_eigen', or 'edge_betweenness'

Value
A list of tbl_graphs

Functions

- to_linegraph(): Convert a graph to its line graph. When unmorphing node data will be merged back into the original edge data. Edge data will be ignored.
- to_subgraph(): Convert a graph to a single subgraph. ... is evaluated in the same manner as filter. When unmorphing all data in the subgraph will get merged back.
- to_subcomponent(): Convert a graph to a single component containing the specified node
- to_split(): Convert a graph into a list of separate subgraphs. ... is evaluated in the same manner as group_by. When unmorphing all data in the subgraphs will get merged back, but in the case of split_by = 'edges' only the first instance of node data will be used (as the same node can be present in multiple subgraphs).
- to_components(): Split a graph into its separate components. When unmorphing all data in the subgraphs will get merged back.
- to_complement(): Convert a graph into its complement. When unmorphing only node data will get merged back.
- to_local_neighborhood(): Convert a graph into the local neighborhood around a single node. When unmorphing all data will be merged back.
- to_dominator_tree(): Convert a graph into its dominator tree based on a specific root. When unmorphing only node data will get merged back.
- to_minimum_spanning_tree(): Convert a graph into its minimum spanning tree/forest. When unmorphing all data will get merged back.
- to_shortest_path(): Limit a graph to the shortest path between two nodes. When unmorphing all data is merged back.
• to_bfs_tree(): Convert a graph into a breath-first search tree based on a specific root. When unmorphing only node data is merged back.
• to_dfs_tree(): Convert a graph into a depth-first search tree based on a specific root. When unmorphing only node data is merged back.
• to_simple(): Collapse parallel edges and remove loops in a graph. When unmorphing all data will get merged back.
• to_contracted(): Combine multiple nodes into one. ... is evaluated in the same manner as group_by. When unmorphing all data will get merged back.
• to_unfolded_tree(): Unfold a graph to a tree or forest starting from multiple roots (or one), potentially duplicating nodes and edges.
• to_directed(): Make a graph directed in the direction given by from and to
• to_undirected(): Make a graph undirected
• to_hierarchical_clusters(): Convert a graph into a hierarchical clustering based on a grouping

Examples

# Compute only on a subgraph of every even node
create_notable('meredith') %>%
morph(to_subgraph, seq_len(graph_order()) %% 2 == 0) %>%
mutate(neighbour_count = centrality_degree()) %>%
unmorph()

node_measures

Querying node measures

Description

These functions are a collection of node measures that do not really fall into the class of centrality measures. For lack of a better place they are collected under the node_* umbrella of functions.

Usage

node_eccentricity(mode = "out")
node_constraint(weights = NULL)
node_coreness(mode = "out")
node_diversity(weights)
node_bridging_score()
node_effective_network_size()
node_measures

node_connectivity_impact()
node_closeness_impact()
node_fareness_impact()

Arguments

node The way edges should be followed in the case of directed graphs.
weights The weights to use for each node during calculation

Value

A numeric vector of the same length as the number of nodes in the graph.

Functions

- node_eccentricity(): measure the maximum shortest path to all other nodes in the graph
- node_constraint(): measures Burts constraint of the node. See igraph::constraint()
- node_coreness(): measures the coreness of each node. See igraph::coreness()
- node_diversity(): measures the diversity of the node. See igraph::diversity()
- node_bridging_score(): measures Valente's Bridging measures for detecting structural bridges (influenceR)
- node_effective_network_size(): measures Burt's Effective Network Size indicating access to structural holes in the network (influenceR)
- node_connectivity_impact(): measures the impact on connectivity when removing the node (NetSwan)
- node_closeness_impact(): measures the impact on closeness when removing the node (NetSwan)
- node_fareness_impact(): measures the impact on fareness (distance between all node pairs) when removing the node (NetSwan)

Examples

# Calculate Burt's Constraint for each node
create_notable('meredith') %>%
  mutate(b_constraint = node_constraint())
Calculate node ranking

Description
This set of functions tries to calculate a ranking of the nodes in a graph so that nodes sharing certain topological traits are in proximity in the resulting order. These functions are of great value when composing matrix layouts and arc diagrams but could conceivably be used for other things as well.

