

Package ‘varjmcm’

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Type Package

Title Estimations for the Covariance of Estimated Parameters in Joint Mean-Covariance Models

Version 0.1.0

Description The goal of the package is to equip the 'jmcm' package (current version 0.1.8.0) with estimations of the covariance of estimated parameters. Two methods are provided. The first method is to use the inverse of estimated Fisher's information matrix, see M. Pourahmadi (2000) <doi:10.1093/biomet/87.2.425>, M. Maadooliat, M. Pourahmadi and J. Z. Huang (2013) <doi:10.1007/s11222-011-9284-6>, and W. Zhang, C. Leng, C. Tang (2015) <doi:10.1111/rssb.12065>. The second method is bootstrap based, see Liu, R. Y. (1988) <doi:10.1214/aos/1176351062> for reference.

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Encoding UTF-8

LazyData true

Depends jmcm

Imports expm, MASS, stats, Matrix

RoxygenNote 6.0.1

NeedsCompilation no

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bootcovjmcm	<i>Estimate the covariance of estimated parameters using a bootstrap based method</i>
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Description

bootcovjmcm gives the estimation of the covariance of estimated parameters returned by jmcm by using a bootstrap based method.

Usage

```
bootcovjmcm(object, mydata, numboot)
```

Arguments

object	a fitted joint mean-covariance model of class "jmcmMod", returned by the function jmcm.
mydata	the data frame used in fitting the model.
numboot	the number of the bootstrap replications

Value

an estimated covariance matrix of the estimated parameters.

References

[1] Liu, R. Y. (1988) "Bootstrap Procedure under Some Non-i.i.d. Models." *Annals of Statistics*, 16, 1696-1708.

Examples

```
cattleA <- cattle[cattle$group=='A', ]
fit.mcd <- jmcm(weight|id|I(ceiling(day/14+1))~1|1,
               data = cattleA,
               cov.method = "mcd",
               triple = c(1,1,1))
bootcovjmcm(fit.mcd, cattleA, 5)
## Larger number of replications is needed to achieve accuracy,
## however it may take hours.
bootcovjmcm(fit.mcd, cattleA, 500)
```

covjmcm	<i>Estimate the covariance of estimated parameters using the explicit formula</i>
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Description

covjmcm is a combination of covjmcm_mcd, covjmcm_acd, and covjmcm_hpc. It identifies the corresponding type of the model, i.e. MCD, ACD, or HPC, and calculates the estimation of the covariance of estimated parameters using explicit formula, which is the inverse of the estimated Fisher's information matrix.

Usage

```
covjmcm(object)
```

Arguments

object	a fitted joint mean-covariance model of class "jmcmMod", returned by the function jmcm.
--------	---

Value

an estimated covariance matrix of the estimated parameters.

References

- [1] Pourahmadi, M., "Maximum likelihood estimation of generalised linear models for multivariate normal covariance matrix," *Biometrika* 87(2), 425–435 (2000).
- [2] M. Maadooliat, M. Pourahmadi and J. Z. Huang, "Robust estimation of the correlation matrix of longitudinal data", *Statistics and Computing* 23, 17-28, (2013).
- [3] W. Zhang, C. Leng, and C. Y. Tang(2015), "A joint modelling approach for longitudinal studies," *Journal of the Royal Statistical Society. Series B.* 77, 219-238.

See Also

[covjmcm_mcd](#), [covjmcm_acd](#), and [covjmcm_hpc](#)

Examples

```
## balanced data
cattleA <- cattle[cattle$group=='A', ]
fit.mcd <- jmcm(weight|id|I(ceiling(day/14+1))~1|1,
               data = cattleA, cov.method = "mcd",
               triple = c(8,3,4))
cov.mcd <- covjmcm(fit.mcd) ##same as covjmcm_mcd(fit.mcd)
## unbalanced data
## This may take about 1.25 min.
```

```
fit.hpc <- jmcm(I(sqrt(cd4)) | id | time ~ 1 | 1,
               data = aids, triple = c(8,1,1),
               cov.method = "hpc")
cov.hpc <- covjmcm(fit.hpc) ##same as covjmcm_hpc(fit.hpc)
```

covjmcm_acd	<i>Calculate the estimation of the covariance of estimated parameters in a ACD model, via the explicit formula.</i>
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Description

covjmcm_acd calculates the estimation of the covariance of estimated parameters in a ACD model using the explicit formula, which is the inverse of the estimated Fisher's information matrix.