Usage

```r
node_rank_hclust(
  method = "average",
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_anneal(
  cool = 0.5,
  tmin = 1e-04,
  swap_to_inversion = 0.5,
  step_multiplier = 100,
  reps = 1,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_branch_bound(
  weighted_gradient = FALSE,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_traveller(
  method = "two_opt",
  ...,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)
```
node_rank

node_rank_two(
    dist = "shortest",
    mode = "out",
    weights = NULL,
    algorithm = "automatic"
)

node_rank_mds(
    method = "cmdscale",
    dist = "shortest",
    mode = "out",
    weights = NULL,
    algorithm = "automatic"
)

node_rank_leafsort(
    method = "average",
    type = "OLO",
    dist = "shortest",
    mode = "out",
    weights = NULL,
    algorithm = "automatic"
)

node_rank_visual(
    dist = "shortest",
    mode = "out",
    weights = NULL,
    algorithm = "automatic"
)

node_rank_spectral(
    normalized = FALSE,
    dist = "shortest",
    mode = "out",
    weights = NULL,
    algorithm = "automatic"
)

node_rank_spin_out(
    step = 25,
    nstart = 10,
    dist = "shortest",
    mode = "out",
    weights = NULL,
    algorithm = "automatic"
)
node_rank_spin_in(
    step = 5,
    sigma = seq(20, 1, length.out = 10),
    dist = "shortest",
    mode = "out",
    weights = NULL,
    algorithm = "automatic"
)

node_rank_quadratic(
    criterion = "2SUM",
    reps = 1,
    step = 2 * graph_order(),
    step_multiplier = 1.1,
    temp_multiplier = 0.5,
    maxsteps = 50,
    dist = "shortest",
    mode = "out",
    weights = NULL,
    algorithm = "automatic"
)

node_rank_genetic(
    ...
)

node_rank_dendser(
    ...
)

Arguments

method The method to use. See Functions section for reference
dist The algorithm to use for deriving a distance matrix from the graph. One of
    • "shortest" (default): Use the shortest path between all nodes
    • "euclidean": Calculate the L2 norm on the adjacency matrix of the graph
    • "manhattan": Calculate the L1 norm on the adjacency matrix of the graph
    • "maximum": Calculate the supremum norm on the adjacency matrix of the graph
node_rank

- "canberra": Calculate a weighted manhattan distance on the adjacency matrix of the graph
- "binary": Calculate distance as the proportion of agreement between nodes based on the adjacency matrix of the graph

or a function that takes a tbl_graph and return a dist object with a size matching the order of the graph.

mode Which edges should be included in the distance calculation. For distance measures based on the adjacency matrix, 'out' will use the matrix as is, 'in' will use the transpose, and 'all' will take the mean of the two. Defaults to 'out'. Ignored for undirected graphs.

weights An edge variable to use as weight for the shortest path calculation if dist = 'shortest'

algorithm The algorithm to use for the shortest path calculation if dist = 'shortest'
cool cooling rate
tmin minimum temperature
swap_to_inversion Proportion of swaps in local neighborhood search
step_multiplier Multiplication factor for number of iterations per temperature
reps Number of repeats with random initialisation
weighted_gradient minmize the weighted gradient measure? Defaults to FALSE

... Arguments passed on to other algorithms. See Functions section for reference
type The type of leaf reordering, either 'GW' to use the "GW" method or 'OLO' to use the "OLO" method (both in seriation)
normalized Should the normalized laplacian of the similarity matrix be used?
step The number iterations to run per initialisation
nstart The number of random initialisations to perform
sigma The variance around the diagonal to use for the weight matrix. Either a single number or a decreasing sequence.
criterion The criterion to minimize. Either "LS" (Linear Seriation Problem), "2SUM" (2-Sum Problem), "BAR" (Banded Anti-Robinson form), or "Inertia" (Inertia criterion)
temp_multiplier Temperature multiplication factor between 0 and 1
maxsteps The upper bound of iterations