Usage

```
covjmcm_acd(object)
```

Arguments

object	a fitted joint mean-covariance model of class "jmcmMod", returned by the function jmcm.
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Value

an estimated covariance matrix of the estimated parameters in a ACD model.

References

[1] M. Maadooliat, M. Pourahmadi and J. Z. Huang, "Robust estimation of the correlation matrix of longitudinal data", *Statistics and Computing* 23, 17-28, (2013).

See Also

[covjmcm](#), [covjmcm_mcd](#), and [covjmcm_hpc](#)

Examples

```
##This may take more than 5s.

cattleA <- cattle[cattle$group=='A', ]
fit.acd <- jmcm(weight|id|I(ceiling(day/14+1))~1|1,
               data = cattleA, cov.method = "acd",
               triple = c(8,3,4))
cov.acd <- covjmcm_acd(fit.acd)
```

covjmcm_hpc	<i>Calculate the estimation of the covariance of estimated parameters in a HPC model, via the explicit formula.</i>
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Description

covjmcm_hpc gives the estimation of the covariance of estimated parameters in a HPC model using the explicit formula, which is the inverse of the estimated Fisher's information matrix.

Usage

```
covjmcm_hpc(object)
```

Arguments

object	a fitted joint mean-covariance model of class "jmcmMod", returned by the function jmcm.
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Value

an estimated covariance matrix of the estimated parameters in a HPC model.

References

[1] W. Zhang, C. Leng, and C. Y. Tang(2015), "A joint modelling approach for longitudinal studies," Journal of the Royal Statistical Society. Series B. 77, 219-238.

See Also

[covjmcm](#), [covjmcm_mcd](#), and [covjmcm_acd](#)

Examples

```
##This may take more than 5s.  
  
cattleA <- cattle[cattle$group=='A', ]  
fit.hpc <- jmcm(weight|id|I(ceiling(day/14+1))~1|1,  
              data = cattleA, cov.method = "hpc",  
              triple = c(8,3,4))  
cov.hpc <- covjmcm_hpc(fit.hpc)
```

covjmcm_mcd	<i>Calculate the estimation of the covariance of estimated parameters in a MCD model, via the explicit formula.</i>
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Description

covjmcm_mcd gives an estimation of the covariance of estimated parameters in a MCD model using the explicit formula, which is the inverse of the estimated Fisher's information matrix.

Usage

```
covjmcm_mcd(object)
```

Arguments

object	a fitted joint mean-covariance model of class "jmcmMod", returned by the function jmcm.
--------	---

Value

an estimated covariance matrix of the estimated parameters in a MCD model.

References

[1] Pourahmadi, M., "Maximum likelihood estimation of generalised linear models for multivariate normal covariance matrix," *Biometrika* 87(2), 425–435 (2000).

See Also

[covjmcm](#), [covjmcm_acd](#), and [covjmcm_hpc](#)

Examples

```
cattleA <- cattle[cattle$group=='A', ]
fit.mcd <- jmcm(weight|id|I(ceiling(day/14+1))~1|1,
               data = cattleA, cov.method = "mcd",
               triple = c(8,3,4))
cov.mcd <- covjmcm_mcd(fit.mcd)
```

varjmcm

varjmcm: Estimations for the Covariance of Estimated Parameters in Joint Mean-Covariance Models

Description

The package provides estimations of the covariance of estimated parameters in joint mean-covariance models, which is fitted in 'jmcm' package. Two methods are available. `bootcovjmcm` calculates the covariance estimation via a bootstrap based method. `covjmcm` uses explicit formula, i.e. the inverse of the estimated Fisher's information, to calculate the covariance estimation. The bootstrap method may need large number of replications and thus may be time consuming. The explicit formula in the second method is asymptotically correct, and thus is valid only when the sample size is large.

References

- [1] Pan J, Pan Y (2017). "jmcm: An R Package for Joint Mean-Covariance Modeling of Longitudinal Data." *Journal of Statistical Software*, 82(9), 1–29.
- [2] Pourahmadi, M., "Maximum likelihood estimation of generalised linear models for multivariate normal covariance matrix," *Biometrika* 87(2), 425–435 (2000).
- [3] M. Maadooliat, M. Pourahmadi and J. Z. Huang, "Robust estimation of the correlation matrix of longitudinal data", *Statistics and Computing* 23, 17-28, (2013).
- [4] W. Zhang, C. Leng, and C. Y. Tang(2015), "A joint modelling approach for longitudinal studies," *Journal of the Royal Statistical Society. Series B.* 77, 219-238.

See Also

[covjmcm](#) and [bootcovjmcm](#) for more details and examples.

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