Value

An integer vector giving the position of each node in the ranking
Functions

- `node_rank_hclust()`: Use hierarchical clustering to rank nodes (see `stats::hclust()` for allowed methods)
- `node_rank_anneal()`: Use simulated annealing based on the "ARSA" method in `seriation`
- `node_rank_branch_bound()`: Use branch and bounds strategy to minimize the gradient measure (only feasible for small graphs). Will use "BBURCG" or "BBWRCG" in `seriation` dependent on the `weighted_gradient` argument
- `node_rank_traveller()`: Minimize hamiltonian path length using a travelling salesperson solver. See the the `solve_TSP` function in `TSP` for an overview of possible arguments
- `node_rank_two()`: Use Rank-two ellipse seriation to rank the nodes. Uses "R2E" method in `seriation`
- `node_rank_mds()`: Rank by multidimensional scaling onto one dimension. `method = 'cmdscale'` will use the classic scaling from `stats`, `method = 'isoMDS'` will use `isoMDS` from `MASS`, and `method = 'sammon'` will use `sammon` from `MASS`
- `node_rank_leafsort()`: Minimize hamiltonian path length by reordering leafs in a hierarchical clustering. Method refers to the clustering algorithm (either 'average', 'single', 'complete', or 'ward')
- `node_rank_visual()`: Use Prim’s algorithm to find a minimum spanning tree giving the rank. Uses the "VAT" method in `seriation`
- `node_rank_spectral()`: Minimize the 2-sum problem using a relaxation approach. Uses the "Spectral" or "Spectral_norm" methods in `seriation` depending on the value of the `norm` argument
- `node_rank_spin_out()`: Sorts points into neighborhoods by pushing large distances away from the diagonal. Uses the "SPIN_STS" method in `seriation`
- `node_rank_spin_in()`: Sorts points into neighborhoods by concentrating low distances around the diagonal. Uses the "SPIN_NH" method in `seriation`
- `node_rank_quadratic()`: Use quadratic assignment problem formulations to minimize criterions using simulated annealing. Uses the "QAP_LS", "QAP_2SUM", "QAP_BAR", or "QAP_Inertia" methods from `seriation` dependant on the `criterion` argument
- `node_rank_genetic()`: Optimizes different criteria based on a genetic algorithm. Uses the "GA" method from `seriation`. See `register_GA` for an overview of relevant arguments
- `node_rank_dendser()`: Optimizes different criteria based on heuristic dendrogram seriation. Uses the "DendSer" method from `seriation`. See `register_DendSer` for an overview of relevant arguments

Examples

```r
graph <- create_notable('zachary') %>%
  mutate(rank = node_rank_hclust())
```
node_topology

Node properties related to the graph topology

Description

These functions calculate properties that are dependent on the overall topology of the graph.

Usage

node_dominator(root, mode = "out")

node_topo_order(mode = "out")

Arguments

root

The node to start the dominator search from

mode

How should edges be followed. Either 'in' or 'out'

Value

A vector of the same length as the number of nodes in the graph

Functions

• node_dominator(): Get the immediate dominator of each node. Wraps igraph::dominator_tree().
• node_topo_order(): Get the topological order of nodes in a DAG. Wraps igraph::topo_sort().

Examples

# Sort a graph based on its topological order
create_tree(10, 2) %>%
  arrange(sample(graph_order())) %>%
  mutate(old_ind = seq_len(graph_order())) %>%
  arrange(node_topo_order())

node_types

Querying node types

Description

These functions all lets the user query whether each node is of a certain type. All of the functions returns a logical vector indicating whether the node is of the type in question. Do note that the types are not mutually exclusive and that nodes can thus be of multiple types.
Usage

node_is_cut()
node_is_root()
node_is_leaf()
node_is_sink()
node_is_source()
node_is_isolated()
node_is_universal(mode = "out")
node_is_simplical(mode = "out")
node_is_center(mode = "out")
node_is_adjacent(to, mode = "all", include_to = TRUE)
node_is_keyplayer(k, p = 0, tol = 1e-04, maxsec = 120, roundsec = 30)

Arguments

mode The way edges should be followed in the case of directed graphs.
to The nodes to test for adjacency to
include_to Should the nodes in to be marked as adjacent as well
k The number of keyplayers to identify
p The probability to accept a lesser state
tol Optimisation tolerance, below which the optimisation will stop
maxsec The total computation budget for the optimization, in seconds
roundsec Number of seconds in between synchronizing workers’ answer

Value

A logical vector of the same length as the number of nodes in the graph.

Functions

• node_is_cut(): is the node a cut node (articulation node)
• node_is_root(): is the node a root in a tree
• node_is_leaf(): is the node a leaf in a tree
• node_is_sink(): does the node only have incoming edges
• node_is_source(): does the node only have outgoing edges
pair_measures

- node_is_isolated(): is the node unconnected
- node_is_universal(): is the node connected to all other nodes in the graph
- node_is_simplical(): are all the neighbors of the node connected
- node_is_center(): does the node have the minimal eccentricity in the graph
- node_is_adjacent(): is a node adjacent to any of the nodes given in to
- node_is_keyplayer(): Is a node part of the keyplayers in the graph (influenceR)

Examples

```r
# Find the root and leaves in a tree
create_tree(40, 2) %>%
  mutate(root = node_is_root(), leaf = node_is_leaf())
```

Description

This set of functions can be used for calculations that involve node pairs. If the calculateable measure is not symmetric the function will come in two flavours, differentiated with _to_/ _from suffix. The *_to() functions will take the provided node indexes as the target node (recycling if necessary). For the *_from() functions the provided nodes are taken as the source. As for the other wrappers provided, they are intended for use inside the tidygraph framework and it is thus not necessary to supply the graph being computed on as the context is known.

Usage

```r
node_adhesion_to(nodes)
node_adhesion_from(nodes)
node_cohesion_to(nodes)
node_cohesion_from(nodes)
node_distance_to(nodes, mode = "out", weights = NULL, algorithm = "automatic")
node_distance_from(nodes, mode = "out", weights = NULL, algorithm = "automatic")
node_cocitation_with(nodes)
```
node_bibcoupling_with(nodes)

node_similarity_with(nodes, mode = "out", loops = FALSE, method = "jaccard")

node_max_flow_to(nodes, capacity = NULL)

node_max_flow_from(nodes, capacity = NULL)

Arguments

nodes The other part of the node pair (the first part is the node defined by the row). Recycled if necessary.

mode How should edges be followed? If 'all' all edges are considered, if 'in' only inbound edges are considered, and if 'out' only outbound edges are considered.

weights The weights to use for calculation.

algorithm The distance algorithms to use. By default it will try to select the fastest suitable algorithm. Possible values are "automatic", "unweighted", "dijkstra", "bellman-ford", and "johnson"

loops Should loop edges be considered?

method The similarity measure to calculate. Possible values are: "jaccard", "dice", and "invlogweighted"

capacity The edge capacity to use.

Value

A numeric vector of the same length as the number of nodes in the graph.

Functions

- node_adhesion_to(): Calculate the adhesion to the specified node. Wraps igraph::edge_connectivity()
- node_adhesion_from(): Calculate the adhesion from the specified node. Wraps igraph::edge_connectivity()
- node_cohesion_to(): Calculate the cohesion to the specified node. Wraps igraph::vertex_connectivity()
- node_cohesion_from(): Calculate the cohesion from the specified node. Wraps igraph::vertex_connectivity()
- node_distance_to(): Calculate various distance metrics between node pairs. Wraps igraph::distances()
- node_distance_from(): Calculate various distance metrics between node pairs. Wraps igraph::distances()
- node_cocitation_with(): Calculate node pair cocitation count. Wraps igraph::cocitation()
- node_bibcoupling_with(): Calculate node pair bibliographic coupling. Wraps igraph::bibcoupling()
- node_similarity_with(): Calculate various node pair similarity measures. Wraps igraph::similarity()
- node_max_flow_to(): Calculate the maximum flow to a node. Wraps igraph::max_flow()
- node_max_flow_from(): Calculate the maximum flow from a node. Wraps igraph::max_flow()

Examples

# Calculate the distance to the center node
create_notable('meredith') %>%
  mutate(dist_to_center = node_distance_to(node_is_center()))
reroute

Description

The reroute verb lets you change the beginning and end node of edges by specifying the new indexes of the start and/or end node(s). Optionally only a subset of the edges can be rerouted using the subset argument, which should be an expression that are to be evaluated in the context of the edge data and should return an index compliant vector (either logical or integer).

Usage

reroute(.data, from = NULL, to = NULL, subset = NULL)

Arguments

- `.data`: A tbl_graph or morphed_tbl_graph object. grouped_tbl_graph will be ungrouped prior to rerouting
- `from, to`: The new indexes of the terminal nodes. If NULL nothing will be changed
- `subset`: An expression evaluating to an indexing vector in the context of the edge data.

Value

An object of the same class as `.data`

Examples

# Switch direction of edges
create_notable('meredith') %>%
  activate(edges) %>%
  reroute(from = to, to = from)

# Using subset
create_notable('meredith') %>%
  activate(edges) %>%
  reroute(from = 1, subset = to > 10)

dsampling_games

Graph games based on direct sampling

Description

This set of graph games creates graphs directly through sampling of different attributes, topologies, etc. The nature of their algorithm is described in detail at the linked igraph documentation.
Usage

play_degree(out_degree, in_degree = NULL, method = "simple")

play_dotprod(position, directed = TRUE)

play_fitness(m, out_fit, in_fit = NULL, loops = FALSE, multiple = FALSE)

play_fitness_power(
  n,
  m,
  out_exp,
  in_exp = -1,
  loops = FALSE,
  multiple = FALSE,
  correct = TRUE
)

play_erdos_renyi(n, p, m, directed = TRUE, loops = FALSE)

play_geometry(n, radius, torus = FALSE)

Arguments

out_degree, in_degree
  The degrees of each node in the graph
method
  The algorithm to use for the generation. Either 'simple', 'vl', or 'simple.no.multiple'
position
  The latent position of each node by column.
directed
  Should the resulting graph be directed
m
  The number of edges in the graph
out_fit, in_fit
  The fitness of each node
loops
  Are loop edges allowed
multiple
  Are multiple edges allowed
n
  The number of nodes in the graph.
out_exp, in_exp
  Power law exponent of degree distribution
correct
  Use finite size correction
p
  The probability of an edge occurring
radius
  The radius within which vertices are connected
torus
  Should the vertices be distributed on a torus instead of a plane

Value

A tbl_graph object
Functions

- `play_degree()`: Create graphs based on the given node degrees. See `igraph::sample_degseq()`
- `play_dotprod()`: Create graphs with link probability given by the dot product of the latent position of terminating nodes. See `igraph::sample_dot_product()`
- `play_fitness()`: Create graphs where edge probabilities are proportional to terminal node fitness scores. See `igraph::sample_fitness()`
- `play_fitness_power()`: Create graphs with an expected power-law degree distribution. See `igraph::sample_fitness_pl()`
- `play_erdos_renyi()`: Create graphs with a fixed edge probability or count. See `igraph::sample_gnp()` and `igraph::sample_gnm()`
- `play_geometry()`: Create graphs by positioning nodes on a plane or torus and connecting nearby ones. See `igraph::sample_grg()`

See Also

Other graph games: `component_games`, `evolution_games`, `type_games`

Examples

```r
plot(play_erdos_renyi(20, 0.3))
```

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**search_graph**

*Search a graph with depth first and breadth first*

**Description**

These functions wraps the `igraph::bfs()` and `igraph::dfs()` functions to provide a consistent return value that can be used in `dplyr::mutate()` calls. Each function returns an integer vector with values matching the order of the nodes in the graph.

**Usage**

```r
bfs_rank(root, mode = "out", unreachable = FALSE)

bfs_parent(root, mode = "out", unreachable = FALSE)

bfs_before(root, mode = "out", unreachable = FALSE)

bfs_after(root, mode = "out", unreachable = FALSE)

bfs_dist(root, mode = "out", unreachable = FALSE)

dfs_rank(root, mode = "out", unreachable = FALSE)

dfs_rank_out(root, mode = "out", unreachable = FALSE)
```
dfs_parent(root, mode = "out", unreachable = FALSE)

dfs_dist(root, mode = "out", unreachable = FALSE)

Arguments

root
The node to start the search from

mode
How edges are followed in the search if the graph is directed. "out" only follows outbound edges, "in" only follows inbound edges, and "all" or "total" follows all edges. This is ignored for undirected graphs.

unreachable
Should the search jump to a new component if the search is terminated without all nodes being visited? Default to FALSE (only reach connected nodes).

Value
An integer vector, the nature of which is determined by the function.

Functions

• bfs_rank(): Get the succession in which the nodes are visited in a breath first search
• bfs_parent(): Get the nodes from which each node is visited in a breath first search
• bfs_before(): Get the node that was visited before each node in a breath first search
• bfs_after(): Get the node that was visited after each node in a breath first search
• bfs_dist(): Get the number of nodes between the root and each node in a breath first search
• dfs_rank(): Get the succession in which the nodes are visited in a depth first search
• dfs_rank_out(): Get the succession in which each nodes subtree is completed in a depth first search
• dfs_parent(): Get the nodes from which each node is visited in a depth first search
• dfs_dist(): Get the number of nodes between the root and each node in a depth first search

Examples

# Get the depth of each node in a tree
create_tree(10, 2) %>%
  activate(nodes) %>%
  mutate(depth = bfs_dist(root = 1))

# Reorder nodes based on a depth first search from node 3
create_notable('franklin') %>%
  activate(nodes) %>%
  mutate(order = dfs_rank(root = 3)) %>%
  arrange(order)
Graph games based on different node types

Description

This set of games are build around different types of nodes and simulating their interaction. The nature of their algorithm is described in detail at the linked igraph documentation.

Usage

```r
play_preference(
  n,
  n_types,
  p_type = rep(1, n_types),
  p_pref = matrix(1, n_types, n_types),
  fixed = FALSE,
  directed = TRUE,
  loops = FALSE
)
```

```r
play_preference_asym(
  n,
  n_types,
  p_type = matrix(1, n_types, n_types),
  p_pref = matrix(1, n_types, n_types),
  loops = FALSE
)
```

```r
play_bipartite(n1, n2, p, m, directed = TRUE, mode = "out")
```

```r
play_traits(
  n,
  n_types,
  growth = 1,
  p_type = rep(1, n_types),
  p_pref = matrix(1, n_types, n_types),
  callaway = TRUE,
  directed = TRUE
)
```

```r
play_citation_type(
  n,
  growth,
  types = rep(0, n),
  p_pref = rep(1, length(unique(types))),
  directed = TRUE
)
```
Arguments

n, n1, n2  The number of nodes in the graph. For bipartite graphs n1 and n2 specifies the number of nodes of each type.
n_types  The number of different node types in the graph
p_type  The probability that a node will be the given type. Either a vector or a matrix, depending on the game
p_pref  The probability that an edge will be made to a type. Either a vector or a matrix, depending on the game
fixed  Should n_types be understood as a fixed number of nodes for each type rather than as a probability
directed  Should the resulting graph be directed
loops  Are loop edges allowed
p  The probability of an edge occurring
m  The number of edges in the graph
mode  The flow direction of edges
growth  The number of edges added at each iteration
callaway  Use the callaway version of the trait based game
types  The type of each node in the graph, enumerated from 0

Value

A tbl_graph object

Functions

- play_preference(): Create graphs by linking nodes of different types based on a defined probability. See igraph::sample_pref()
- play_preference_asym(): Create graphs by linking nodes of different types based on an asymmetric probability. See igraph::sample_asym_pref()
- play_bipartite(): Create bipartite graphs of fixed size and edge count or probability. See igraph::sample_bipartite()
- play_traits(): Create graphs by evolving a graph with type based edge probabilities. See igraph::sample_traits() and igraph::sample_traits_callaway()
- play_citation_type(): Create citation graphs by evolving with type based linking probability. See igraph::sample_cit_types() and igraph::sample_cit_cit_types()

See Also

Other graph games: component_games, evolution_games, sampling_games

Examples

plot(play_bipartite(20, 30, 0.4))
**with_graph**

**Evaluate a tidygraph algorithm in the context of a graph**

**Description**

All tidygraph algorithms are meant to be called inside tidygraph verbs such as `mutate()`, where the graph that is currently being worked on is known and thus not needed as an argument to the function. In the off chance that you want to use an algorithm outside of the tidygraph framework you can use `with_graph()` to set the graph context temporarily while the algorithm is being evaluated.

**Usage**

```r
with_graph(graph, expr)
```

**Arguments**

- `graph` The `tbl_graph` to use as context
- `expr` The expression to evaluate

**Value**

The value of `expr`

**Examples**

```r
gr <- play_erdos_renyi(10, 0.3)
with_graph(gr, centrality_degree())
```
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